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(54) **EXPANDABLE INTERVERTEBRAL IMPLANT SYSTEM AND METHOD**

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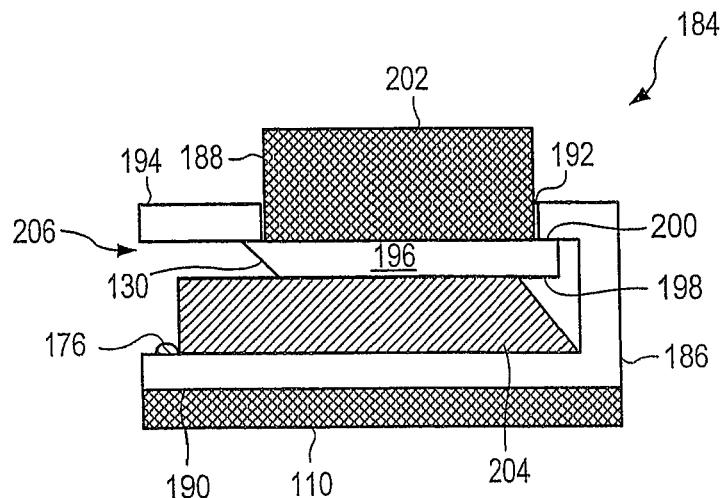
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(57) **ABSTRACT**

An intervertebral implant system for a human spine including a first body having a first external surface to be disposed adjacent a first vertebrae during use and a first internal surface opposite the first external surface, a second body having a second external surface to be disposed adjacent a second vertebrae during use and a second internal surface opposite the second external surface, an elongated insertion instrument releasable coupleable to the first or second body during use, and a spacer linearly advanced between the first internal surface of the first body and the first internal surface of the second body during use. The elongated insertion instrument guides at least a portion of the linear advancement of the spacer, and wherein the linear advancement of the spacer results in expansion of the intervertebral implant such that the first external surface and the second external surface move away from one another to expand a height of the implant.

37 Claims, 45 Drawing Sheets



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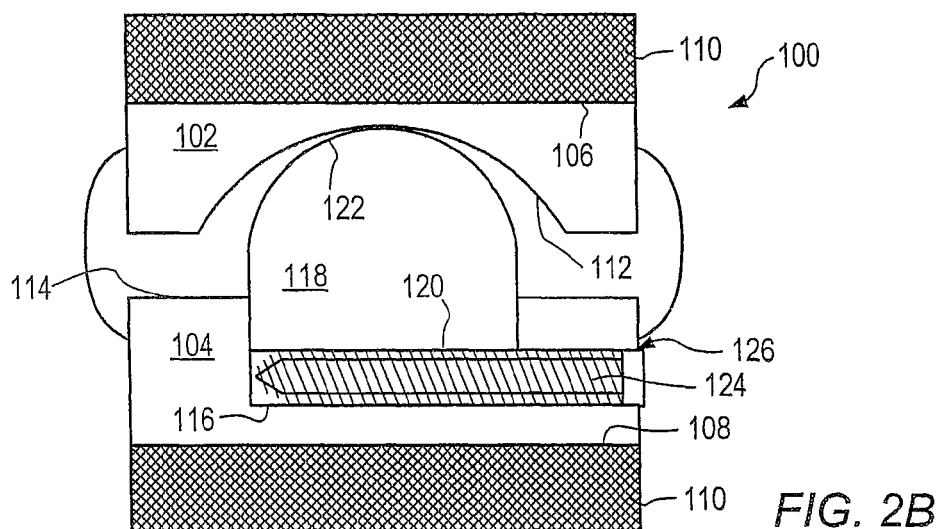
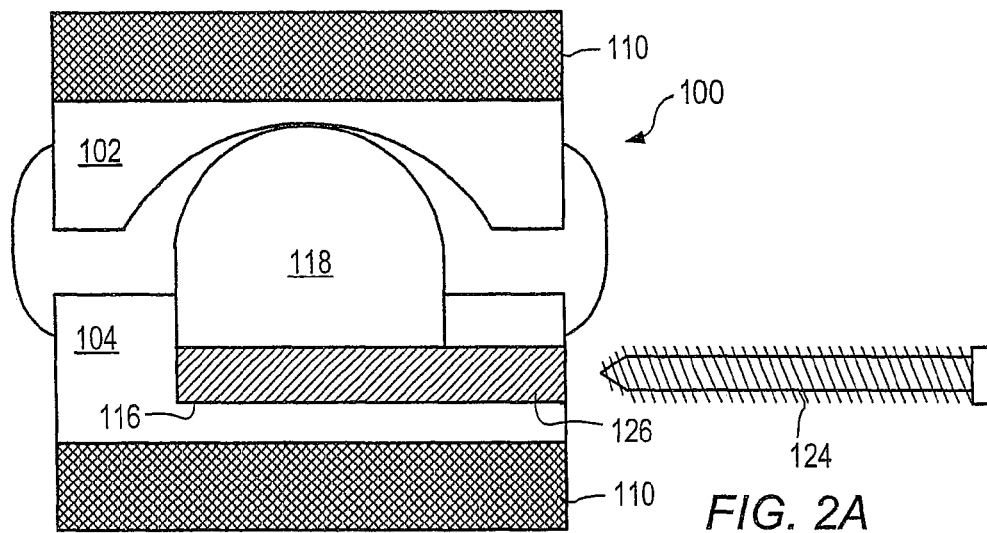
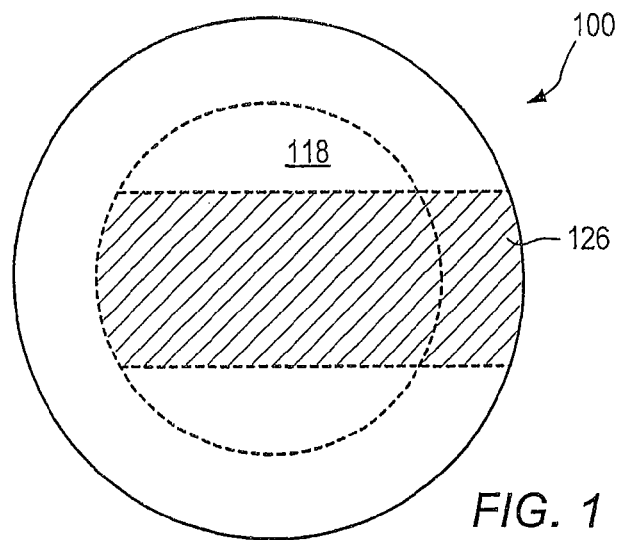
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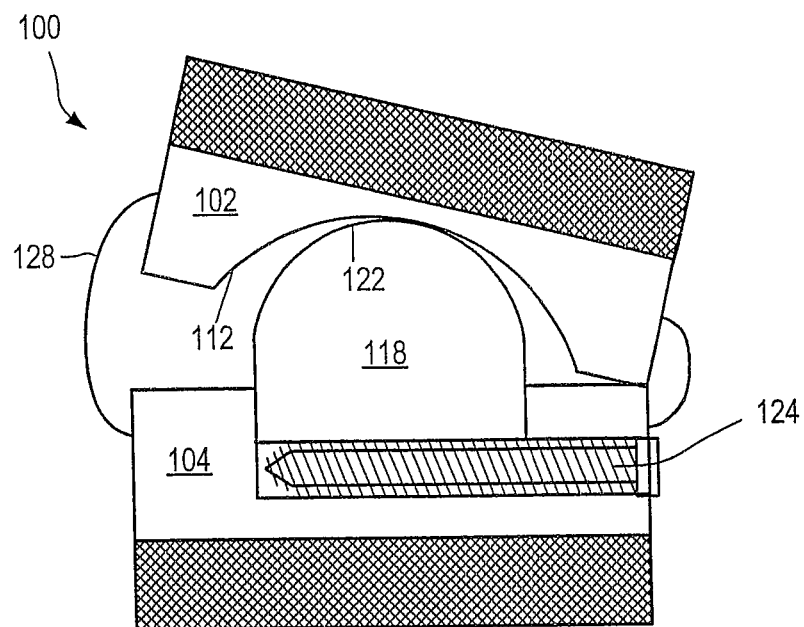


FIG. 3A

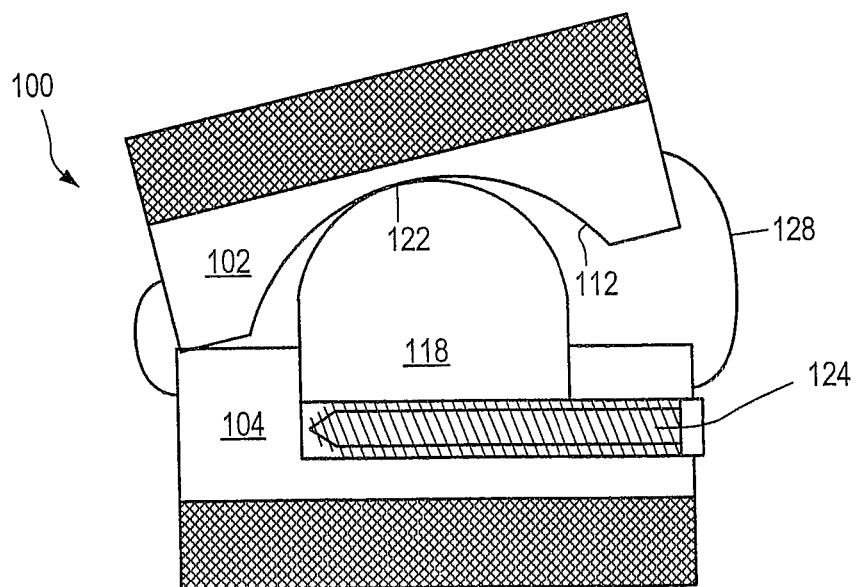


FIG. 3B

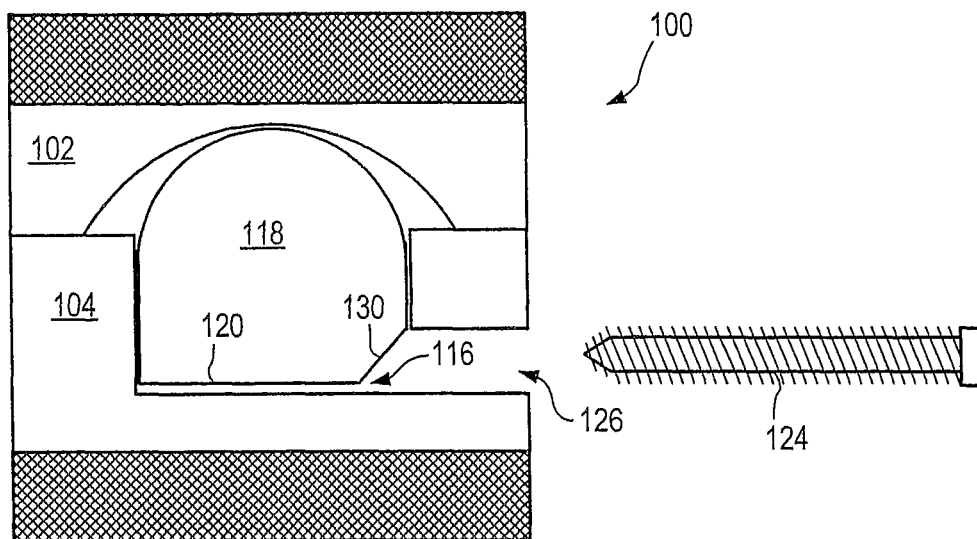


FIG. 4A

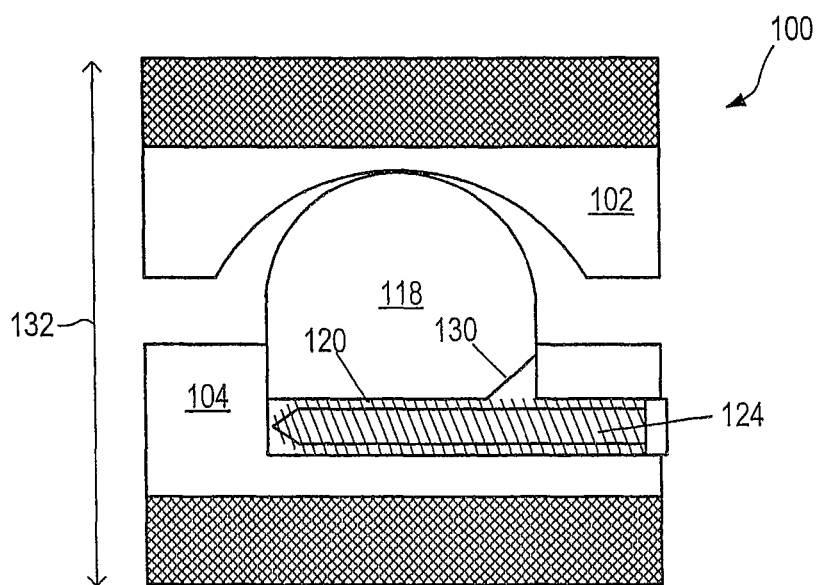
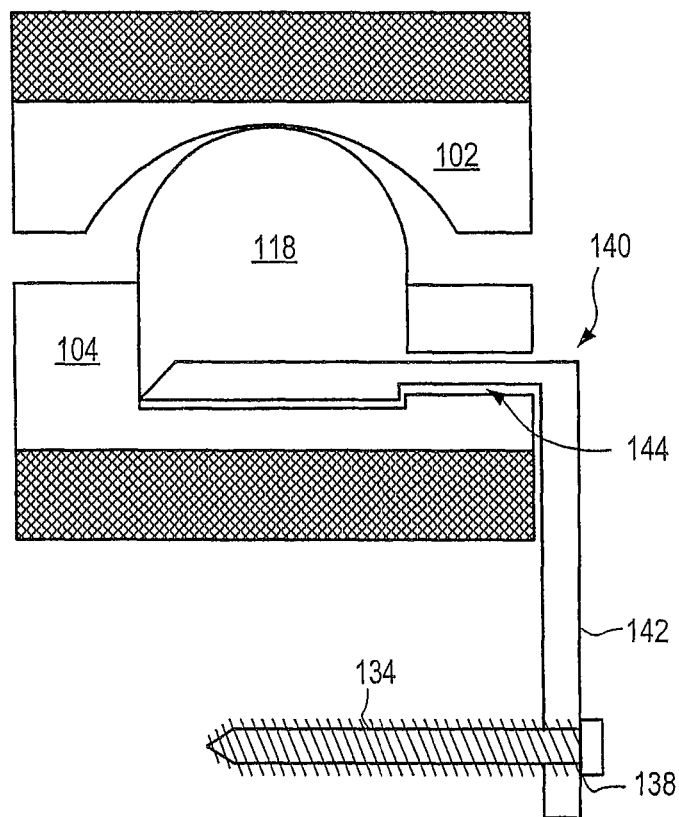
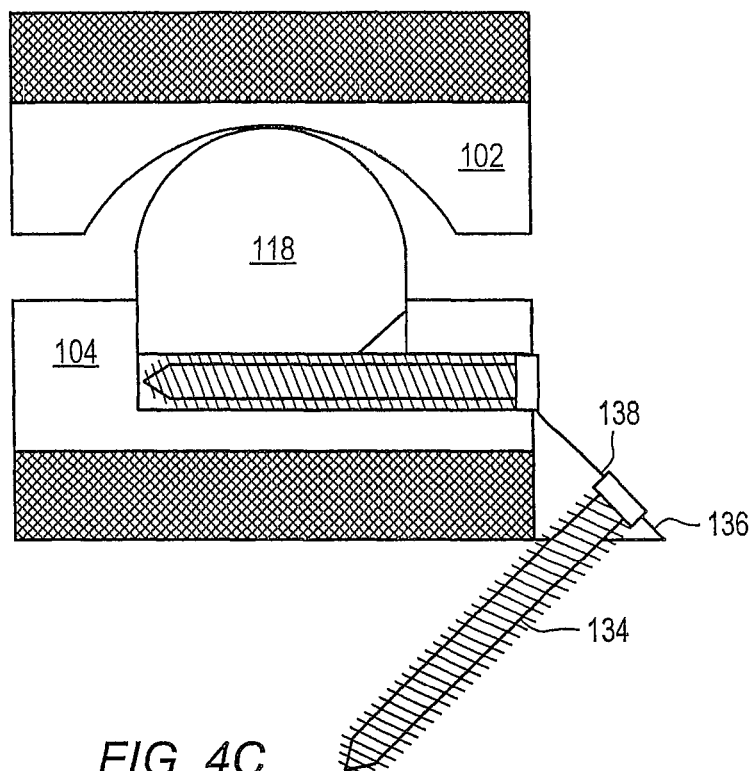


FIG. 4B



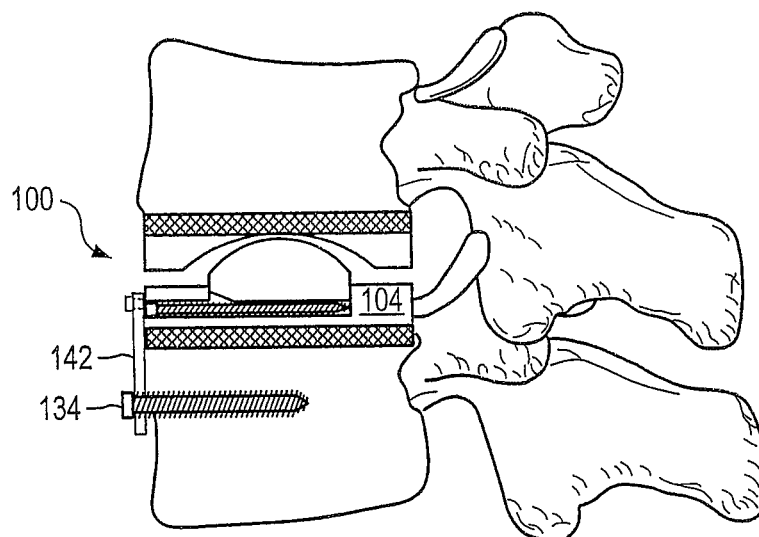


FIG. 4E

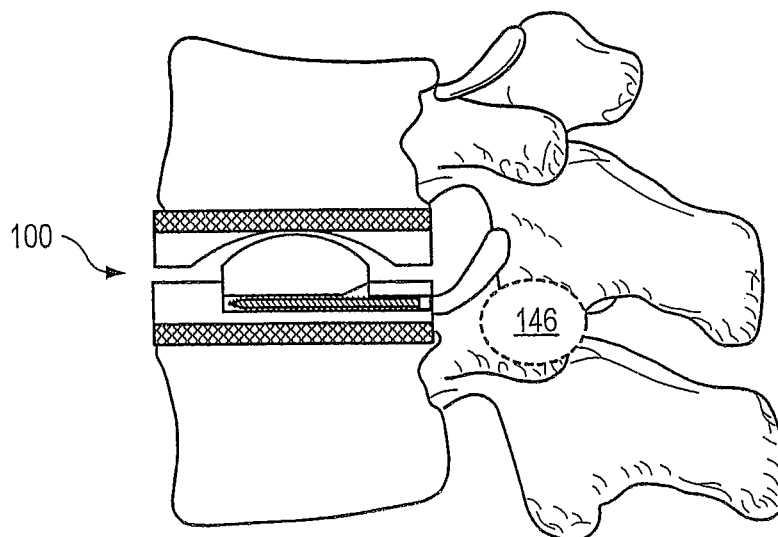


FIG. 5

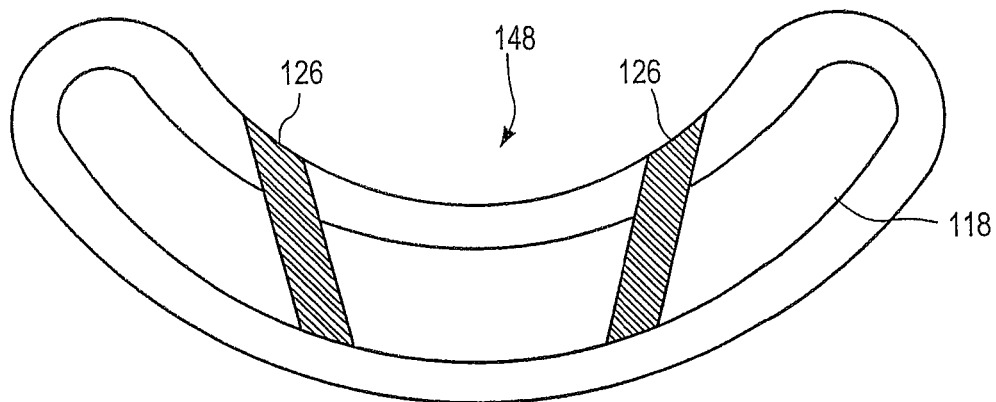


FIG. 6A

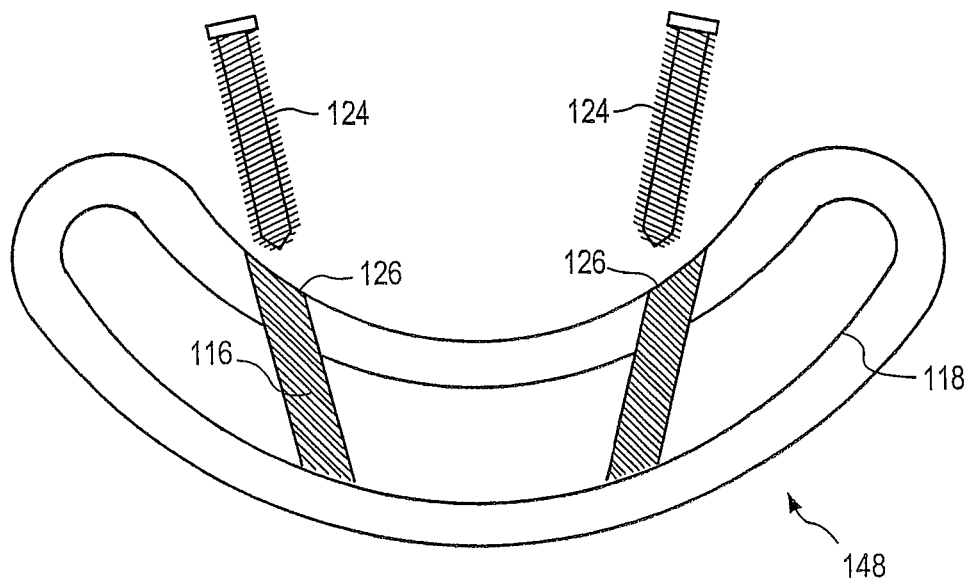
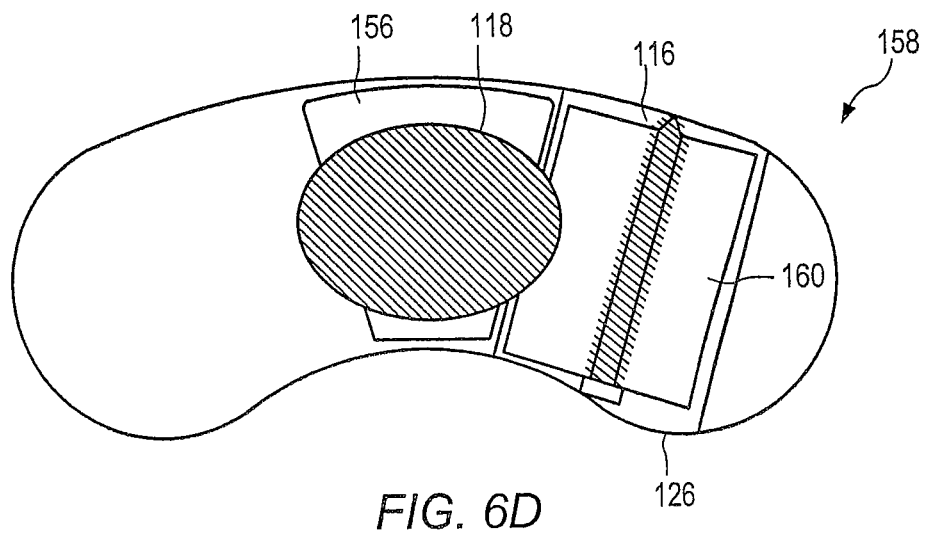
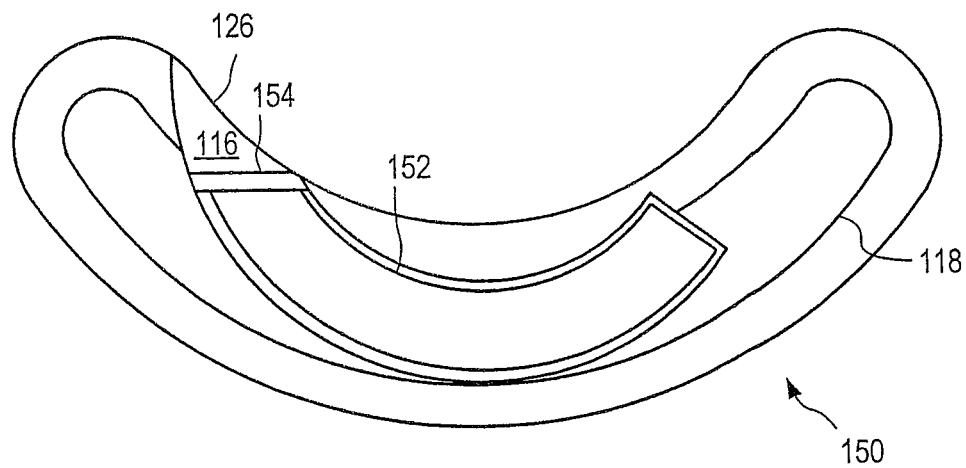


FIG. 6B



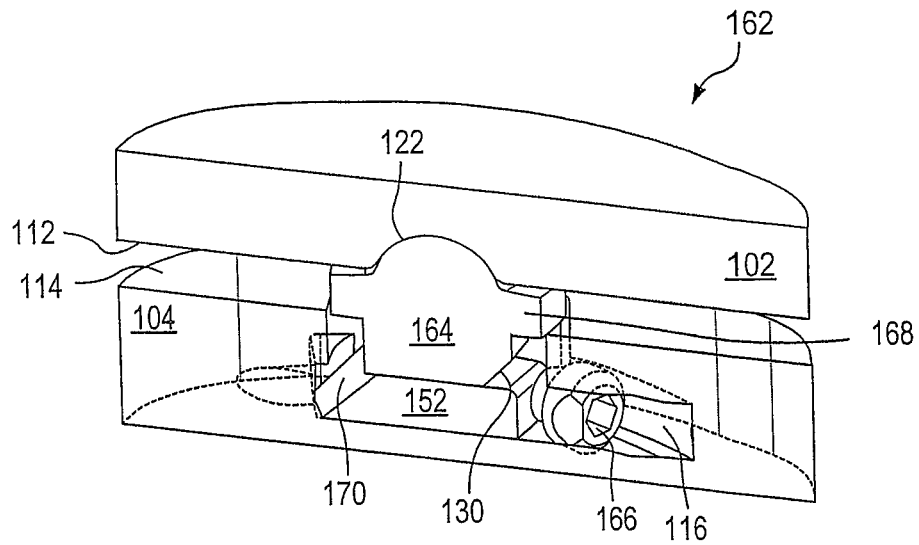


FIG. 7A

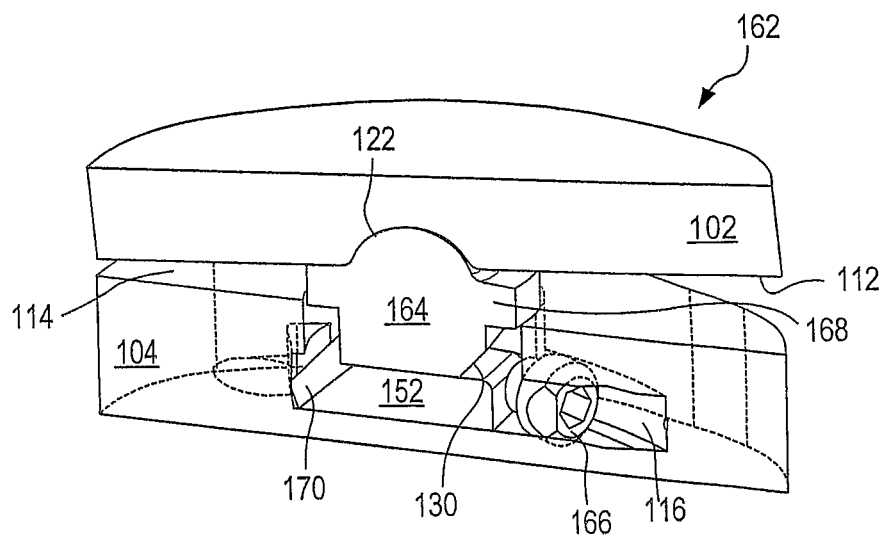


FIG. 7B

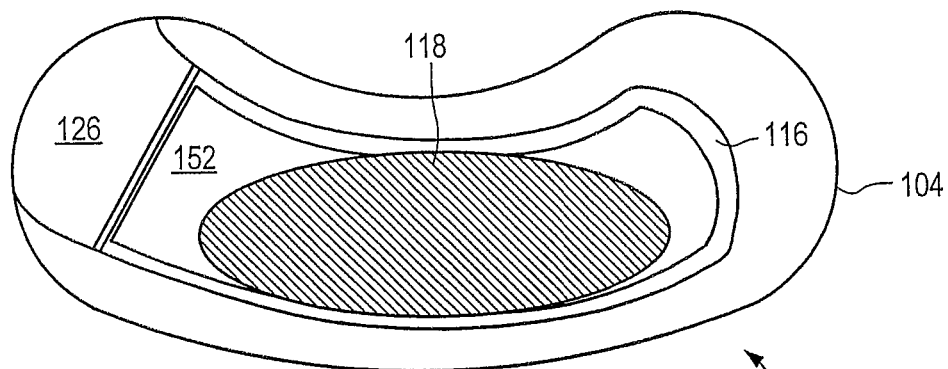


FIG. 8A

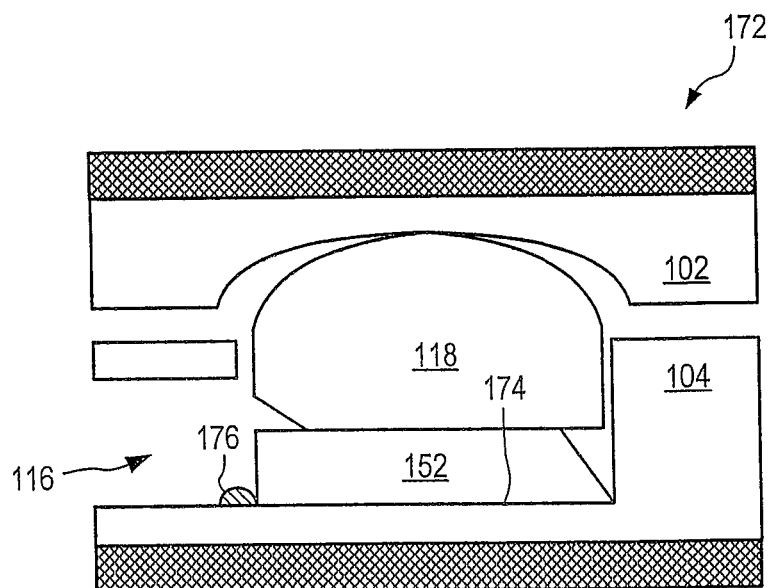


FIG. 8B

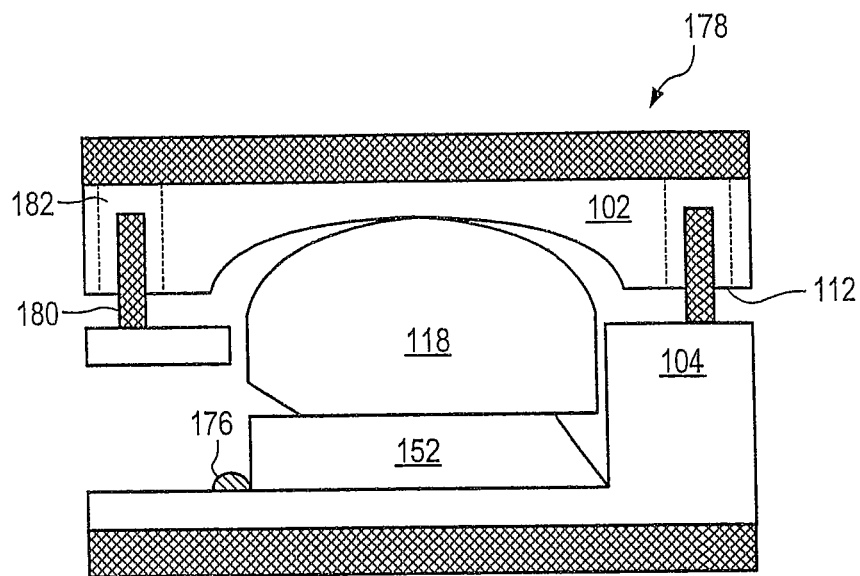


FIG. 8C

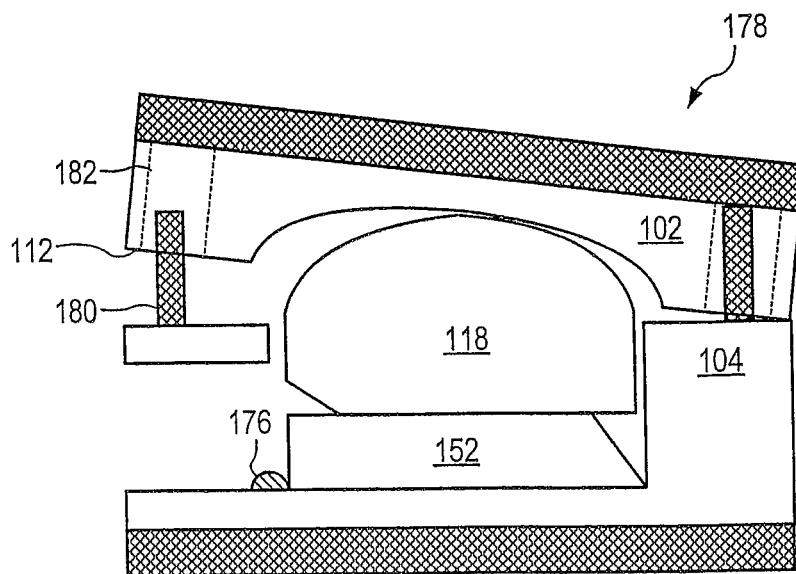


FIG. 8D

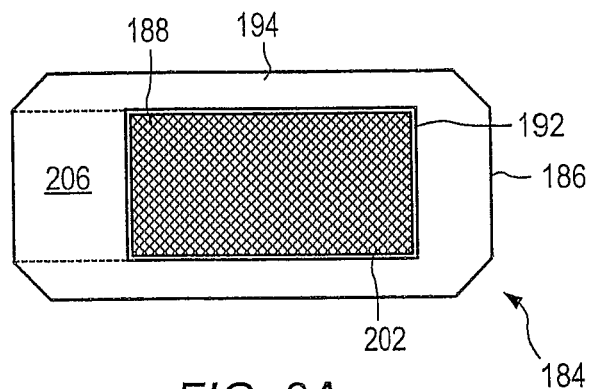


FIG. 9A

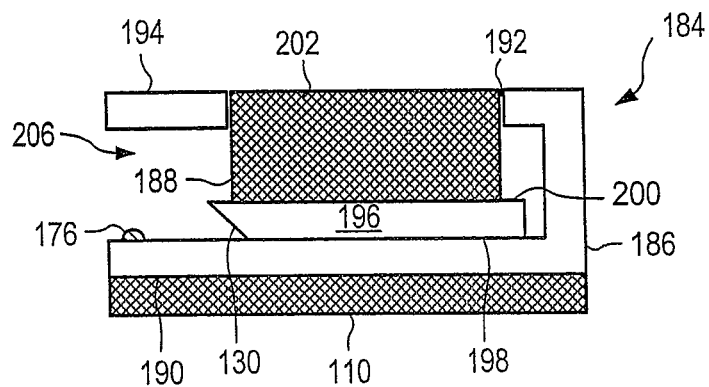


FIG. 9B

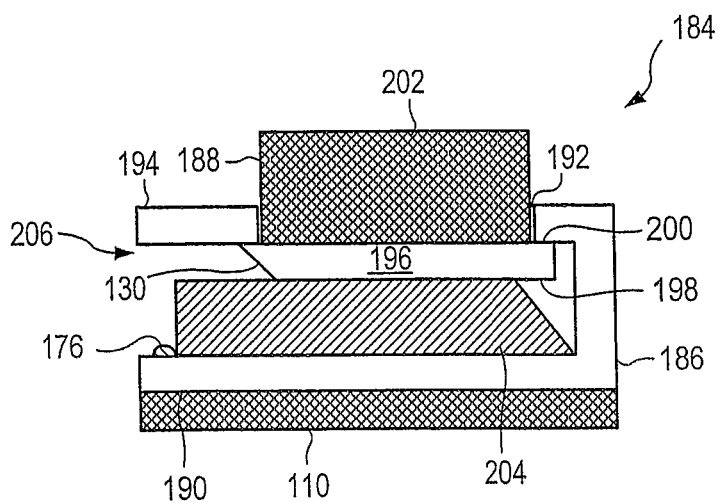


FIG. 9C

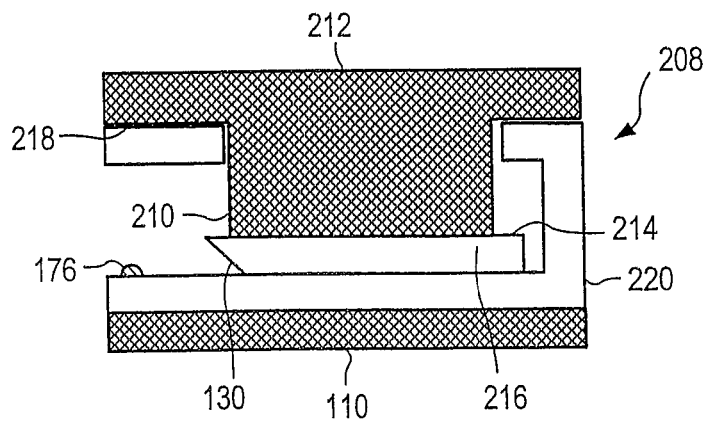


FIG. 9D

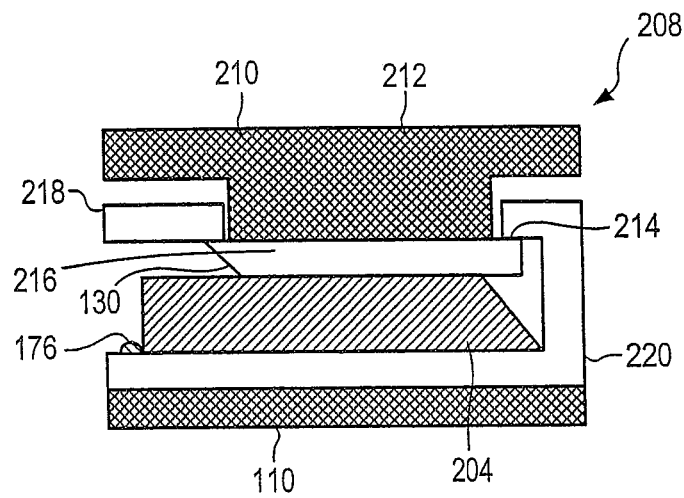


FIG. 9E

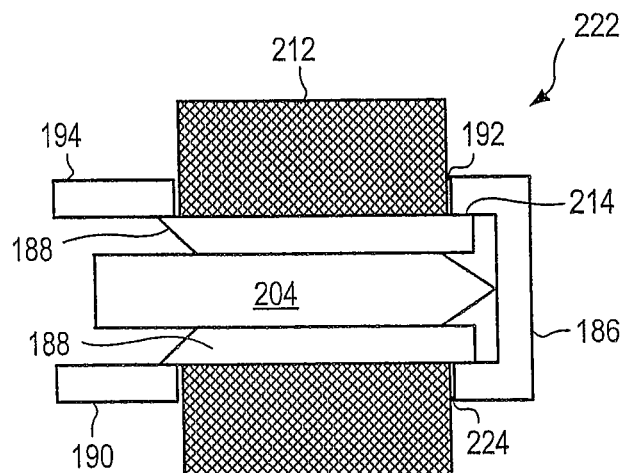


FIG. 9F

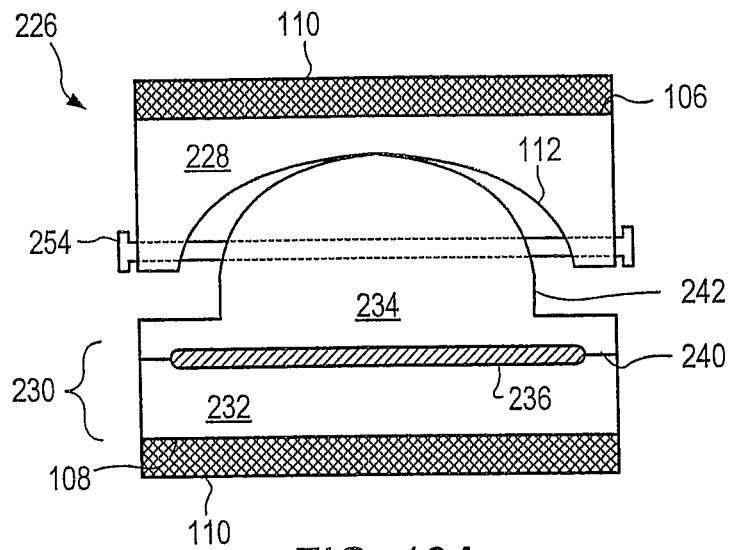


FIG. 10A

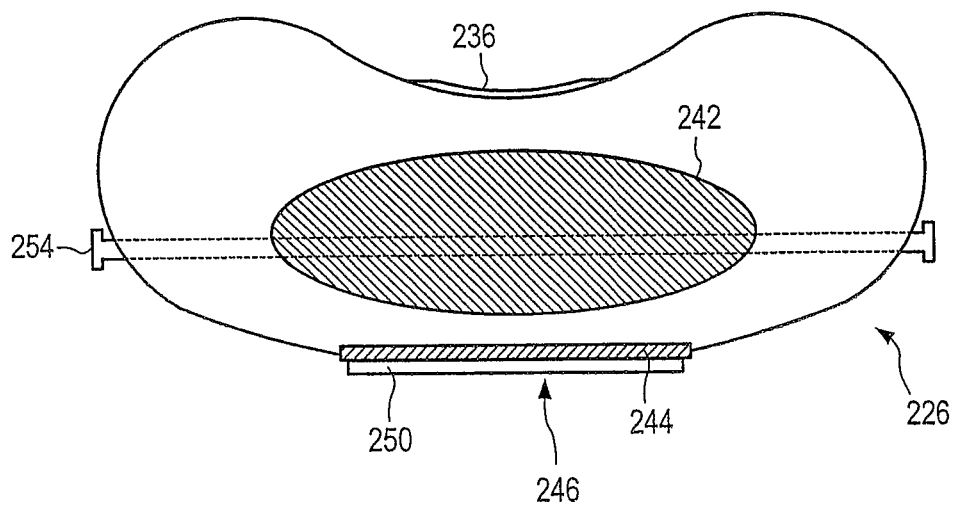


FIG. 10B

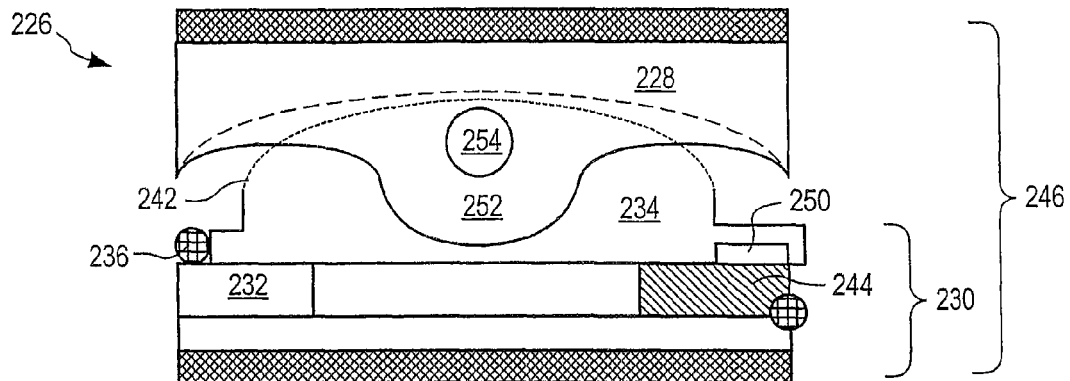


FIG. 11A

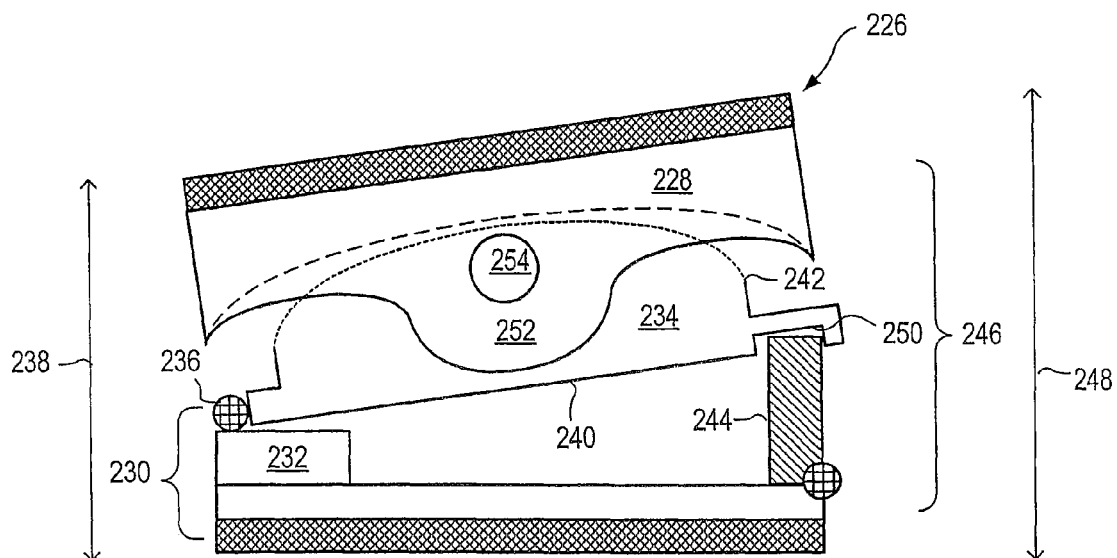


FIG. 11B

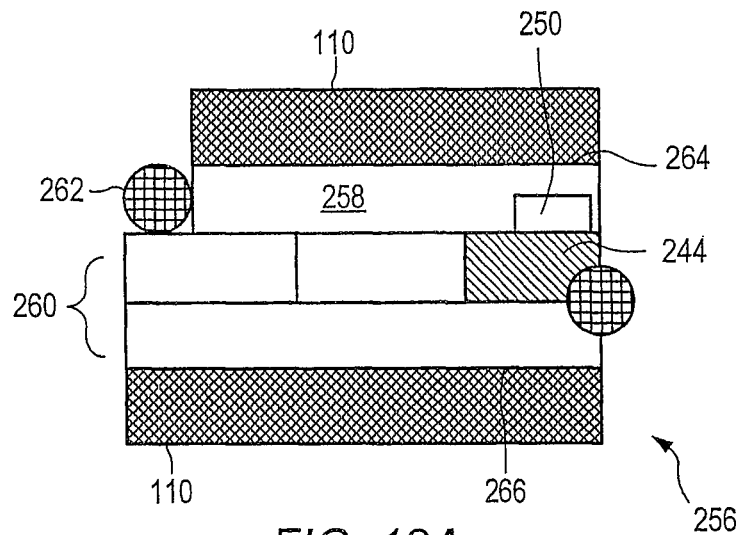


FIG. 12A

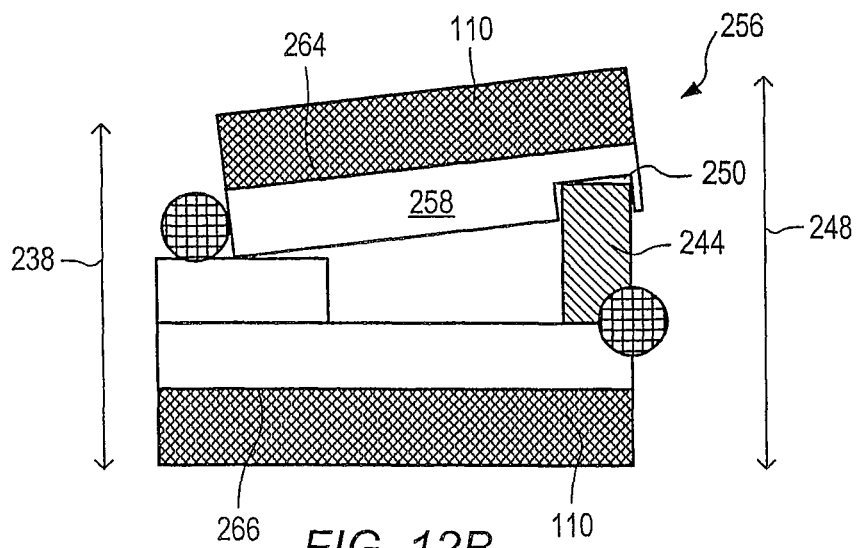


FIG. 12B

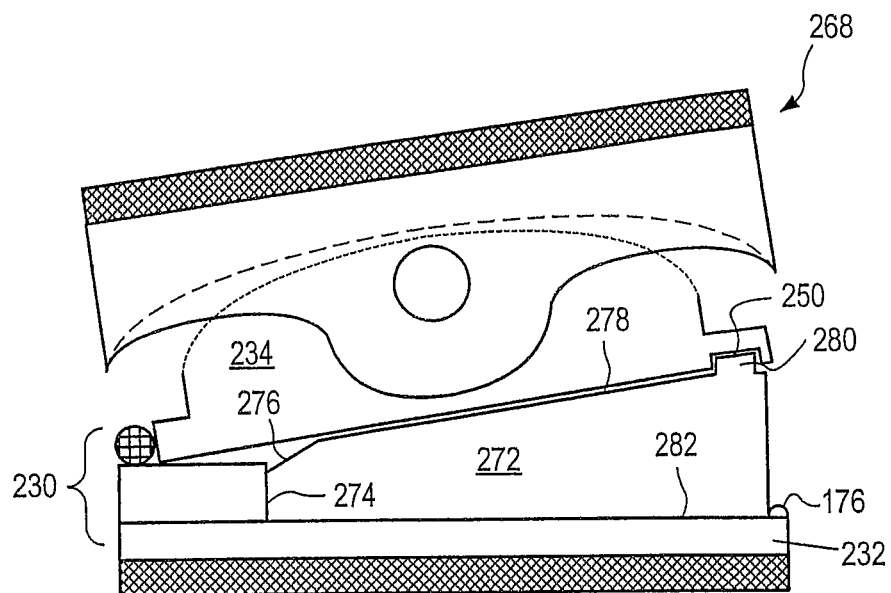


FIG. 13A

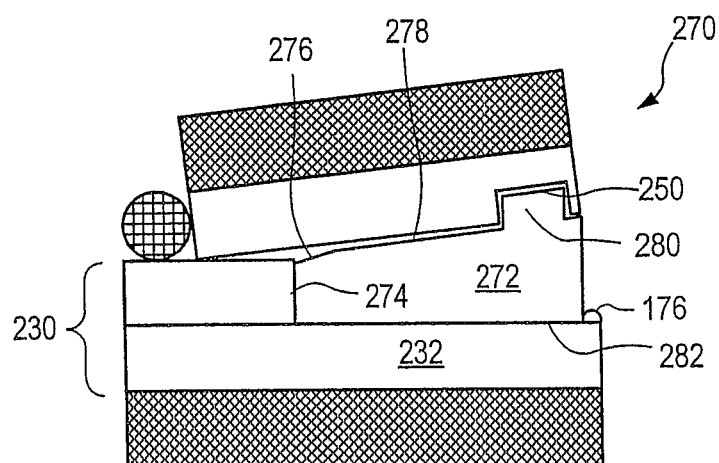
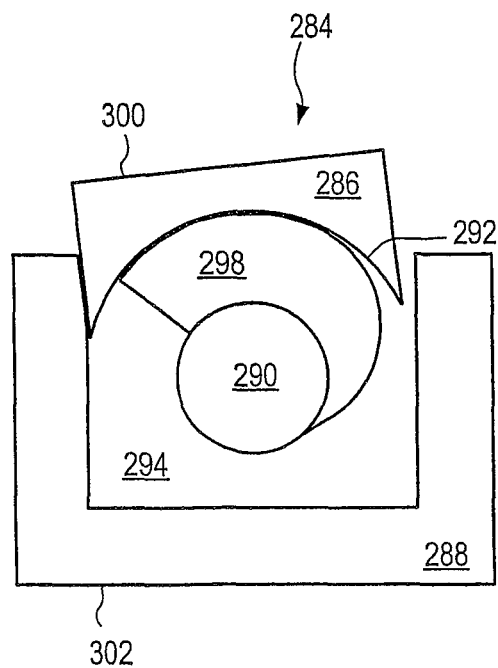
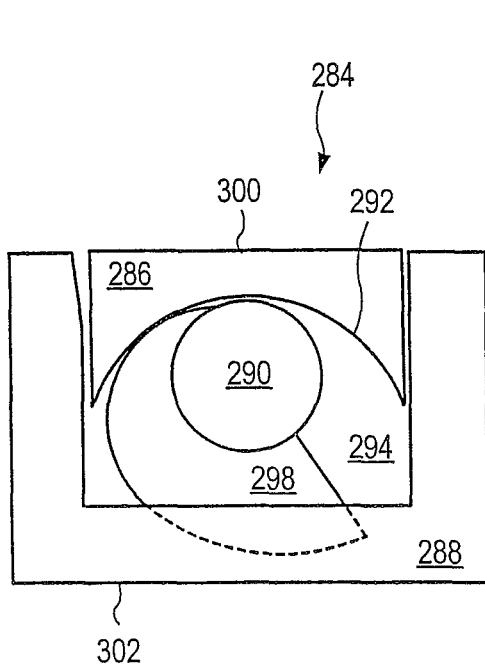
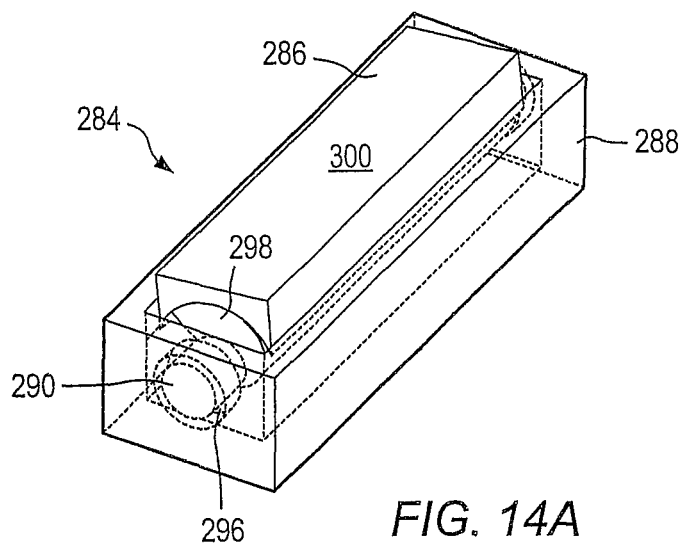


FIG. 13B



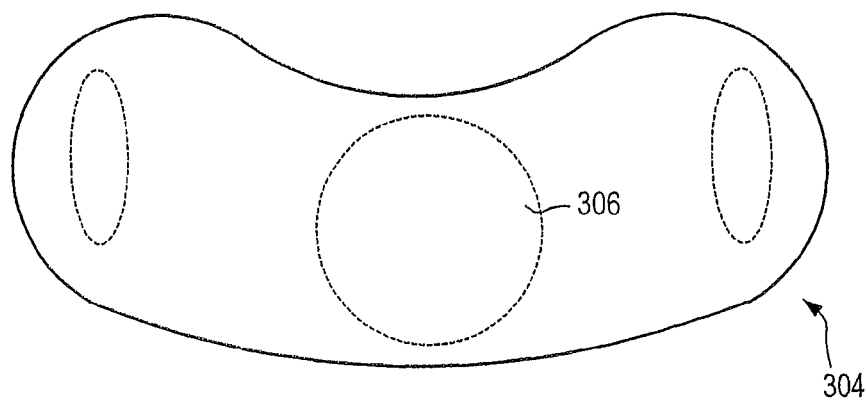


FIG. 15A

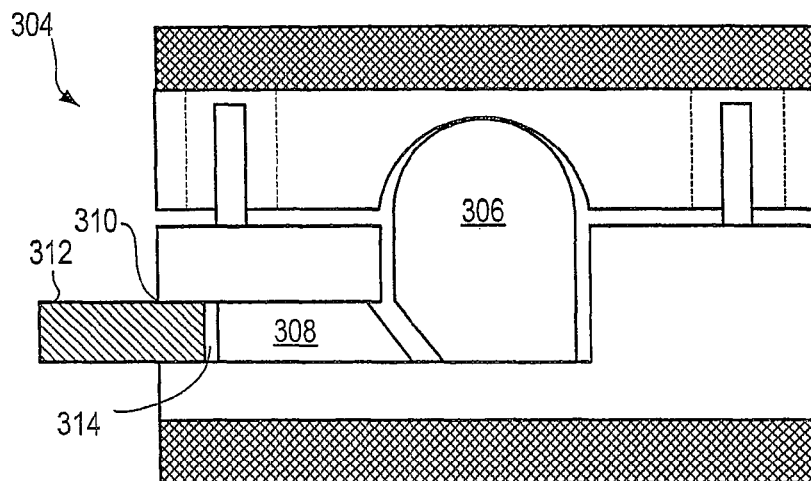


FIG. 15B

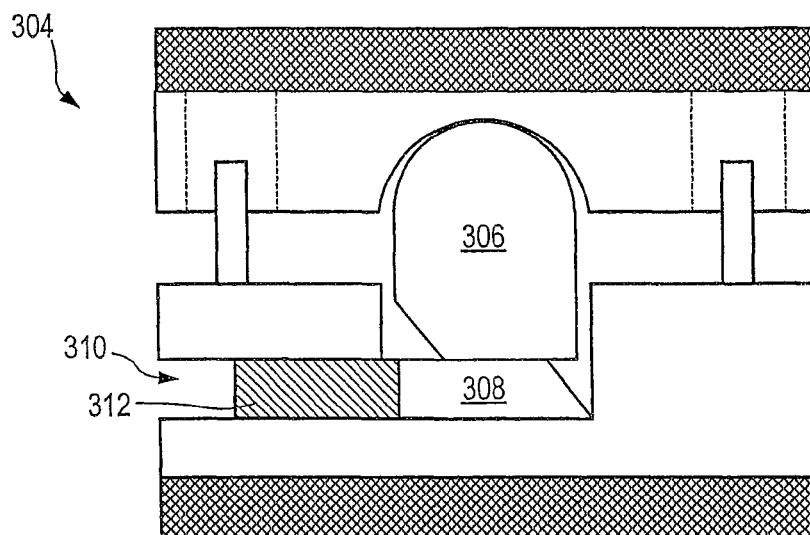
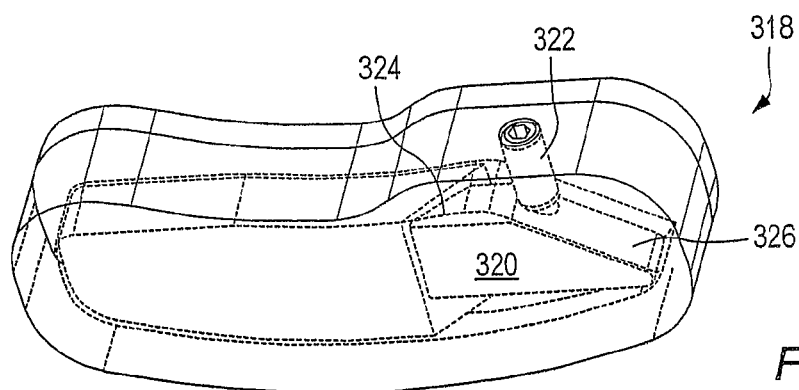
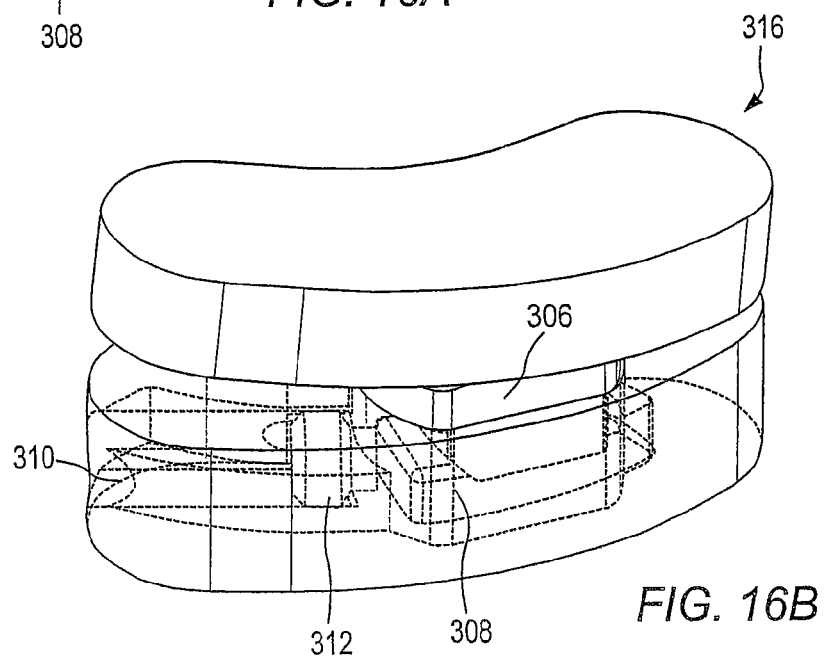
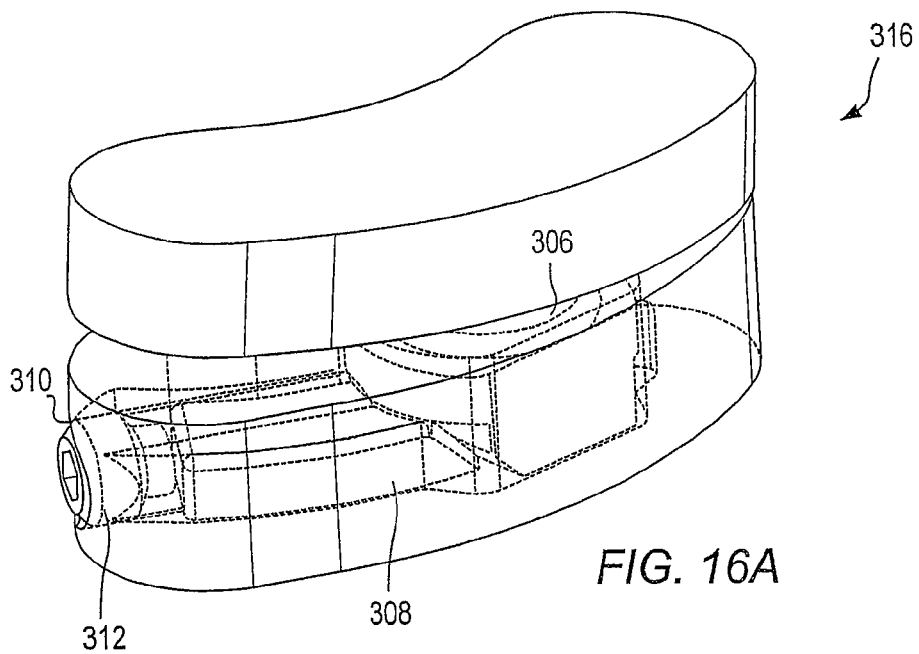


FIG. 15C



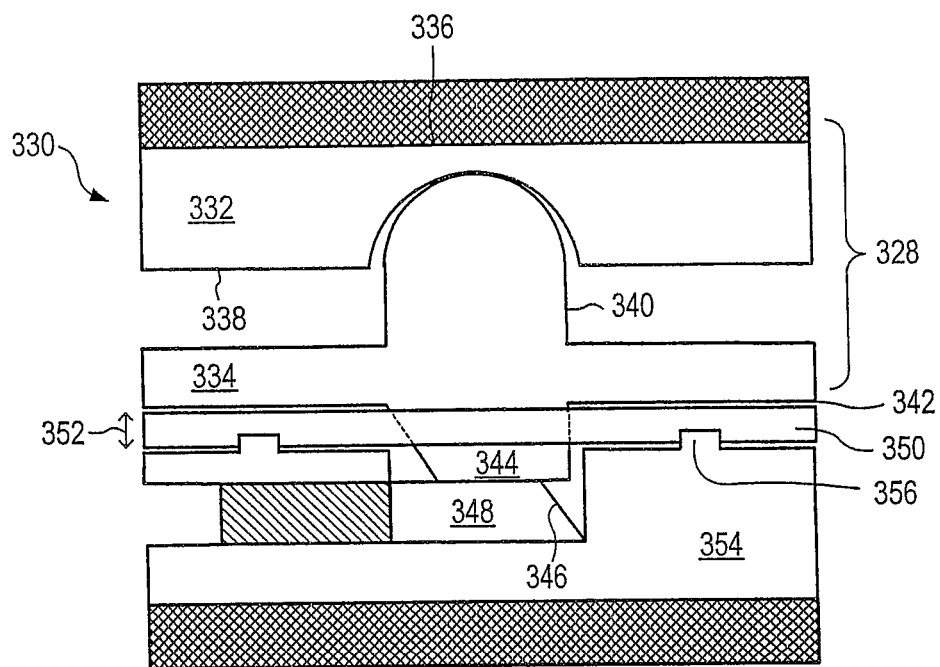


FIG. 18A

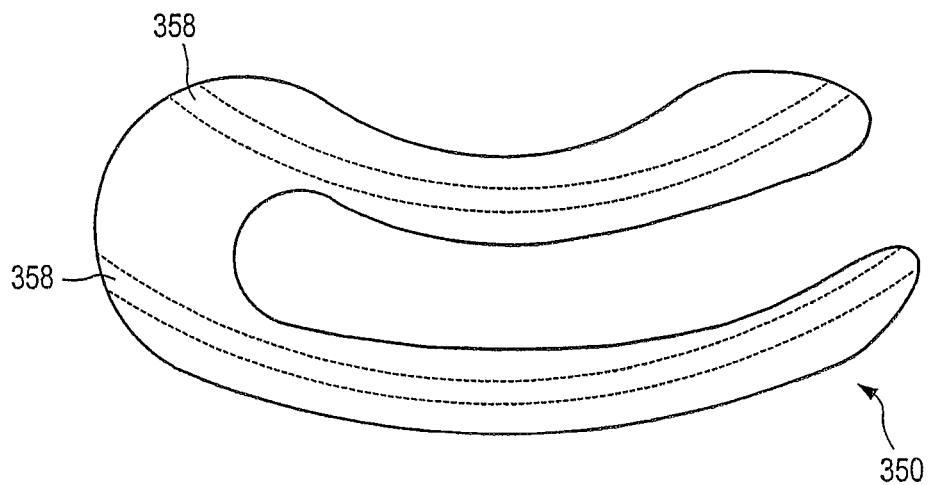


FIG. 18B

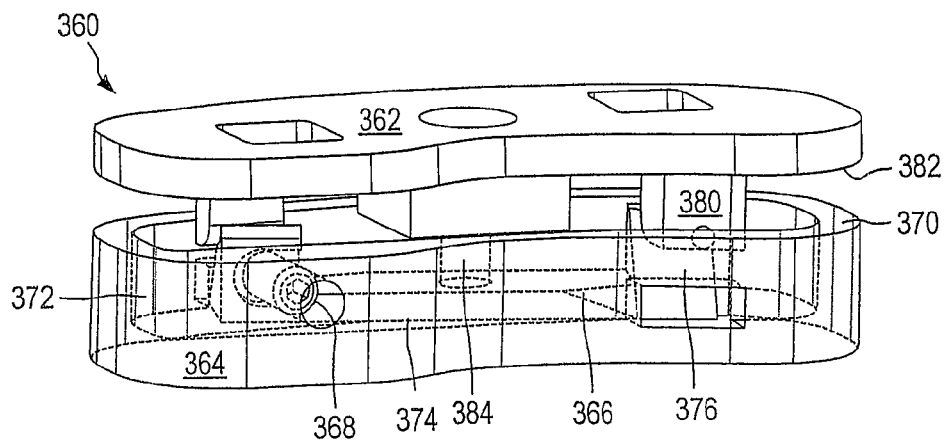


FIG. 19A

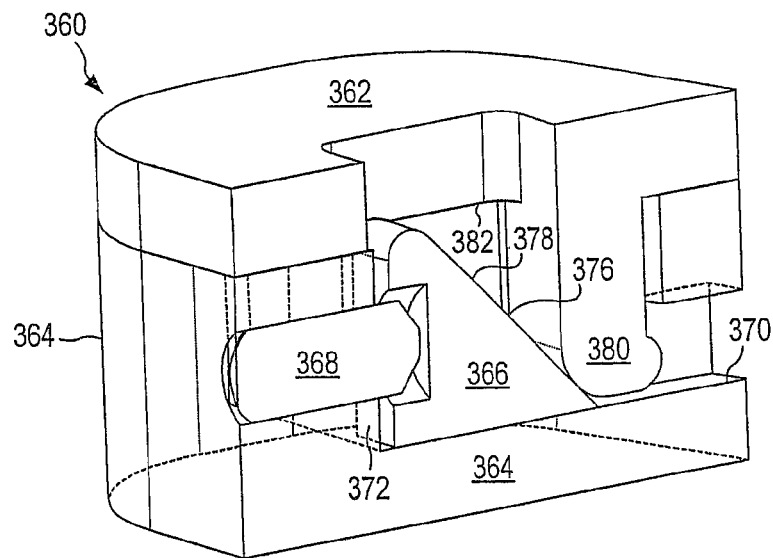


FIG. 19B

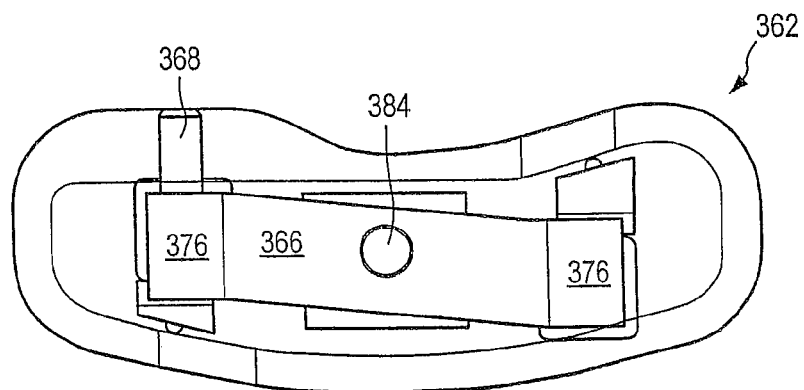
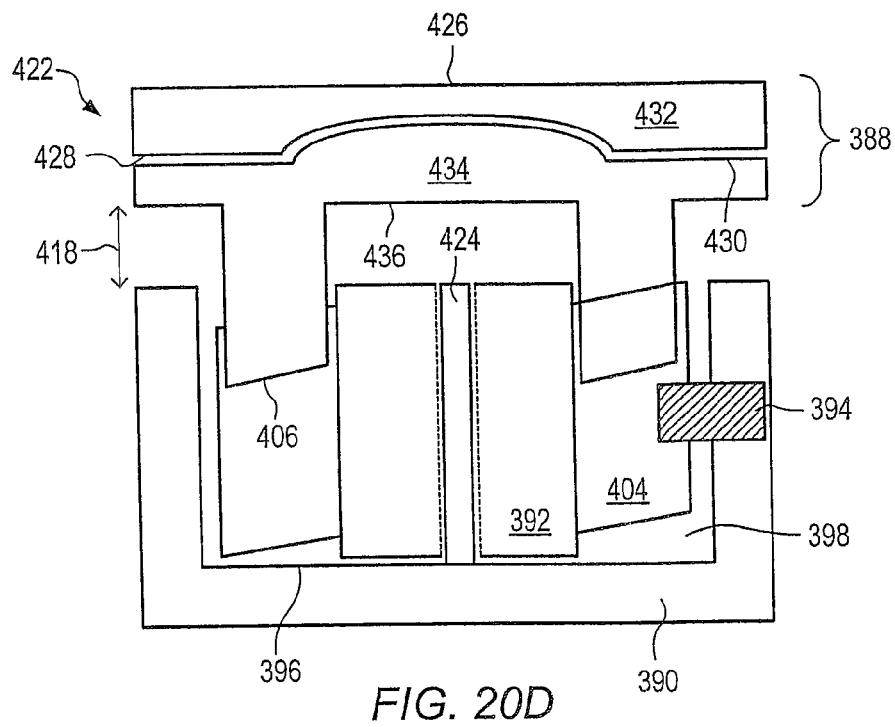
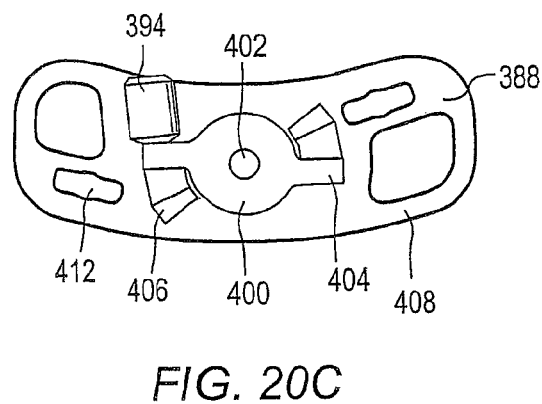
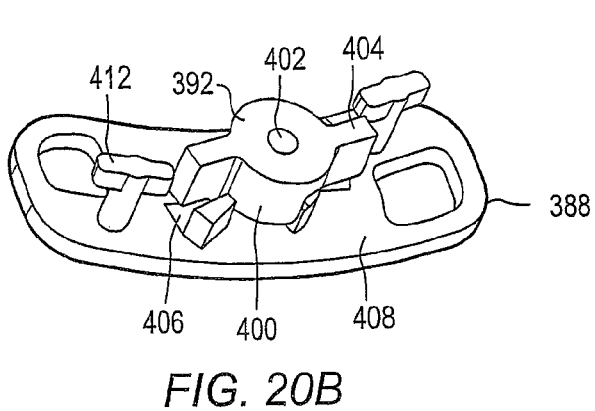
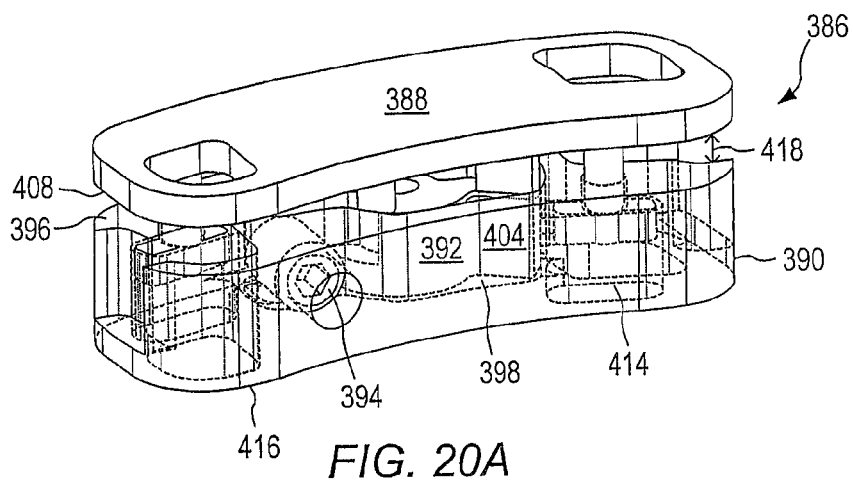


FIG. 19C



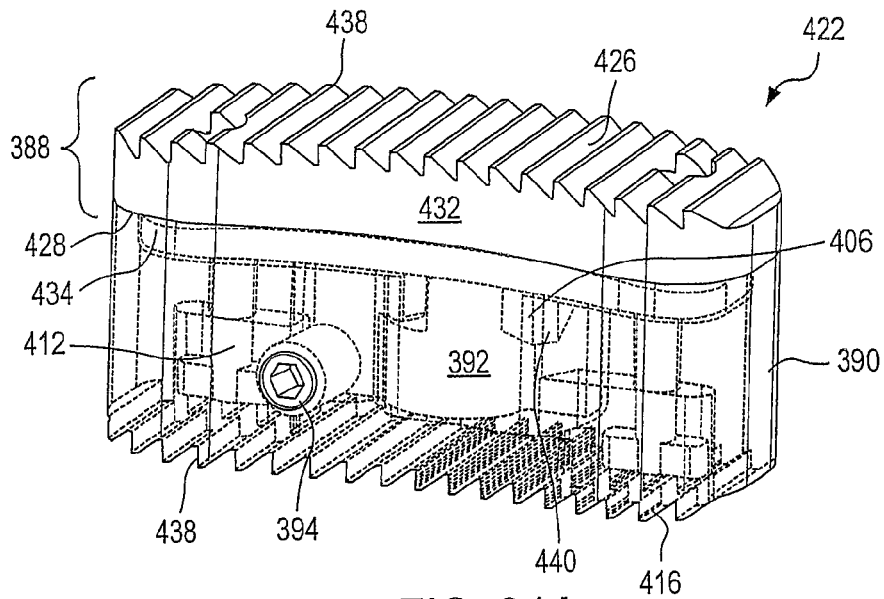


FIG. 21A

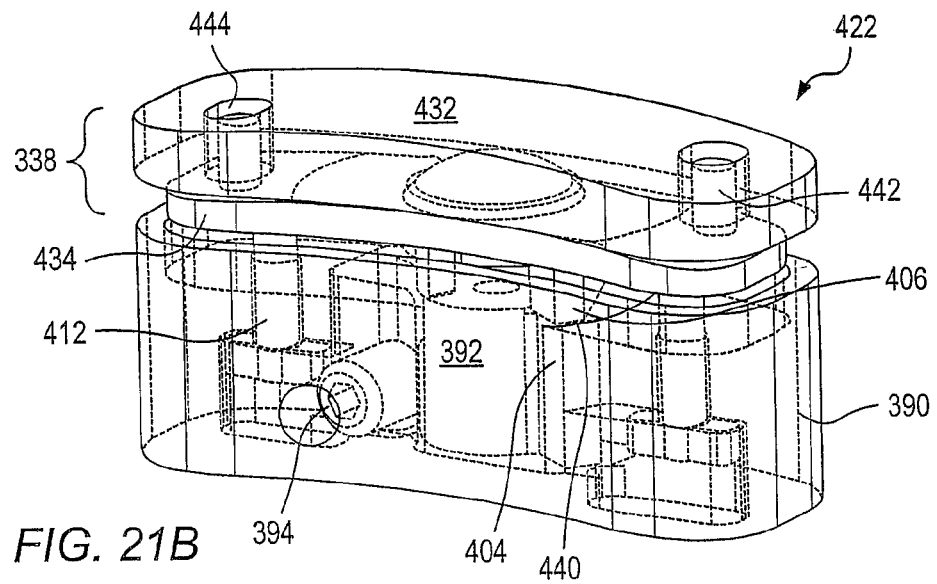


FIG. 21B

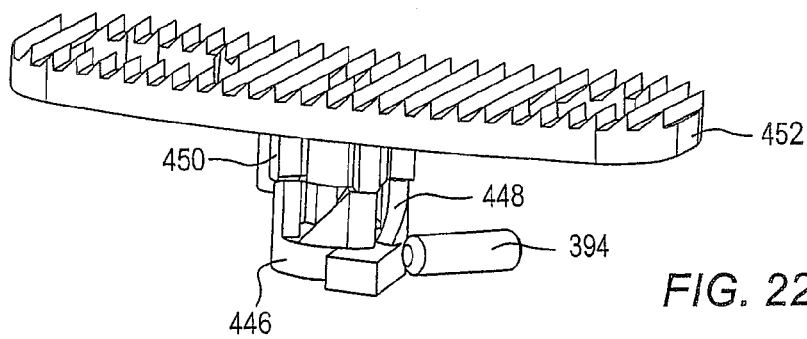


FIG. 22

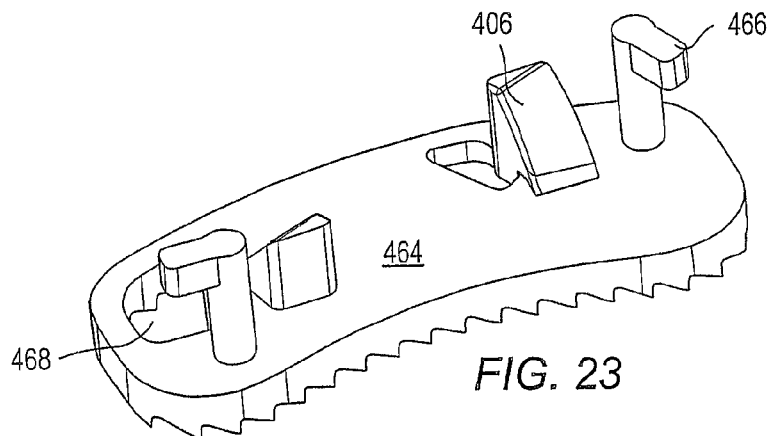


FIG. 23

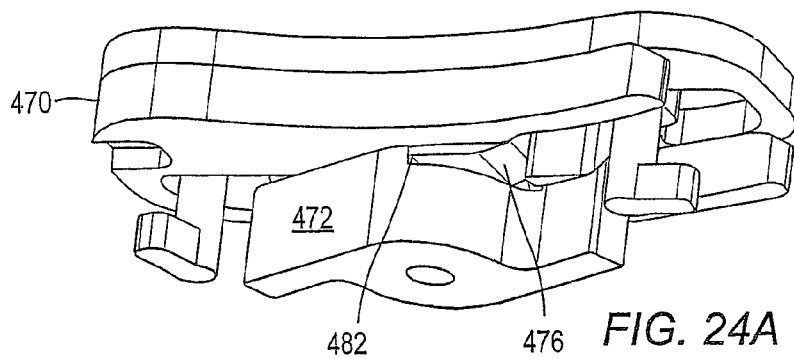


FIG. 24A

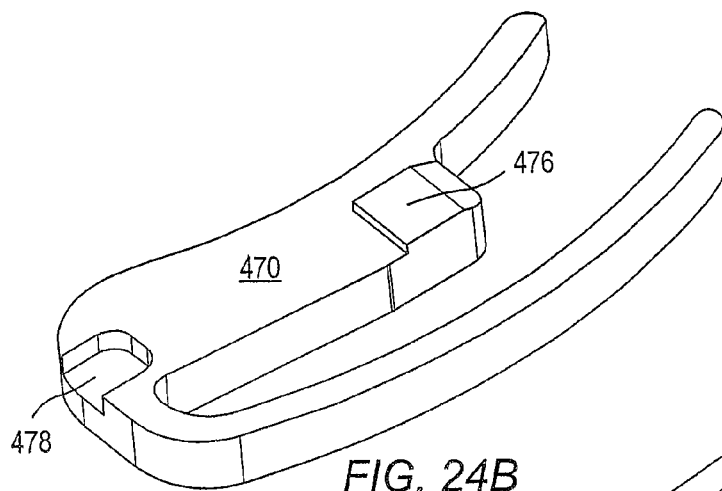


FIG. 24B

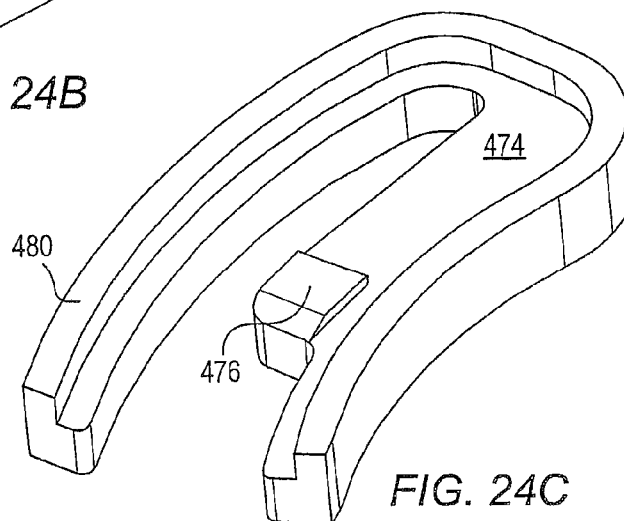


FIG. 24C

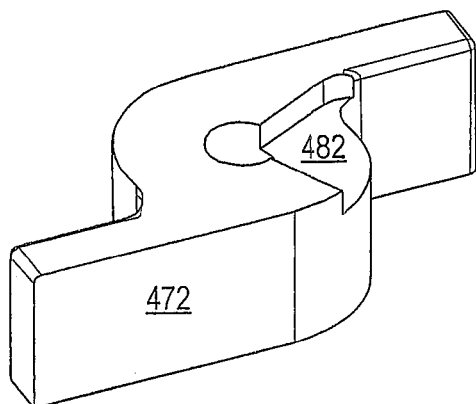


FIG. 24D

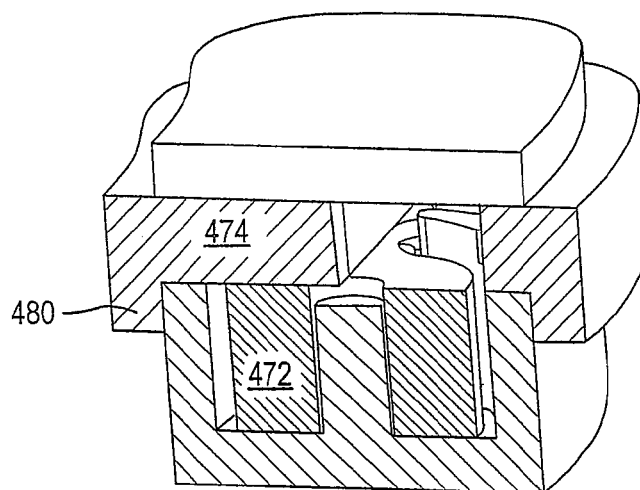


FIG. 24E

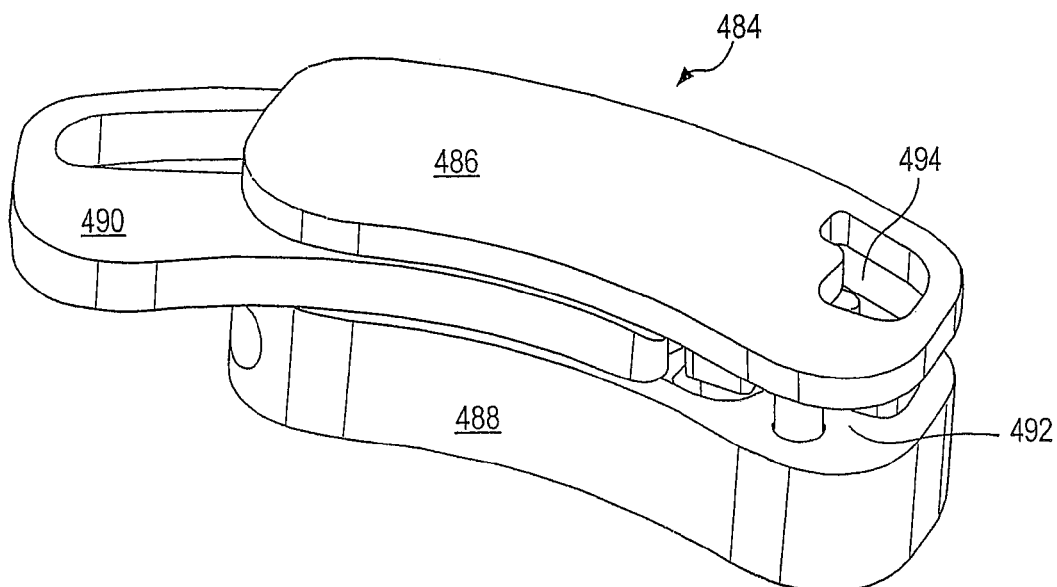


FIG. 25

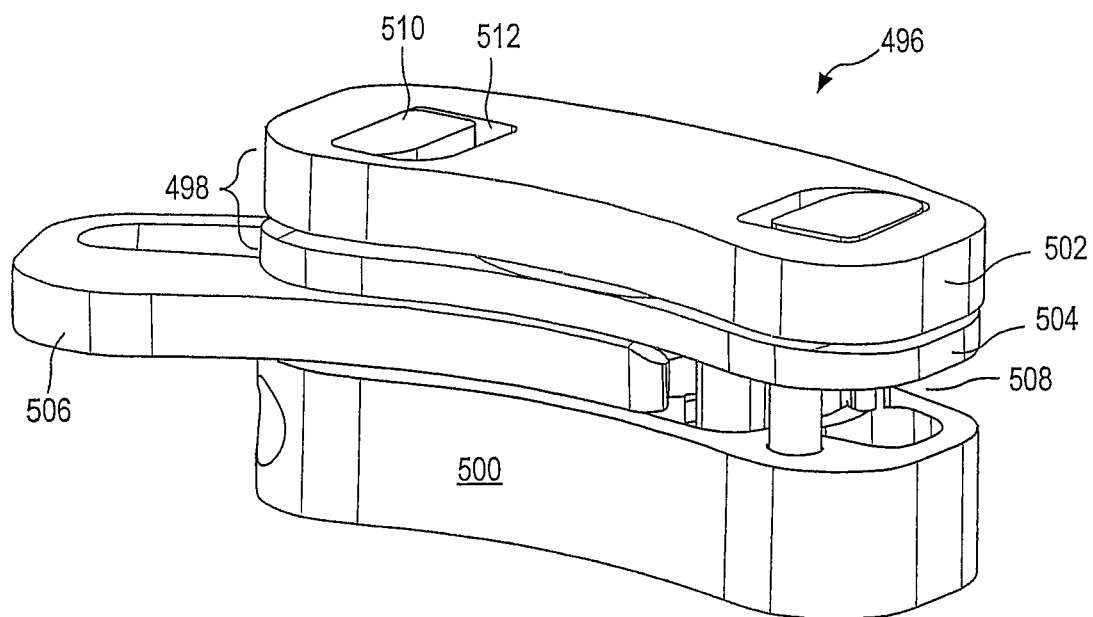


FIG. 26A

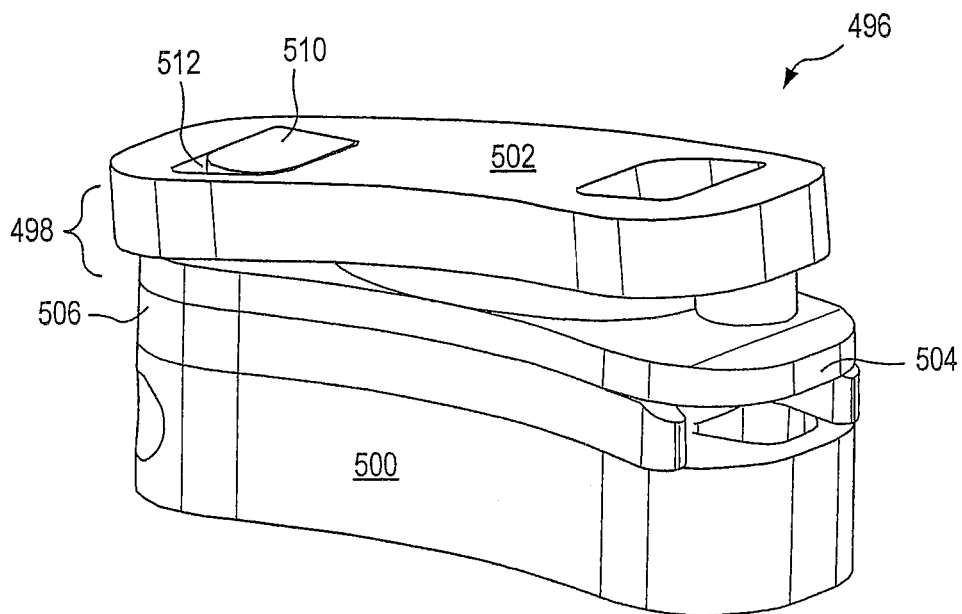


FIG. 26B

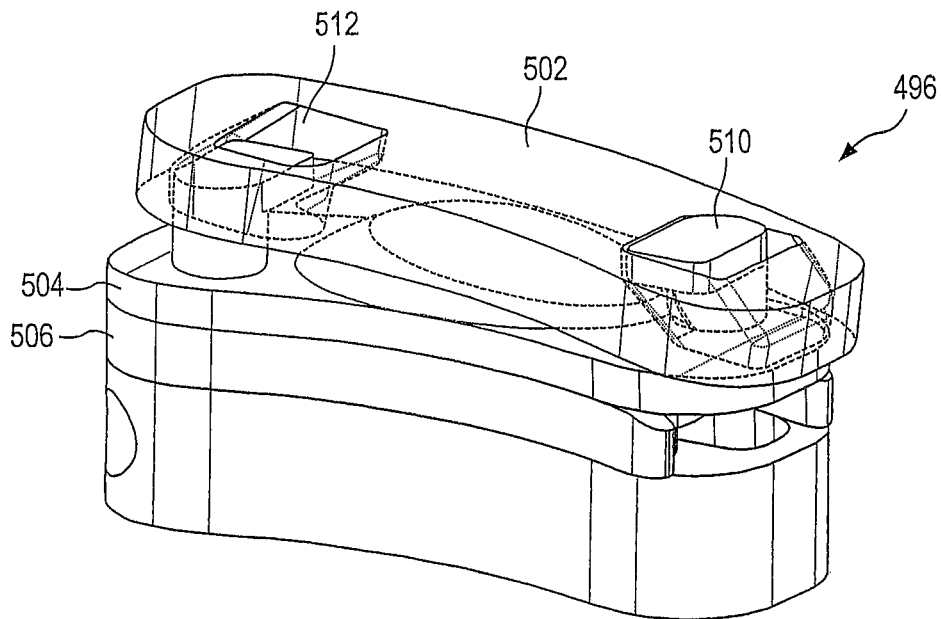


FIG. 26C

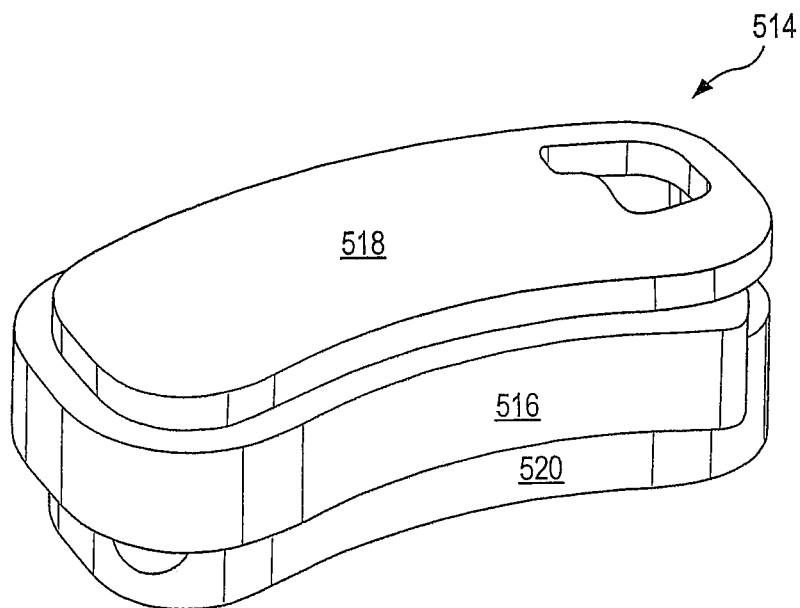


FIG. 27

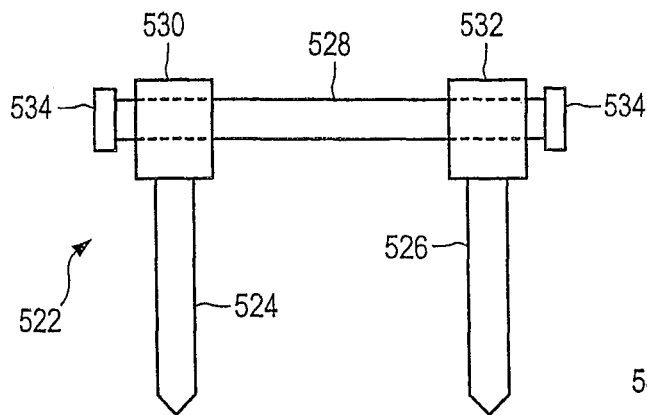


FIG. 28A

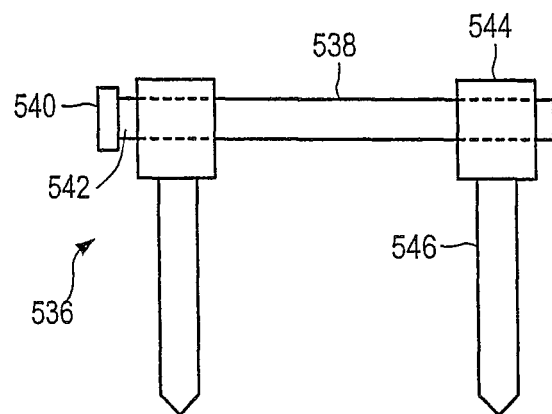


FIG. 28B

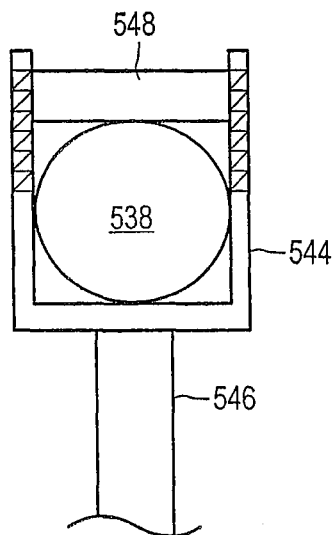


FIG. 28C

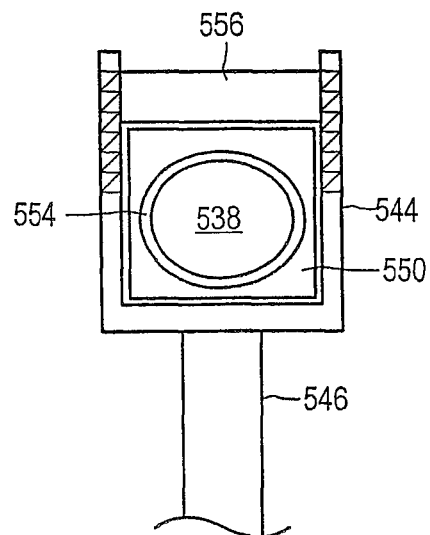


FIG. 28D

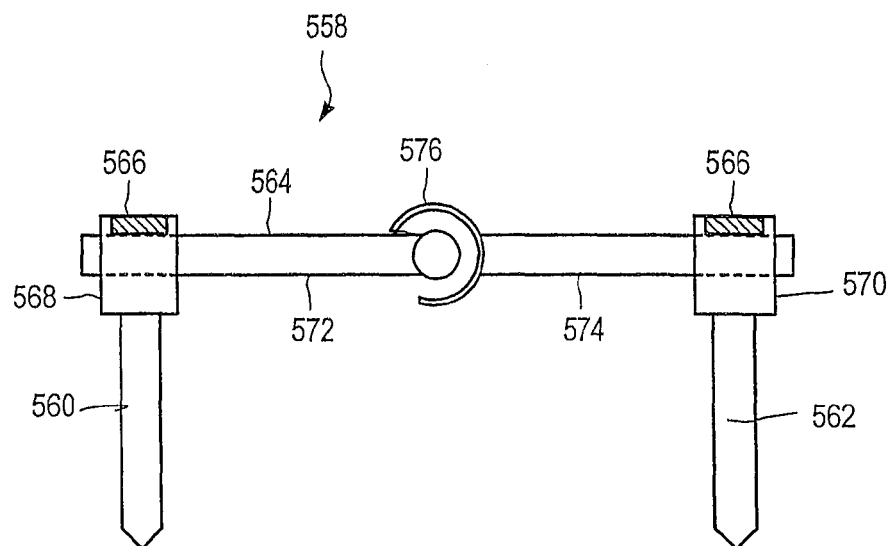


FIG. 29A

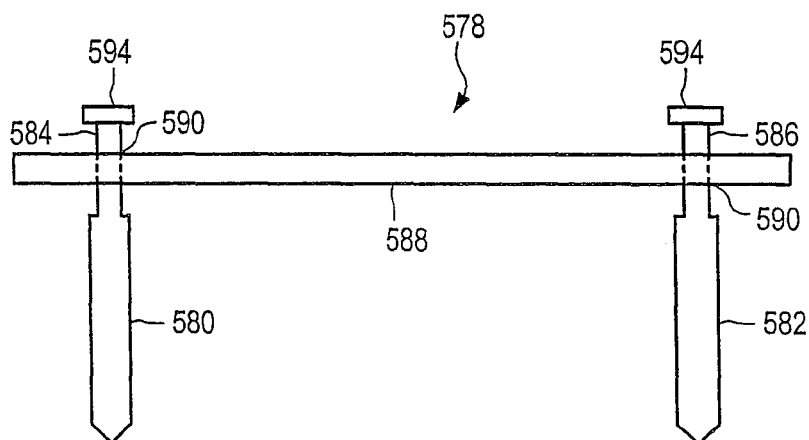


FIG. 29B

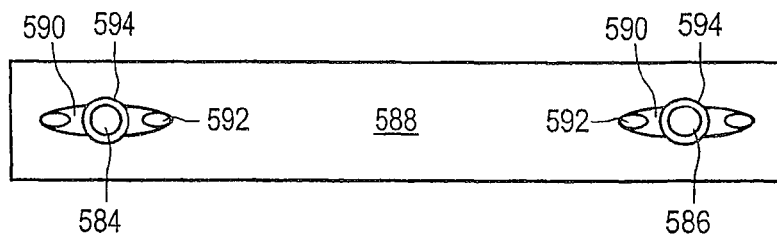


FIG. 29C

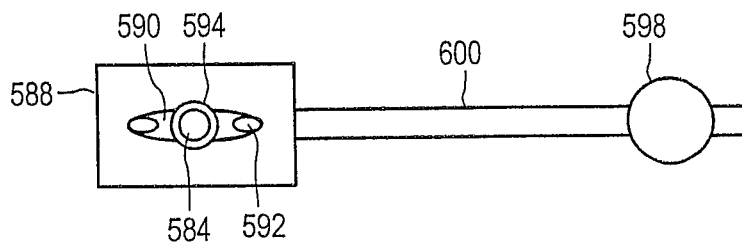


FIG. 29D

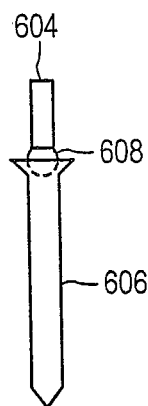


FIG. 29E

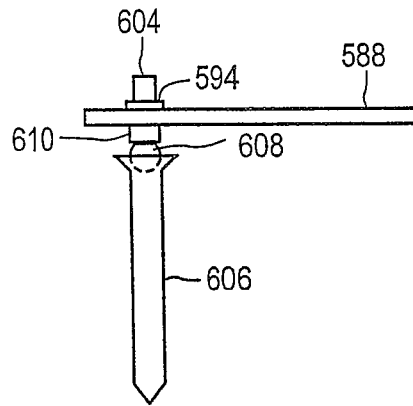


FIG. 29F

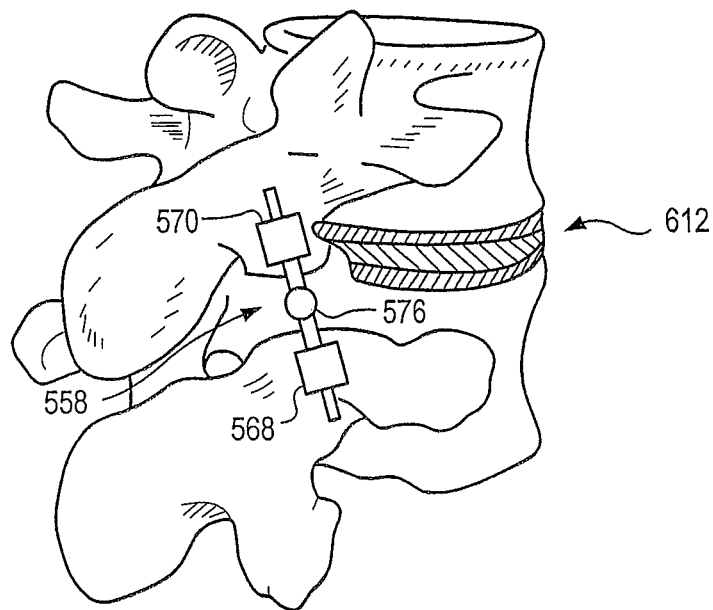


FIG. 30

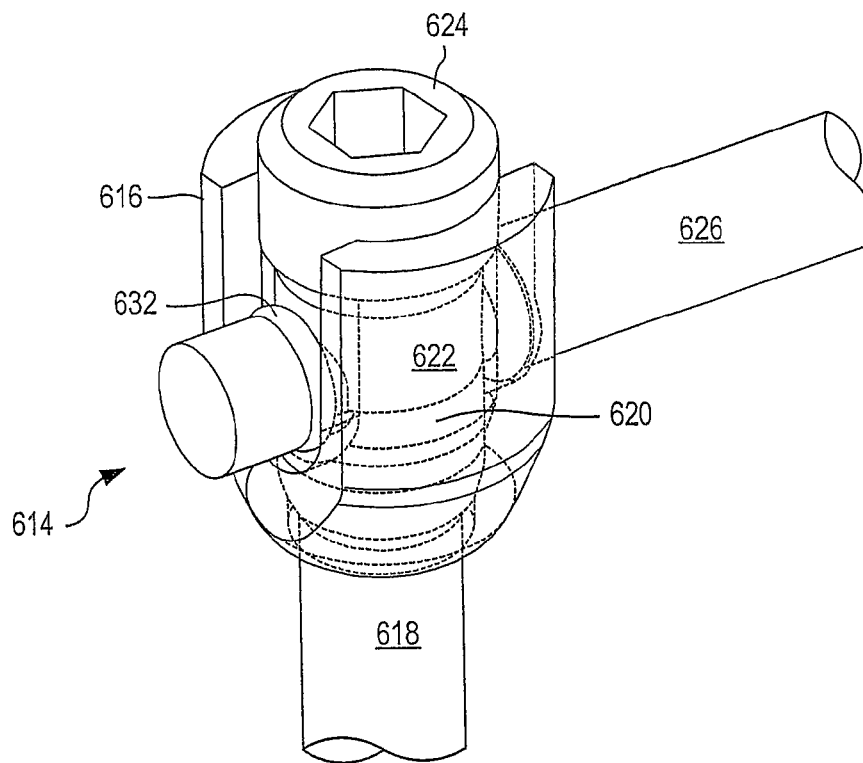


FIG. 31A

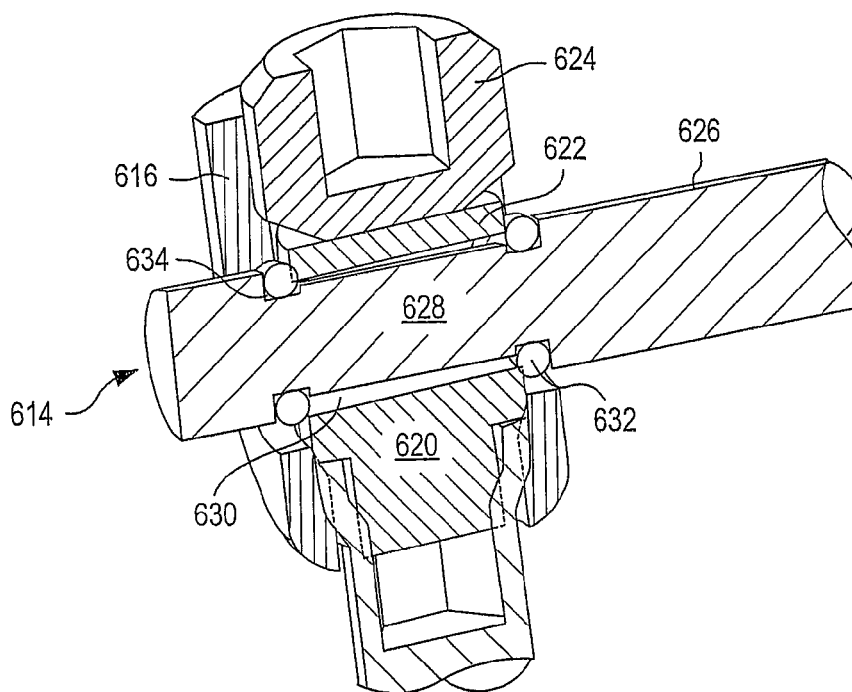


FIG. 31B

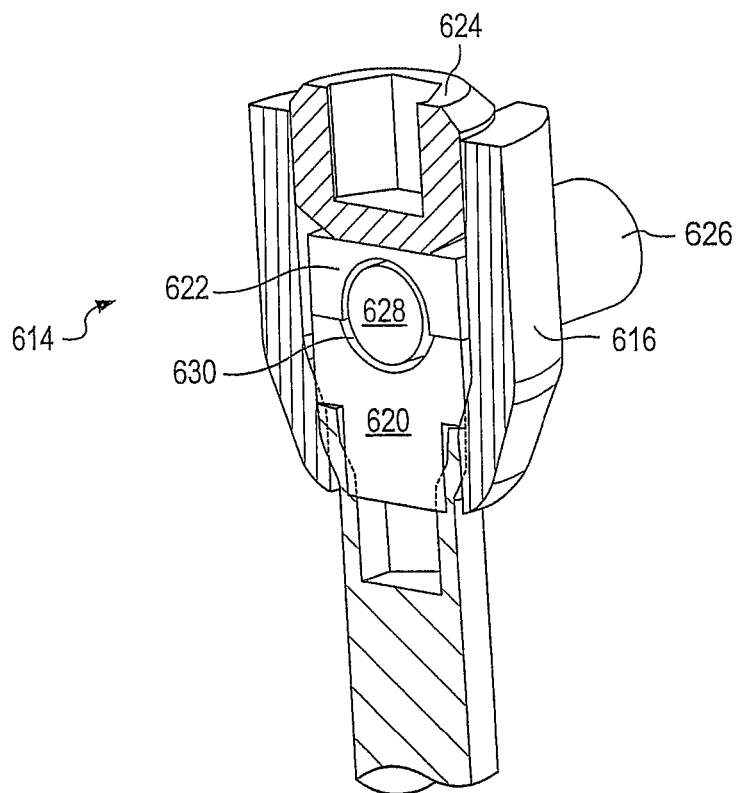


FIG. 31C

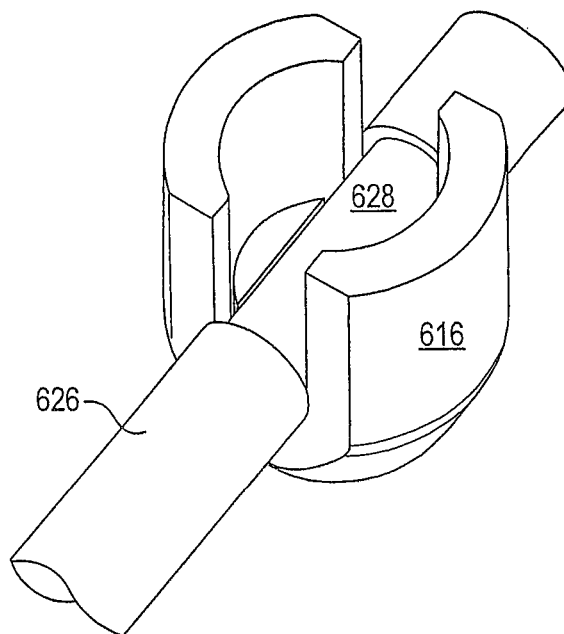


FIG. 31D

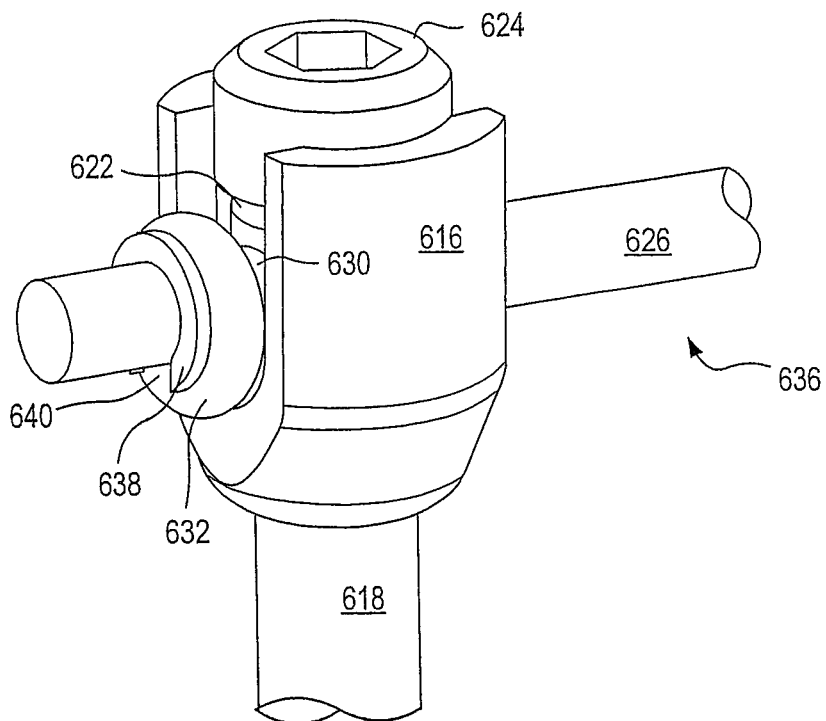


FIG. 32

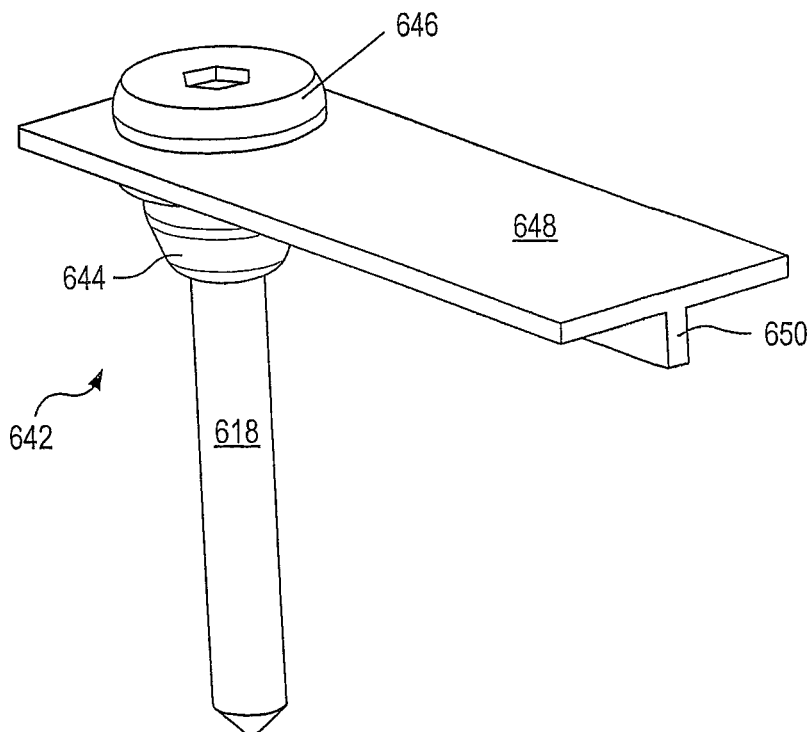


FIG. 33A

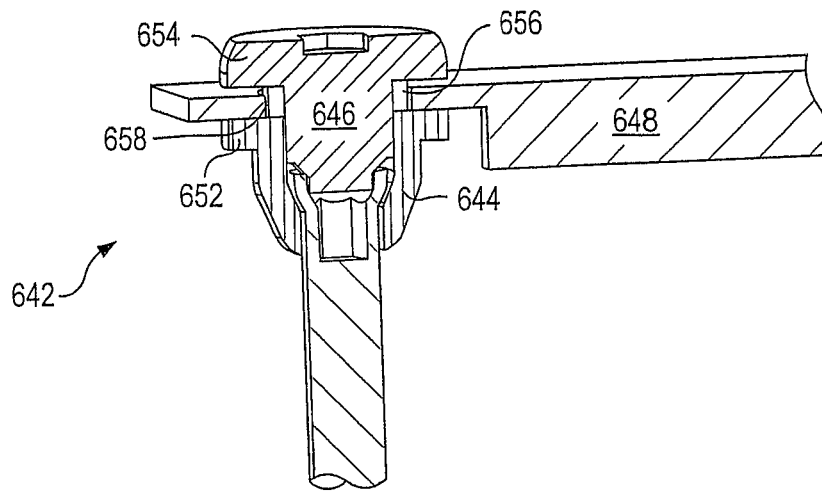


FIG. 33B

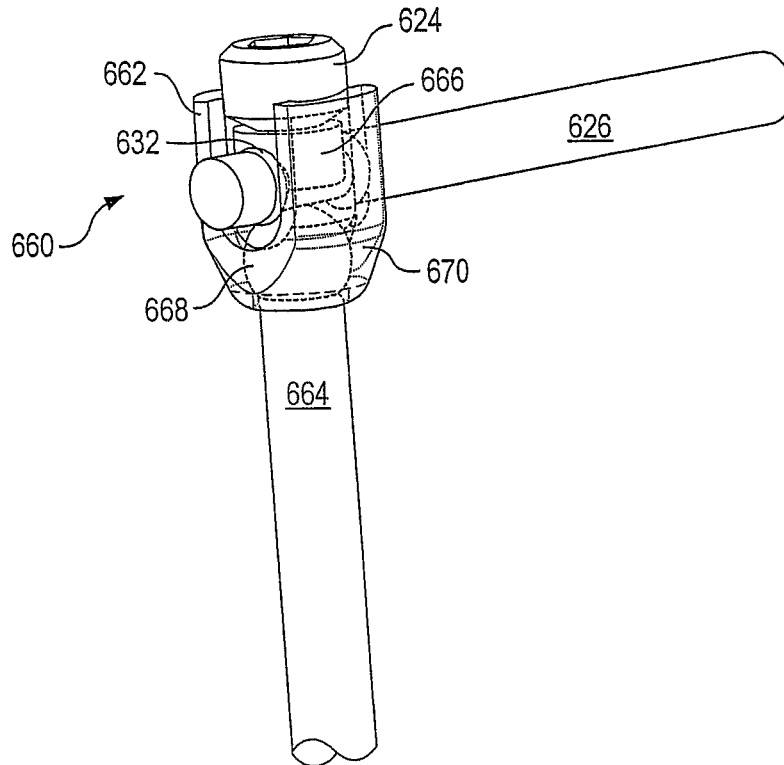


FIG. 34A

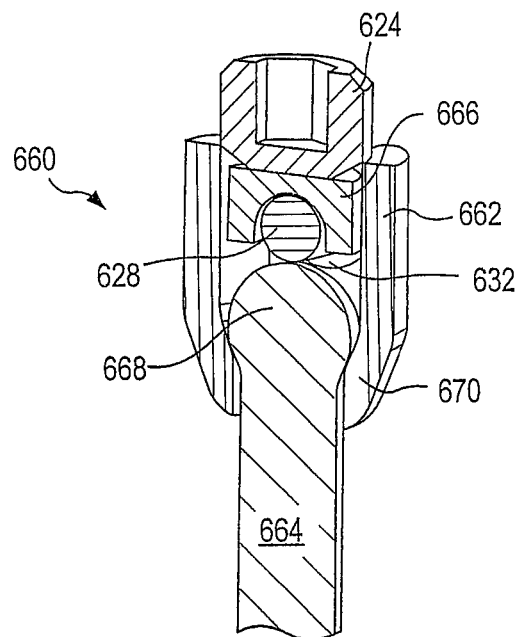


FIG. 34B

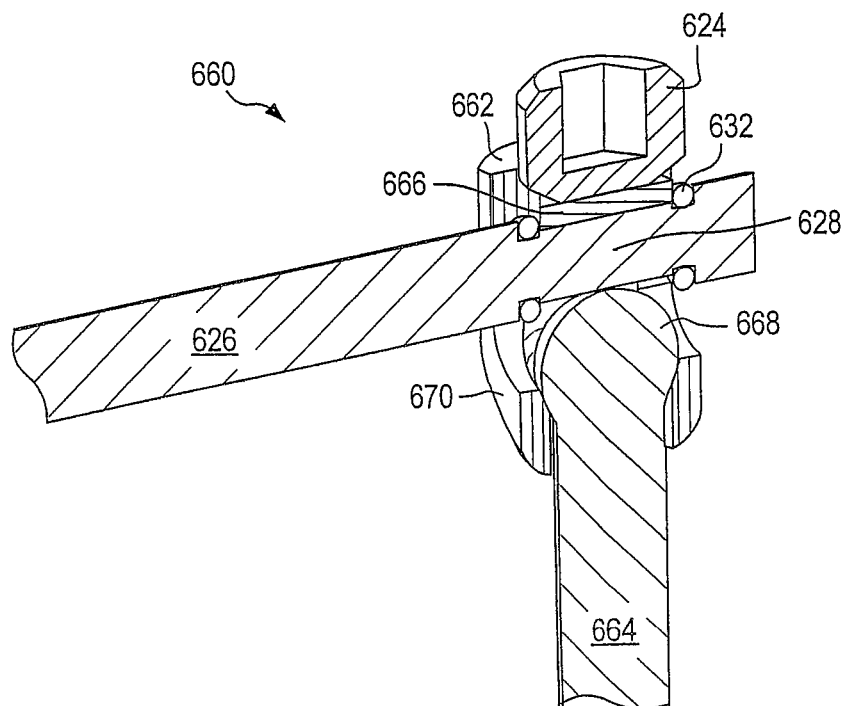
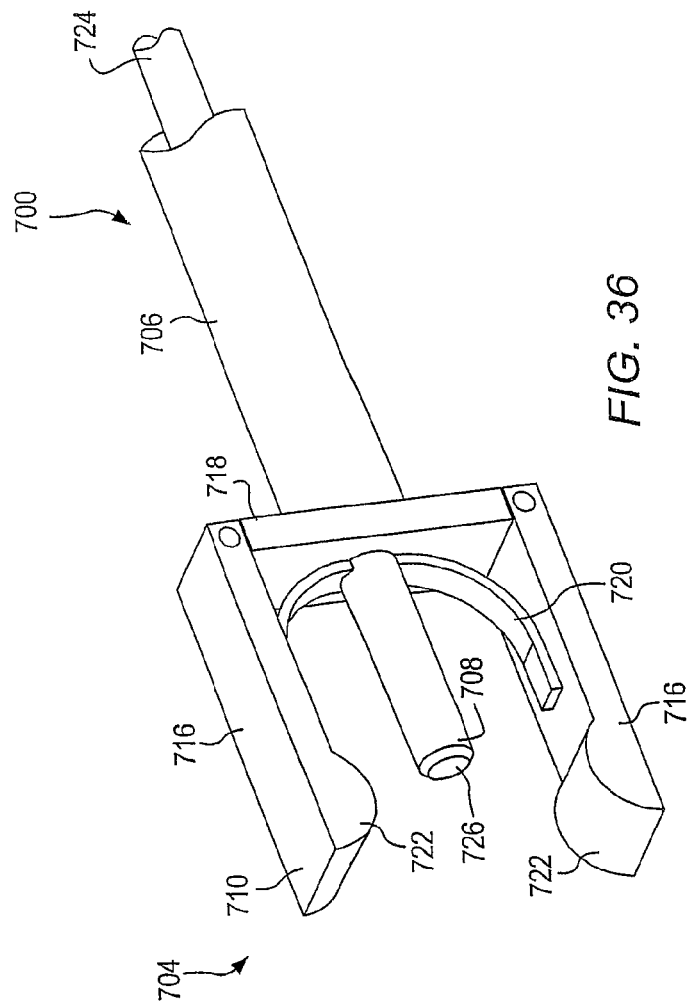
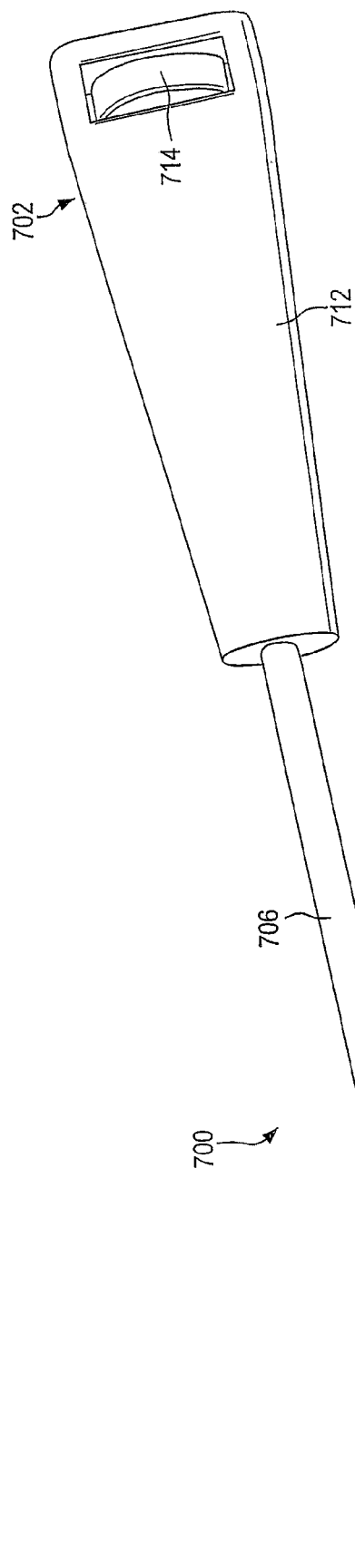


FIG. 34C



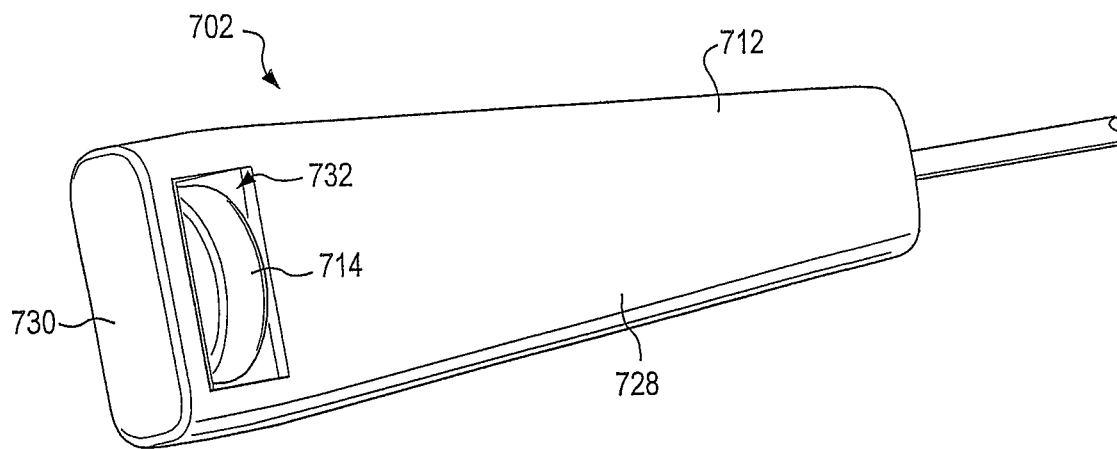


FIG. 37

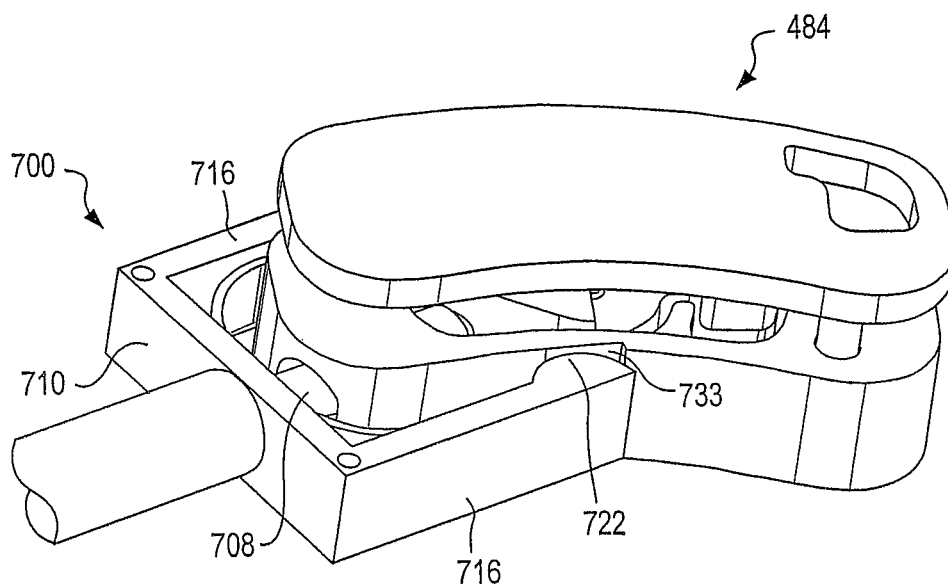
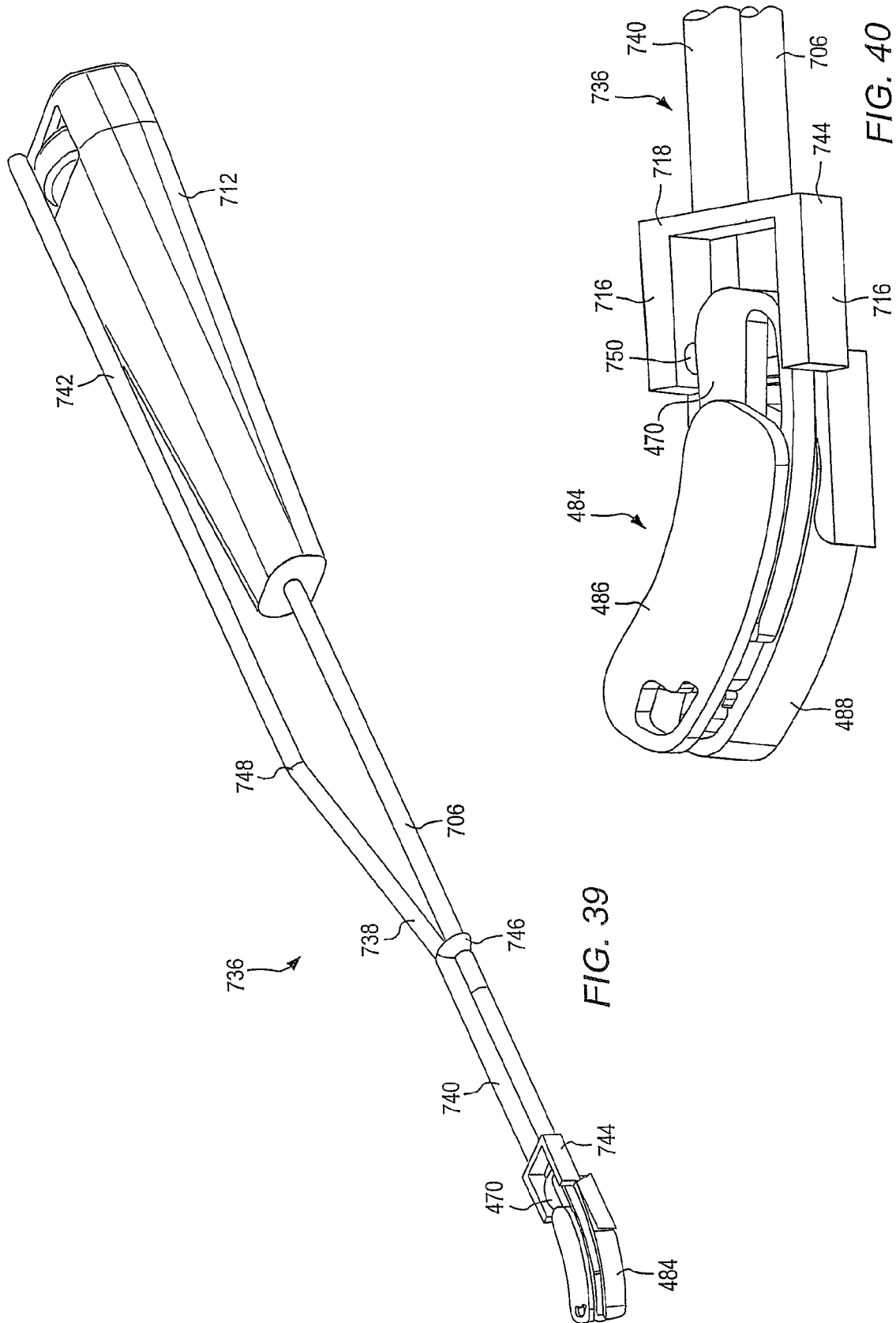


FIG. 38



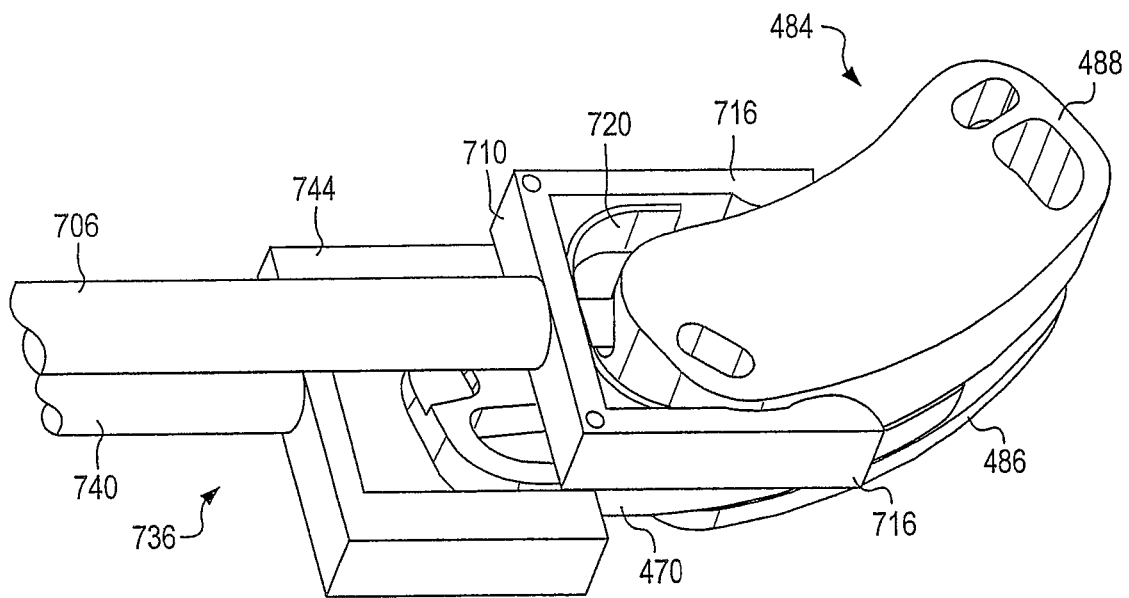


FIG. 41

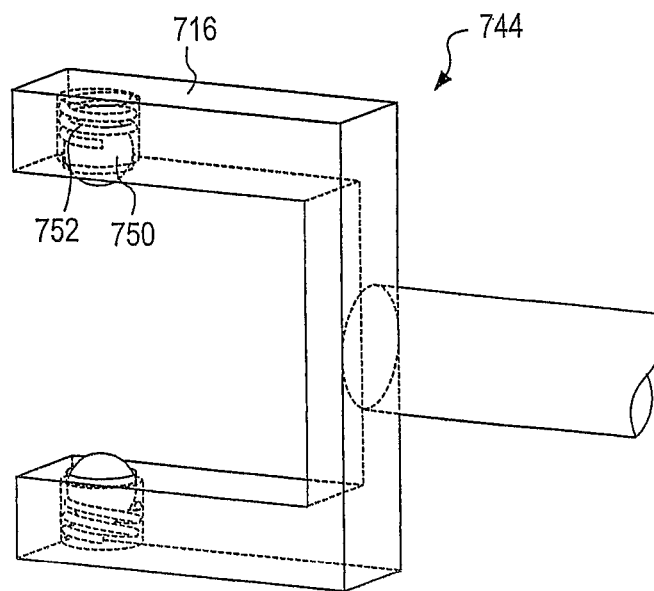


FIG. 42

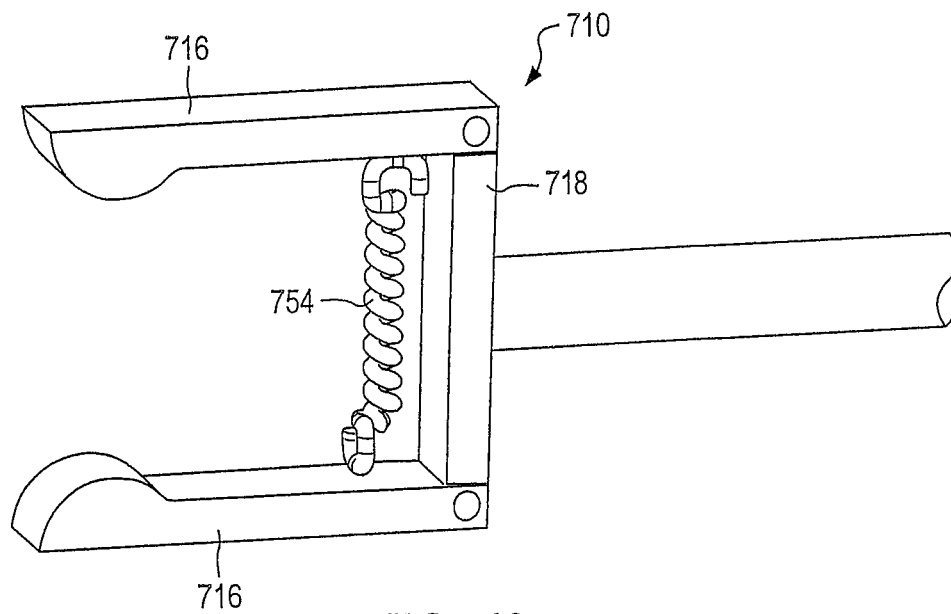


FIG. 43

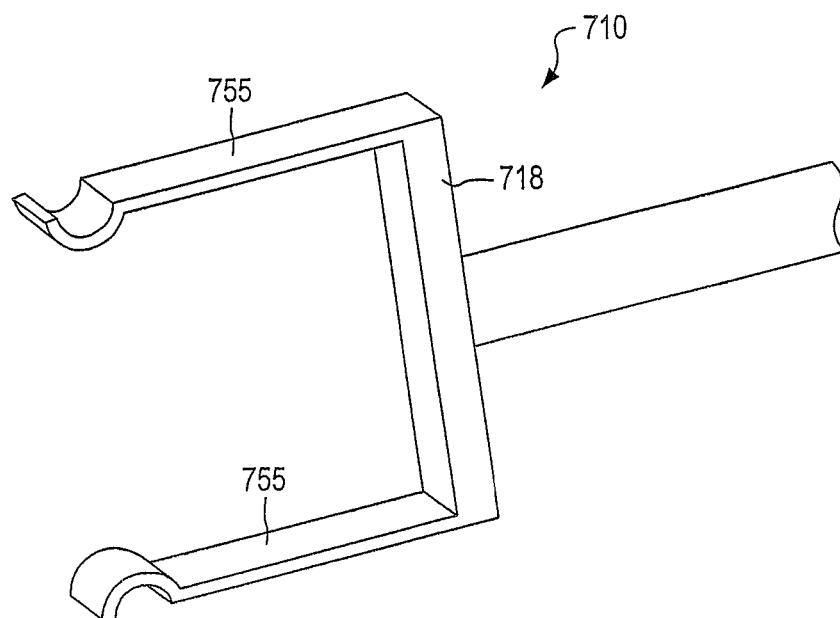


FIG. 44

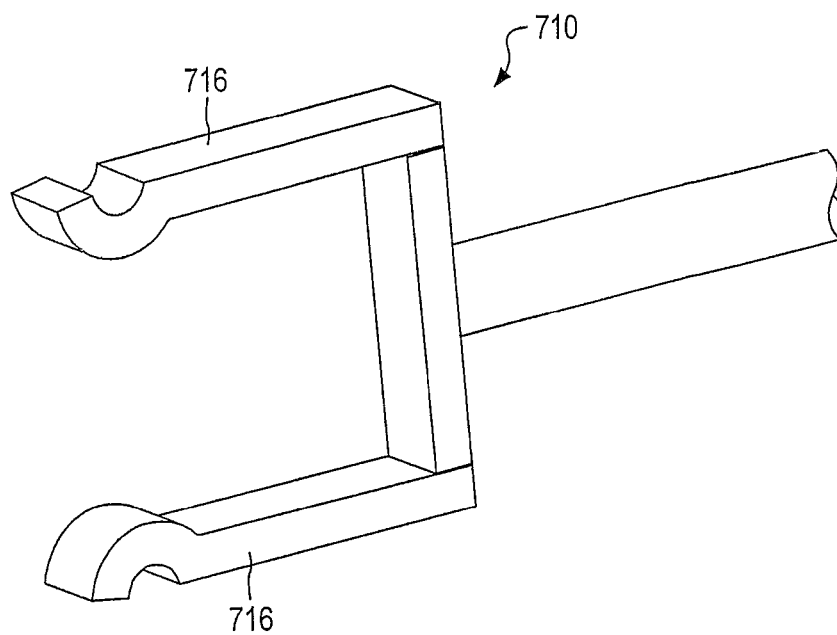


FIG. 45

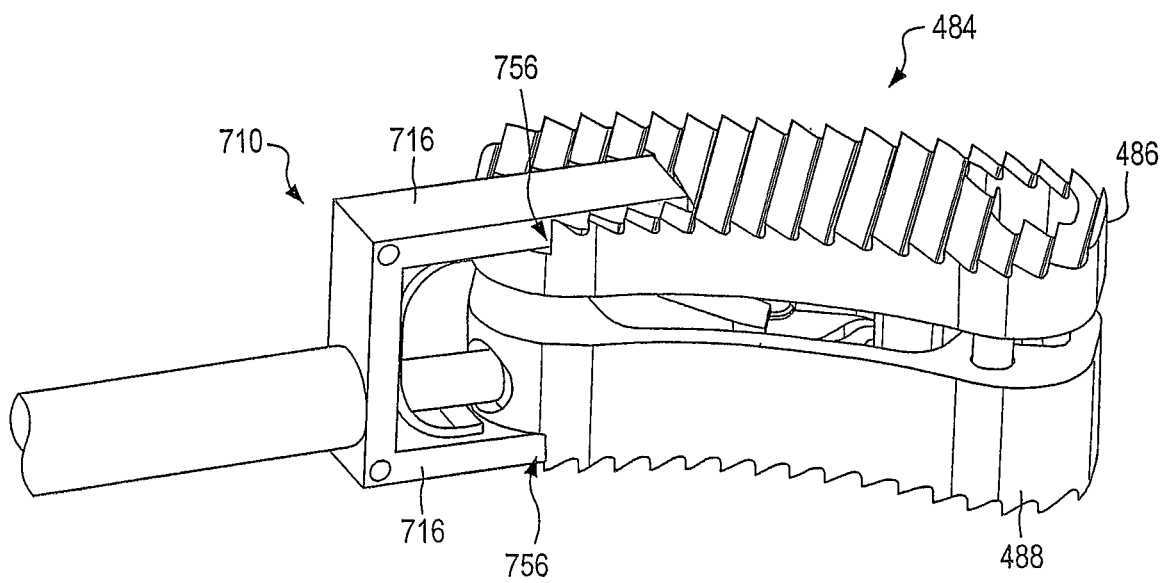
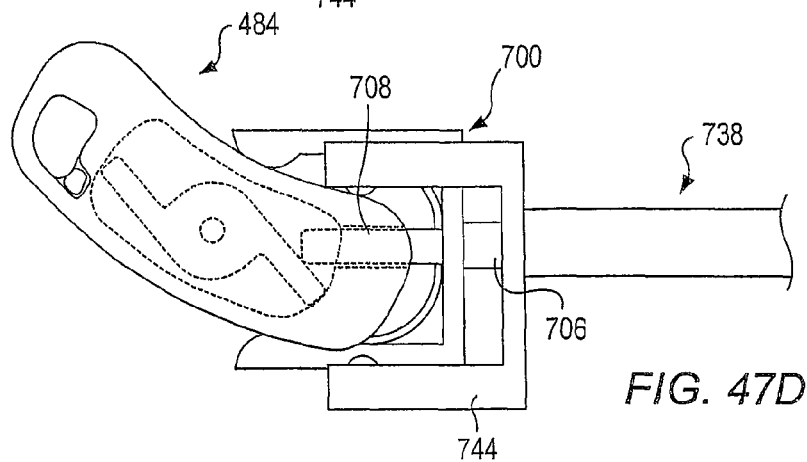
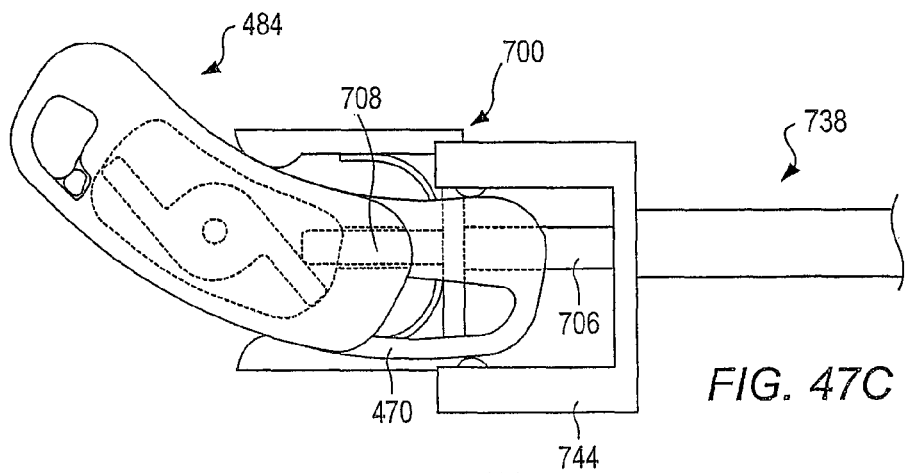
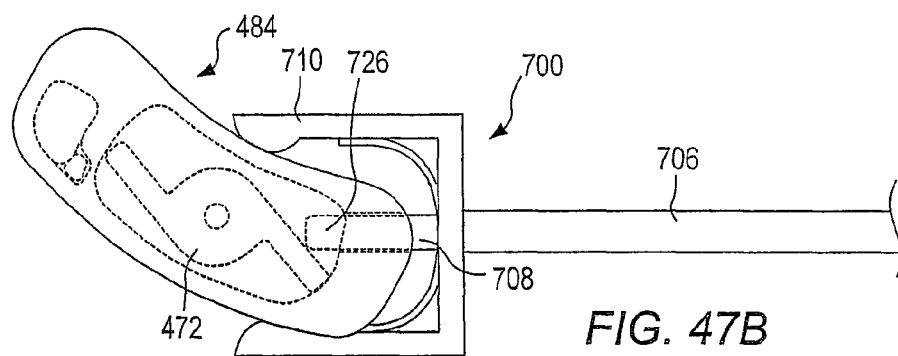
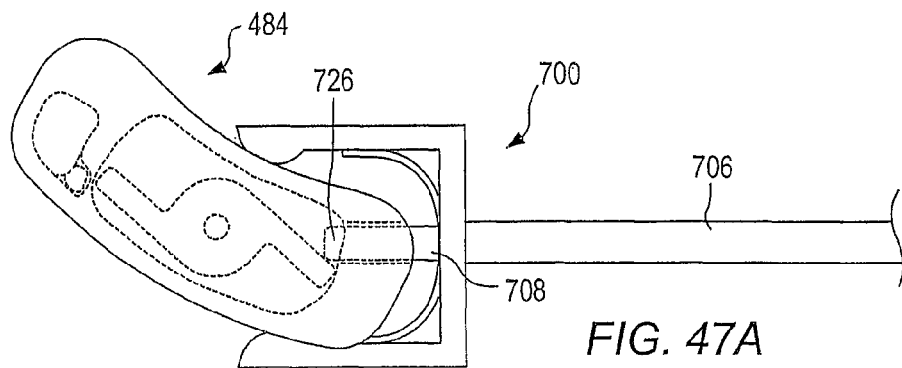


FIG. 46



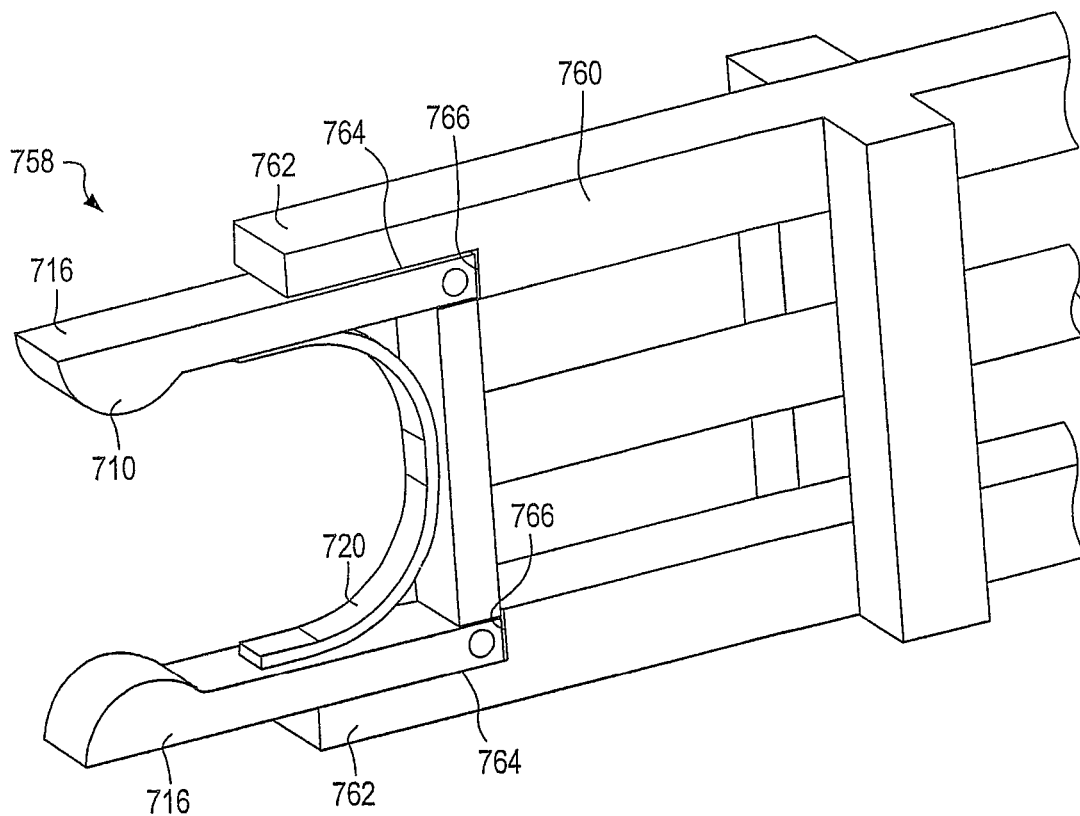


FIG. 48

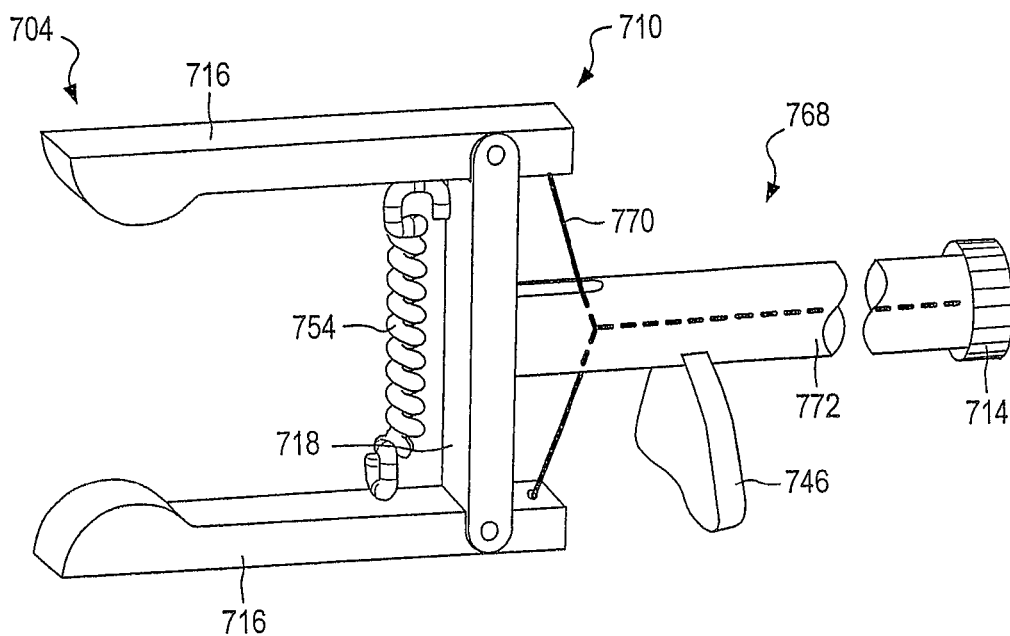


FIG. 49

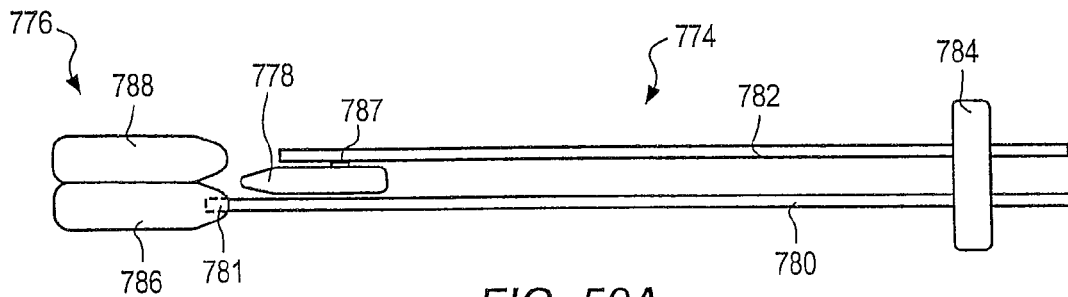


FIG. 50A

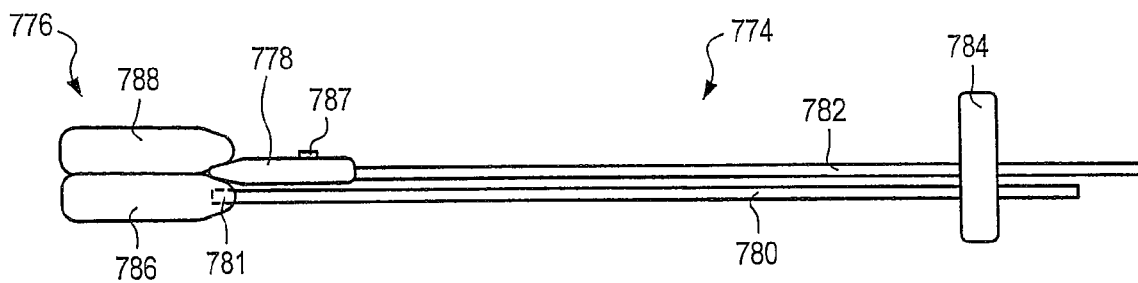


FIG. 50B

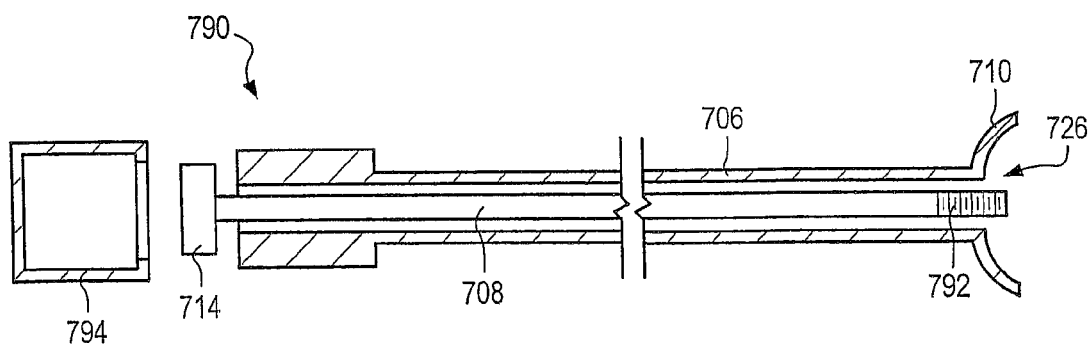


FIG. 51

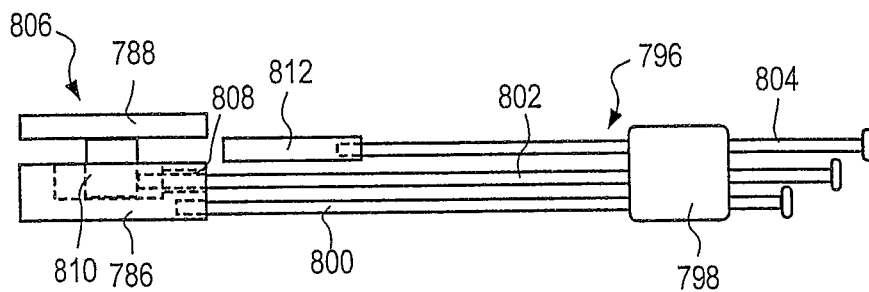


FIG. 52A

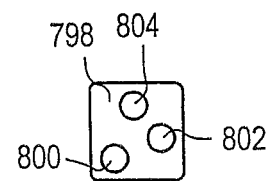


FIG. 52B

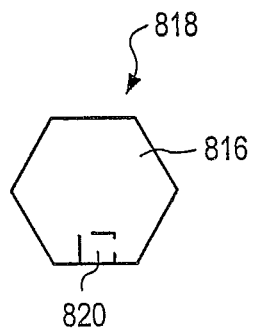


FIG. 53

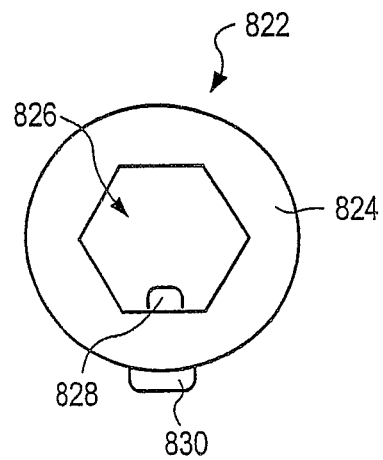


FIG. 54

EXPANDABLE INTERVERTEBRAL IMPLANT SYSTEM AND METHOD

PRIORITY

This application is a continuation of U.S. patent application Ser. No. 11/134,091 entitled "Method of Insertion of an Expandable Intervertebral Implant" to Charles R. Gordon, Corey T. Harbold, and Heather S. Hanson filed on May 20, 2005 which is a continuation of U.S. patent application Ser. No. 11/050,632 entitled "Functional Spinal Units" to Charles R. Gordon, Corey T. Harbold, and Heather S. Hanson, filed on Feb. 3, 2005. U.S. patent application Ser. No. 11/050,632 is a continuation in part of U.S. patent application Ser. No. 10/634,950; U.S. patent application Ser. No. 10/660,155; U.S. patent application Ser. No. 10/777,411; and PCT Application No. US2004/025090. PCT Application US2004/025090 entitled "Artificial Spinal Unit Assemblies" to Charles Gordon and Corey Harbold, filed on Aug. 4, 2004, claims the benefit of U.S. patent application Ser. No. 10/634,950; U.S. patent application Ser. No. 10/660,155; and U.S. patent application Ser. No. 10/777,411. U.S. patent application Ser. No. 10/777,411 entitled "Artificial Spinal Unit Assemblies" to Charles Gordon and Corey Harbold, filed on Feb. 12, 2004, is a continuation in part of U.S. patent application Ser. No. 10/634,950. U.S. patent application Ser. No. 10/660,155 entitled "Artificial Functional Spinal Unit Assemblies" to Charles Gordon and Corey Harbold, filed on Sep. 11, 2003, is a continuation in part of U.S. patent application Ser. No. 10/634,950. U.S. patent application Ser. No. 10/634,950 entitled "Artificial Functional Spinal Unit Assemblies" to Charles Gordon and Corey Harbold was filed on Aug. 5, 2003. Each of the above identified documents are hereby incorporated by reference.

BACKGROUND

1. Field of the Invention

Embodiments of the invention generally relate to functional spinal implant assemblies for insertion into an intervertebral space between adjacent vertebrae of a human spine, and reconstruction of the posterior elements to provide stability, flexibility, and proper biomechanical motion. More specifically, embodiments of the invention relate to artificial functional spinal units including an expandable artificial intervertebral implant that can be inserted via a posterior surgical approach and used in conjunction with one or more facet replacement devices to approach an anatomically correct range of motion. Embodiments of the invention may also be inserted via an anterior surgical approach.

2. Description of Related Art

The human spine is a complex mechanical structure including alternating bony vertebrae and fibrocartilaginous discs that are connected by strong ligaments and supported by musculature that extends from the skull to the pelvis and provides axial support to the body. The intervertebral discs provide mechanical cushion between adjacent vertebral segments of the spinal column and generally include three basic components: the nucleus pulposus, the annulus fibrosis, and two vertebral end plates. The end plates are made of thin cartilage overlying a thin layer of hard cortical bone that attaches to the spongy, cancellous bone of the vertebral body. The annulus fibrosis forms the disc's perimeter and is a tough outer ring that binds adjacent vertebrae together. The vertebrae generally include a vertebral foramen bounded by the anterior vertebral body and the neural arch, which consists of two pedicles and two laminae that are united posteriorly. The

spinous and transverse processes protrude from the neural arch. The superior and inferior articular facets lie at the root of the transverse process.

The human spine is a highly flexible structure capable of a high degree of curvature and twist in nearly every direction. However, genetic or developmental irregularities, trauma, chronic stress, and degenerative wear can result in spinal pathologies for which surgical intervention may be necessary. In cases of deterioration, disease, or injury, a spinal disc may be removed from a human spine. A disc may become damaged or diseased, reducing intervertebral separation. Reduction of the intervertebral separation may reduce a height of the disc nucleus, which may cause the annulus to buckle in areas where the laminated plies are loosely bonded. As the overlapping laminated plies of the annulus begin to buckle and separate, circumferential or radial annular tears may occur. Such disruption to the natural intervertebral separation may produce pain, which may be alleviated by removal of the disc and maintenance of the natural separation distance. In cases of chronic back pain resulting from a degenerated or herniated disc, removal of the disc becomes medically necessary.

In some cases, a damaged disc may be replaced with a disc prosthesis intended to duplicate the function of a natural spinal disc. U.S. Pat. No. 4,863,477 to Monson, which is incorporated herein by reference, discloses a resilient spinal disc prosthesis intended to replace the resilience of a natural human spinal disc. U.S. Pat. No. 5,192,326 to Bao et al., which is incorporated herein by reference, describes a prosthetic nucleus for replacing just the nucleus portion of a human spinal disc. U.S. Patent Application Publication No. 2005/0021144 to Malberg et al., which is incorporated herein by reference, describes an expandable spinal implant.

In other cases, it may be desirable to fuse adjacent vertebrae of a human spine together after removal of a disc. This procedure is generally referred to as "intervertebral fusion" or "interbody fusion." Intervertebral fusion has been accomplished with a variety of techniques and instruments. It is generally known that the strongest intervertebral fusion is the interbody fusion (between the lumbar bodies), which may be augmented by a posterior or facet fusion. In cases of intervertebral fusion, either structural bone or an interbody fusion cage filled with bone graft material (e.g., morselized bone) is placed within the space where the spinal disc once resided. Multiple cages or bony grafts may be used within that space.

Cages of the prior art have been generally successful in promoting fusion and approximating proper disc height. Cages inserted from the posterior approach, however, are limited in size by the interval between the nerve roots. Therefore, a fusion implant assembly that could be expanded from within the intervertebral space could reduce potential trauma to the nerve roots and yet still allow restoration of disc space height. It should be noted, however, that fusion limits overall flexibility of the spinal column and artificially constrains the natural motion of the patient. This constraint may cause collateral injury to the patient's spine as additional stresses of motion, normally borne by the now-fused joint, are transferred onto the nearby facet joints and intervertebral discs. Thus, an implant assembly that mimics the biomechanical action of the natural disc cartilage, thereby permitting continued normal motion and stress distribution, would be advantageous.

A challenge of instrumenting a disc posteriorly is that a device large enough to contact the end plates and slightly expand the space must be inserted through a limited space. This challenge is often further heightened by the presence of posterior osteophytes, which may cause "fish mouting" of the posterior end plates and result in very limited access to the

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disc. A further challenge in degenerative disc spaces is the tendency of the disc space to assume a lenticular shape, which requires a relatively larger implant than often is easily introduced without causing trauma to the nerve roots. The size of rigid devices that may safely be introduced into the disc space is thereby limited.

The anterior approach poses significant challenges as well. Though the surgeon may gain very wide access to the interbody space from the anterior approach, this approach has its own set of complications. The retroperitoneal approach usually requires the assistance of a surgeon skilled in dealing with the visceral contents and the great vessels, and the spine surgeon has extremely limited access to the nerve roots. Complications of the anterior approach that are approach-specific include retrograde ejaculation, ureteral injury, and great vessel injury. Injury to the great vessels may result in massive blood loss, postoperative venous stasis, limb loss, and intraoperative death. The anterior approach is more difficult in patients with significant obesity and may be virtually impossible in the face of previous retroperitoneal surgery.

Despite its difficulties, the anterior approach does allow for the wide exposure needed to place a large device. In accessing the spine anteriorly, one of the major structural ligaments, the anterior longitudinal ligament, must be completely divided. A large amount of anterior annulus must also be removed along with the entire nucleus. Once these structures have been resected, the vertebral bodies are over distracted in order to place the device within the disc and restore disc space height. Failure to adequately tension the posterior annulus and ligaments increases the risk of device failure and migration. Yet in the process of placing these devices, the ligaments are overstretched while the devices are forced into the disc space under tension. This over distraction can damage the ligaments and the nerve roots. The anterior disc replacement devices currently available or in clinical trials may be too large to be placed posteriorly, and may require over distraction during insertion in order to allow the ligaments to hold them in position.

SUMMARY

In some embodiments, provided is an intervertebral implant system for a human spine including a first body having a first external surface to be disposed adjacent a first vertebrae during use and a first internal surface opposite the first external surface, a second body having a second external surface to be disposed adjacent a second vertebrae during use and a second internal surface opposite the second external surface, an elongated insertion instrument releasably coupleable to the first or second body during use, and a spacer linearly advanced between the first internal surface of the first body and the first internal surface of the second body during use. The elongated insertion instrument guides at least a portion of the linear advancement of the spacer, and wherein the linear advancement of the spacer results in expansion of the intervertebral implant such that the first external surface and the second external surface move away from one another to expand a height of the implant.

In some embodiments, provided is a method of implanting an intervertebral implant into a human spine including: disposing an upper body into an intervertebral space between an upper vertebrae and a lower vertebrae, wherein the upper body includes a superior surface disposed adjacent the upper vertebrae and an inferior surface opposite the superior surface, disposing a lower body into the intervertebral space between the upper vertebrae and the lower vertebrae, wherein the lower body includes an inferior surface disposed adjacent

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the lower vertebrae and a superior surface opposite the inferior surface, releasably coupling an elongated insertion instrument to at least one of the upper body and the lower body, and linearly advancing a spacer between the inferior surface of the upper body and the superior surface of the lower body. The elongated insertion instrument guides at least a portion of linear advancement of the spacer, and wherein linear advancement of the spacer results in expansion of the intervertebral implant such that the superior surface of the upper member and the inferior surface of the lower member move away from one another to expand a height of the implant.

In some embodiments, provided is an intervertebral implant system for a human spine including an upper body to be disposed in an intervertebral space between an upper vertebrae and a lower vertebrae during use, wherein the upper body has a superior surface disposed adjacent the upper vertebrae and an inferior surface opposite the superior surface, a lower body to be disposed into the intervertebral space between the upper vertebrae and the lower vertebrae during use, wherein the lower body has an inferior surface disposed adjacent the lower vertebrae and a superior surface opposite the inferior surface, an elongated insertion instrument to releasably coupled to at least one of the upper body and the lower body during use, and a spacer to be linearly advanced between the inferior surface of the upper body and the superior surface of the lower body during use. The elongated insertion instrument guides at least a portion of linear advancement of the spacer, and wherein linear advancement of the spacer results in expansion of the intervertebral implant such that the superior surface of the upper member and the inferior surface of the lower member move away from one another to expand a height of the implant.

BRIEF DESCRIPTION OF THE DRAWINGS

Advantages of the present invention will become apparent to those skilled in the art with the benefit of the following detailed description and upon reference to the accompanying drawings in which:

FIG. 1 depicts a top view of an embodiment of a cylindrical, expandable implant.

FIG. 2A is a side cross-sectional view of the embodiment depicted in FIG. 1.

FIG. 2B is a side cross-sectional view of the implant embodiment depicted in FIG. 1.

FIG. 3A is a cross-sectional view of an embodiment of an expandable implant in extension.

FIG. 3B is a cross-sectional view of an embodiment of an expandable implant in flexion.

FIG. 4A is a cross-sectional view of an embodiment of an expandable implant prior to expansion.

FIG. 4B is a cross-sectional view of an embodiment of an expandable implant following expansion.

FIG. 4C is a cross-sectional view of an embodiment of an expandable implant employing buttress screws to secure the device between vertebrae.

FIG. 4D is a cross-sectional view of an embodiment of an expandable implant employing an expansion plate with a securing keel to secure the device between vertebrae.

FIG. 4E is a side perspective of an embodiment of an expandable implant employing a securing keel.

FIG. 5 is a side perspective view illustrating placement of an expandable implant in an intervertebral space.

FIG. 6A depicts a top view of an embodiment of a c-shaped, expandable implant.

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FIG. 6B is a top view of an embodiment of a c-shaped expandable implant, illustrating insertion of expansion screws to expand the implant.

FIG. 6C is a top view of an embodiment of a c-shaped, expandable implant, illustrating insertion of a non-threaded expansion member to expand the implant.

FIG. 6D is a top view of an embodiment of a c-shaped, expandable implant with a posteriorly positioned expansion opening.

FIG. 7A is a cross-sectional view of an embodiment of an expandable, articulating implant including an insert with stops.

FIG. 7B is a cross-sectional view of the embodiment depicted in FIG. 7A showing articulation of the implant.

FIG. 8A is a top view of an embodiment of a c-shaped, expandable implant, illustrating the insertion of an expansion plate to expand the implant.

FIG. 8B is a side cross-sectional view of an embodiment of a c-shaped, expandable implant, illustrating the insertion of an expansion plate to expand the implant.

FIG. 8C is a side cross-sectional view of an embodiment of an expandable implant, featuring stabilizers.

FIG. 8D is a side cross-sectional view of an embodiment of an expandable implant in flexion, featuring stabilizers.

FIG. 9A is a top view of an embodiment of an expandable cage.

FIG. 9B is a side cross-sectional view of an embodiment of an expandable cage prior to expansion.

FIG. 9C is a side cross-sectional view of an embodiment of an expandable following expansion.

FIG. 9D is a side cross-sectional view of an embodiment of an expandable cage with a larger upper surface area prior to expansion.

FIG. 9E is a side cross-sectional view of an embodiment of an expandable cage with a larger upper surface area following expansion.

FIG. 9F is a cross-sectional view of an embodiment of a cage that is expandable in two directions.

FIG. 10A is a posterior view of an embodiment of a c-shaped lordotic expandable implant.

FIG. 10B is a top view of an embodiment of a c-shaped lordotic expandable implant.

FIG. 11A is a lateral view of an embodiment of a c-shaped lordotic expandable implant prior to expansion.

FIG. 11B is a lateral view of an embodiment of a c-shaped lordotic expandable implant following expansion.

FIG. 12A is a side cross-sectional view of an embodiment of an expandable lordotic cage prior to expansion.

FIG. 12B is a side cross-sectional view of an embodiment of an expandable lordotic cage following expansion.

FIG. 13A is a lateral view of an embodiment of a c-shaped lordotic expandable implant with an inclined expansion member.

FIG. 13B is a side cross-sectional view of an embodiment of an expandable lordotic cage with an inclined expansion member.

FIG. 14A is a perspective view of an embodiment of an expandable, articulating implant with a spiral cam.

FIG. 14B is a cross-sectional view of the implant embodiment depicted in FIG. 14A prior to expansion.

FIG. 14C is a cross-sectional view of the implant embodiment depicted in FIG. 14A following expansion.

FIG. 15A is a top view of an embodiment of a c-shaped expandable, articulating implant with a round insert.

FIG. 15B is a side cross-sectional view of an embodiment of a c-shaped implant with an expansion member/advancing element combination prior to expansion.

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FIG. 15C is a side cross-sectional view of an embodiment of a c-shaped implant with an expansion member/advancing element combination following expansion.

FIG. 16A is a perspective view of an embodiment of an expandable, articulating implant before expansion.

FIG. 16B is a perspective view of an embodiment of an expandable, articulating implant following expansion.

FIG. 17 is a perspective view of an embodiment of a portion of an implant with a double-wedged expansion member.

FIG. 18A is a cross-sectional view of an embodiment of an expandable, articulating implant with a wedged insert.

FIG. 18B is a top view of an embodiment of a spacer.

FIG. 19A is a perspective view of an embodiment of an expandable cage with an elongated insert.

FIG. 19B is a cross-sectional view of the expandable cage embodiment depicted in FIG. 19A.

FIG. 19C is a view of the inferior surface of the upper body of the cage depicted in FIG. 19A.

FIG. 20A is a perspective view of an embodiment of a cage including a cam and cam ramps.

FIG. 20B is a view of the inferior surface of the upper body of the embodiment of the cage depicted in FIG. 20A.

FIG. 20C illustrates the use of an advancing element to advance the cam onto the cam ramp of the cage embodiment depicted in FIG. 20B.

FIG. 20D is a cross-sectional view of an embodiment of an articulating cage including a cam and cam ramps.

FIG. 21A depicts a perspective view of an embodiment of an expandable, articulating cage with toothed engaging surfaces.

FIG. 21B depicts a perspective view of the cage depicted in FIG. 21A (without the toothed engaging surface) after expansion.

FIG. 22 depicts a perspective view of an embodiment of an insert with four cam ramps.

FIG. 23 depicts a perspective view of an embodiment of a portion of a cage with cam ramps and stabilizers.

FIG. 24A depicts a perspective view of an embodiment of a spacer coupled to an insert of an implant.

FIG. 24B depicts a perspective view of an embodiment of a spacer with a protrusion.

FIG. 24C depicts a perspective view of an embodiment of a spacer with a protrusion and a lip.

FIG. 24D depicts a perspective view of an embodiment of an insert with a recess for accepting a protrusion of a spacer.

FIG. 24E depicts a cross-sectional view of an embodiment of a spacer with a lip coupled to an insert in an expandable cage.

FIG. 25 depicts a perspective view of an embodiment of insertion of a spacer into an expanded cage.

FIG. 26A depicts a perspective view of an embodiment of insertion of a spacer into an expanded cage.

FIG. 26B depicts a perspective view of an embodiment of the cage depicted in FIG. 26A after insertion of the spacer.

FIG. 26C depicts a perspective view of an embodiment of the cage depicted in FIG. 26A after insertion of the spacer.

FIG. 27 depicts a perspective view of an embodiment of an expanded cage with a large profile spacer.

FIG. 28A is a side view of an embodiment of a facet replacement device, featuring a rod with two washer-type heads.

FIG. 28B is a side view of an embodiment of a portion of a facet replacement device, featuring a rod with a single washer-type head.

FIG. 28C is a cross-sectional view of an embodiment of a pedicle screw featuring a locking screw head.

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FIG. 28D is a cross-sectional view of an embodiment of a pedicle screw featuring a head-locking insert that allows translation and rotation of a rod.

FIG. 29A is a side view of an embodiment of a portion of a facet replacement device, featuring a rod having a ball joint.

FIG. 29B is a side view of an embodiment of a portion of a facet replacement device featuring a retaining plate.

FIG. 29C is a top view of an embodiment of a portion of a facet replacement device featuring a retaining plate.

FIG. 29D is a top view of an embodiment of a portion of a facet replacement device featuring a combination multi-axial pedicle screw and retaining bar with post-type pedicle screw system.

FIG. 29E is a side view of an embodiment of a post-type pedicle screw.

FIG. 29F illustrates attachment of the retaining bar to the post-type pedicle screw.

FIG. 30 is a posterior view of a portion of a human spine after reconstruction and implantation of an embodiment of an artificial functional spinal unit including an expandable implant and a facet replacement device.

FIG. 31A is a perspective view of an embodiment of a portion of a facet replacement device.

FIG. 31B is a cross-sectional view of the facet replacement device depicted in FIG. 31A.

FIG. 31C is a cross-sectional view of the facet replacement device depicted in FIG. 31A.

FIG. 31D is a perspective view of an embodiment of a reduced diameter portion of a rod resting in a pedicle screw head of a facet replacement device.

FIG. 32 is a perspective view of an embodiment of a portion of a facet replacement device with a retainer to limit the motion of a rod.

FIG. 33A is a perspective view of an embodiment of a portion of a facet replacement device designed to couple to a plate with a T-shaped cross section.

FIG. 33B is a cross-sectional view of the facet replacement device depicted in FIG. 33A.

FIG. 34A is a perspective view of an embodiment of a portion of a facet replacement device including a pedicle screw with a ball joint.

FIG. 34B is a cross-sectional view of the facet replacement device depicted in FIG. 34A.

FIG. 34C is a cross-sectional view of the facet replacement device depicted in FIG. 34A.

FIG. 35 is a perspective view of an instrument for installing and expanding an implant.

FIG. 36 is a detail view of a distal end of an instrument for installing and expanding an implant.

FIG. 37 is a detail view of a proximal end of an instrument for installing and expanding an implant.

FIG. 38 is a perspective view of an expandable implant held by an instrument including a holding device and expansion driver.

FIG. 39 is a perspective view of an instrument for installing an expandable implant including a spacer.

FIG. 40 is a perspective top view of an expandable implant held by an instrument with a partially inserted spacer.

FIG. 41 is a perspective bottom view of an expandable implant with a partially inserted spacer.

FIG. 42 is a perspective view of a holding device including opposing arms with ball detent mechanisms.

FIG. 43 is a perspective view of a holding device including opposing arms coupled by a coil spring.

FIG. 44 is a perspective view of a holding device including opposing spring arms.

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FIG. 45 is a perspective view of a holding device with shape memory alloy arms.

FIG. 46 is a perspective view of an implant held in a holding device including upper and lower holding arms.

FIGS. 47A-47D illustrate use of an instrument to expand an implant and install a spacer.

FIG. 48 is a perspective view of a distal end of an instrument including a holding device with a slide.

FIG. 49 is a perspective view of an instrument with a holding device coupled to a control member.

FIG. 50A is a side view of a dual rod instrument during guided advancement of a spacer.

FIG. 50B is a side view of a dual rod instrument with one rod positioned to impact the spacer between upper and lower bodies of an implant.

FIG. 51 is a cross-sectional view of an instrument including a driving portion that directly engages an insert for expanding an implant.

FIGS. 52A and 52B are side views of an instrument including multiple rods with threaded ends.

FIG. 53 is a schematic end view of a head of a fastener for a spinal system.

FIG. 54 is a schematic end view of a driver for a fastener of a spinal system.

While the invention may be susceptible to various modifications and alternative forms, specific embodiments thereof are shown by way of example in the drawings and will herein be described in detail. The drawings may not be to scale. It should be understood, however, that the drawings and detailed description thereto are not intended to limit the invention to the particular form disclosed, but to the contrary, the intention is to cover all modifications, equivalents, and alternatives falling within the spirit and scope of the present invention as defined by the appended claims.

DETAILED DESCRIPTION

As used herein, “implant” generally refers to an artificial intervertebral implant or cage. The shape and/or size of an implant or other device disclosed herein may be chosen according to factors including, but not limited to, the surgical approach employed for insertion (e.g., anterior or posterior), the intended position in the spine (e.g., cervical or lumbar), and a size of the patient. For example, cervical implants may range from about 6 mm to about 11 mm in height, and lumbar implants may range from about 10 mm to about 18 mm in height. Heights outside these ranges may be used as required by a patient's anatomy. In general, implants with a substantially round cross section may range from about 14 mm to about 26 mm in diameter, and implants with a substantially square cross section may range from a size of about 14 mm square to a size of about 26 mm square. Implants that are substantially rectangular or trapezoidal may range from about 8 mm to about 12 mm along short side of the implant to about 24 mm to about 30 mm along a long side of the implant. As used herein, “c-shaped” implants generally refer to implants with an arcuate shape. Some c-shaped implants may be slightly curved (e.g., “banana-shaped”), while other c-shaped implants may have a higher degree of curvature (e.g., more closely approximating a “c”).

It is to be understood that implants described herein may include features not necessarily depicted in each figure. In some embodiments, an endplate engaging surface of any implant may have regularly or irregularly spaced protrusions of uniform or various shapes and sizes to facilitate retention of the implant in a desired position between vertebrae. For example, an endplate engaging surface of an implant may

include teeth or ridges. In some embodiments, members of an implant may include one or more openings to accommodate packing of bone graft material and/or to allow for bone ingrowth. In certain embodiments, one or more surfaces of an implant may include material, such as osteoconductive scaffolding, to enhance integration of the implant in a patient's spine. In some embodiments, a substance to be delivered to a patient's body may be included in a portion of the implant for delivery to the insertion site. In certain embodiments, implants depicted herein may include features allowing the implant to provide a desired lordotic angle (e.g., up to about 15° between vertebrae).

As used herein, an "expandable" implant generally refers to an implant designed such that a height of the implant and/or a separation distance between two parts of the implant may be increased. In some embodiments, an implant may be expanded after insertion of the implant in a human spine. In certain embodiments, a height of an implant may be decreased after the implant has been expanded during insertion in a human spine. In other embodiments, expansion of an implant may be substantially irreversible after insertion in a human spine.

As used herein, an "articulating" implant generally refers to an implant designed such that at least two members of the implant are capable of undergoing rotational motion with respect to each other in at least one direction after insertion in a human spine. In some embodiments, one or more members of an articulating implant may be capable of rotating in more than one direction with respect one or more other members of the implant after insertion in a human spine to allow, for example, anterior-posterior rotation and/or lateral bending. In some embodiments, rotation may occur about fixed axes. In certain embodiments, an axis of rotation may change as one member of an implant rotates relative to another member of the implant. In some embodiments, one or more members of an articulating implant may be capable of translating with respect to one or more other members of the implant. As used herein, an articulating implant may also be described as "functional" or "dynamic".

Implant embodiments depicted herein may be expandable and/or articulating. In certain embodiments, expansion of an implant after insertion in a human spine may allow articulation of the implant. That is, the implant may not display articulating motion before expansion of the implant in a human spine. In other embodiments, expansion of an implant after insertion in a human spine may allow an increased range of motion (increased articulation) between at least two members of the implant. As used herein, "insertion" of an implant in a human spine may refer to assembly, insertion, positioning, and/or expansion of the implant.

As used herein "facet replacement device" generally refers to a facet replacement device. For simplicity, a portion of a facet replacement device may generally be referred to as a facet replacement device. The facet replacement devices disclosed herein generally allow for rotational and/or translational motion of one or more portions of the facet replacement device including, but not limited to, a plate or elongated member (e.g., rod, bar, rail). Pedicle screws of facet replacement devices disclosed herein may retain multi-axial character after insertion of the facet replacement device. As used herein, "pedicle screw" refers to a portion of a facet replacement device that couples to bone. As used herein, "pedicle screw head" refers to a portion of a facet replacement device that accepts an elongated member. As used herein, "pedicle screw" and "pedicle screw head" may be separate components that may be assembled for use in a facet replacement device.

As used herein, "coupled" includes a direct or indirect coupling unless expressly stated otherwise. For example, a control member may be directly coupled to a driver or indirectly coupled by way of an intermediate shaft. As used herein, "member" includes an individual member or a combination of two or more individual members. A "member" may be straight, curved, flexible, rigid, or a combination thereof. A member may have any of various regular and irregular forms including, but not limited to, a rod, a plate, a disk, a cylinder, a disk, or a bar.

An implant may be constructed of one or more biocompatible metals having a non-porous quality (e.g., titanium) and a smooth finish. In some embodiments, an implant may be constructed of ceramic and/or one or more other suitable biocompatible materials, such as biocompatible polymers. Biocompatible polymers include, but are not limited to, polyetheretherketone resin ("PEEK"). In certain embodiments, an implant may be constructed of a combination of one or more biocompatible metals and one or more ceramic and/or polymeric materials. For example, an implant may be constructed of a combination of biocompatible materials including titanium and PEEK.

FIG. 1 depicts a top view of an embodiment of an expandable, articulating implant. Implant 100 may be substantially cylindrical. FIGS. 2A and 2B depict a side cross-sectional view of implant 100. In some embodiments, implant 100 may include upper body 102 and lower body 104. As used herein, "body" may be of unitary construction or may include two or more members. References to "upper body" and "lower body" are chosen for convenience of description of the figures. In some embodiments, an implant may be inserted in a human spine with the "upper body" superior to the "lower body". In some embodiments, an implant may be inserted in a human spine with the "lower body" superior to the "upper body". In certain embodiments, upper and lower bodies of an implant may be substantially interchangeable. Similarly, "inferior" and "superior" surfaces are also named for convenience of description and may assume "superior" and "inferior" positions, respectively, upon insertion.

Implant 100 may include upper body 102 and lower body 104 in a substantially planar configuration. In some embodiments, superior surface 106 of upper body 102 and inferior surface 108 of lower body 104 may include (e.g., be coupled to) osteoconductive scaffolding 110 (e.g., an osteoconductive mesh structure). Vertebral bone from a patient's spine may grow through osteoconductive scaffolding 110 after insertion of implant 100. In some embodiments, osteoconductive scaffolding 110 may include spines and/or barbs that project into and secure against the bony endplates of the adjacent vertebral bodies upon expansion of the implant, reducing the possibility of subluxation and/or dislocation.

In some embodiments, a shape of recess 116 and insert 118 may be substantially the same as a shape of upper body 102 and/or lower body 104. In certain embodiments, a shape of insert 118 may be different from a shape of upper body 102 and/or lower body 104. For example, a shape of insert 118 may be oval or round, and upper body 102 and/or lower body 104 may be c-shaped. Implant 100 may include expansion member 124. Expansion member 124 may be inserted into opening 126 to elevate insert 118 from recess 116.

In some embodiments, at least a portion of inferior surface 112 of upper body 102 may be concave. In certain embodiments, superior surface 114 of lower body 104 may include recess 116. Recess 116 may include, but is not limited to, a channel or groove. In some embodiments, recess 116 may have a rectangular cross section that extends along lower body 104 in the medial-lateral direction. In certain embodi-

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ments, a shape of recess 116 may be substantially the same as a shape of upper body 102 and/or lower body 104. Insert 118 may be positioned in recess 116 on superior surface 114 of lower body 104. In some embodiments, inferior surface 120 of insert 118 may be substantially flat. In some embodiments, at least a portion of superior surface 122 of insert 118 may be convex. A convex portion of superior surface 122 of insert 118 may articulate with a concave portion of inferior surface 112 of upper body 102, allowing rotation of upper body 102 with respect to lower body 104.

In some embodiments, one or more expansion members may be used to increase a height of an implant and/or increase a separation distance between two or more members of an implant by engaging a portion (e.g., an insert) of the implant. In some embodiments, an expansion member may be a part of the implant. That is, the expansion member may remain coupled to the implant after insertion of the implant in a human spine. For example, expansion members may include, but are not limited to, screws, plates, wedges, and/or a combination of two or more of these elements. In some embodiments, an expansion member may be a tool, instrument, or driver that is used to expand the implant during insertion but does not remain as part of the implant following insertion. In certain embodiments, an expansion member may be used to elevate an insert with respect to the lower body of the implant, thereby increasing a height of the implant and/or increasing a separation distance between two or more members of the implant. In certain embodiments, an expansion member may be used to translate and/or rotate an insert with respect to a body of the implant (e.g., upper body, lower body), thereby increasing a height of the implant and/or increasing a separation distance between two or more members of the implant.

As depicted in FIGS. 2A and 2B, expansion member 124 may be a screw. Expansion member 124 may be inserted through opening 126 and below insert 118 to elevate the insert from lower body 104. In some embodiments, opening 126 may be threaded to accept a threaded expansion member. In certain embodiments, opening 126 may include features (e.g., notches) to allow stepwise insertion of an expansion member. For example, an expansion member may enter opening 126 in a ratcheting motion. In some embodiments, a void space may be created between insert 118 and the bottom of recess 116 adjacent to the expansion member.

FIGS. 3A and 3B depict side cross-sectional views of implant 100 after insertion of expansion member 124 (e.g., after expansion of the implant) such that concave inferior surface 112 of upper body 102 is able to articulate with convex superior surface 122 of insert 118. FIG. 3A depicts implant 100 with upper body 102 rotated with respect to lower body 104 to undergo extension. FIG. 3B depicts implant 100 with upper body 102 rotated with respect to lower body 104 to undergo flexion. In some embodiments, stabilizers 128 may be used to maintain alignment of upper body 102 and lower body 104 during insertion, expansion, and/or articulation of implant 100. Stabilizers 128 may include, but are not limited to, cables, retaining pegs, elastic bands, springs, and/or combinations thereof.

FIGS. 4A and 4B illustrate the expansion of implant 100 in more detail. As shown in FIG. 4A, prior to expansion of implant 100, upper body 102 may rest upon lower body 104. Inferior surface 120 of insert 118 may rest upon the bottom of recess 116, which extends along a portion of lower body 104. In some embodiments, a surface of insert 118 may have angled portion 130. In some embodiments, an angled portion may be a wedge-shaped portion. In certain embodiments, an angled portion may include a curved surface or other surface to facilitate elevation of insert 118 from lower body 104.

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Angled portion 130 may facilitate the lifting of insert 118, allowing expansion member 124 to engage inferior surface 120 of insert 118. Following insertion of expansion member 124 (e.g., following expansion to a desired intervertebral disc height 132), inferior surface 120 of insert 118 may rest upon the expansion member with upper body 102 raised above lower body 104, as depicted in FIG. 4B.

After expansion of implant 100, the implant may be secured in place in a human spine with one or more fasteners (e.g., one or more buttress screws). FIG. 4C illustrates an embodiment utilizing fastener 134. Lower body 104 may include portion 136 with one or more openings 138 defined therethrough. One or more fasteners 134 may be inserted through portion 136 and secured into a vertebral body. In some embodiments, fastener 134 may be a screw (e.g., a buttress screw).

In some embodiments, an implant may be secured in place with a portion of an expansion member. As shown in FIG. 4D, expansion member 140 may include portion 142 with one or more openings 138 defined therethrough. In some embodiments, portion 142 may be a keel. After expansion member 140 is impacted into place, one or more screws 134 may be inserted through portion 142 and secured into a vertebral body. Expansion member 140 and lower body 104 may also include complementary engaging portion 144 to secure expansion member 140 with lower body 104.

FIG. 4E illustrates implant 100 secured between vertebrae of a human spine. One end of portion 142 may be secured onto lower body 104 of implant 100. Portion 142 may be rotated after placement of the device in the intervertebral space. After rotation of portion 142, the portion is secured to the vertebral body above or below implant 100 with one or more fasteners 134 (e.g., screws). FIG. 5 depicts implant 100 following insertion in a spinal column. In some embodiments, implant 100 may be posteriorly inserted and expanded through void space 146 created by removal of a facet joint.

FIG. 6A depicts a top view of an embodiment of a c-shaped expandable implant. Implant 148 may include insert 118. In some embodiments, insert 118 may be substantially the same as a shape of an upper body and/or lower body of implant 148. In certain embodiments, a shape of insert 118 may be different from a shape of upper body 102 and/or lower body 104. For example, a shape of insert 118 may be oval or round, and upper body 102 and/or lower body 104 may be c-shaped. Implant 148 may include two or more expansion members 124. Expansion members 124 may be inserted into openings 126 to elevate insert 118 from recess 116.

FIGS. 6B and 6C illustrate the insertion of expansion members into c-shaped implants. In the embodiment depicted in FIG. 6B, expansion members 124 for implant 148 may be screws. One or more expansion members 124 may be inserted through one or more openings 126. In some embodiments, one or more openings 126 may be threaded. In certain embodiments, as shown in FIG. 6C, implant 150 may include expansion member 152. Expansion member 152 may be an elongated or curved member sized and/or shaped for insertion through opening 126. In some embodiments, expansion member 152 may have an angled or wedge portion. Opening 126 may be non-threaded. Expansion member 152 may be impacted or driven through opening 126 into recess 116 to engage insert 118. Recess 116 may be an arcuate channel or a groove shaped and/or sized to facilitate insertion of expansion member 152 before or after implant 150 has been positioned between vertebrae of a human spine. A shape of expansion member 152 may be complementary to a shape of recess 116. Engaging insert 118 with expansion member 152 may elevate the insert from the lower body of implant 150, increas-

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ing a separation distance between the upper body and the lower body of the implant. In some embodiments, member 154 may be used to retain expansion member 152 in recess 116. Member 154 may be, for example, a cap or set screw that fits through opening 126 into a portion (e.g., a threaded portion) of recess 116.

FIG. 6D depicts an alternative embodiment for posteriorly securing an expansion member in a c-shaped implant. Expansion member 156 may be an expansion plate. Expansion member 156 may be inserted through opening 126 of implant 158. Expansion member 156 may be inserted posteriorly through opening 126 to slidably engage insert 118 in implant 158 in the medial-lateral direction. After expansion, member 160 may be inserted in recess 116. In some embodiments, member 160 may be a retainer plate. In some embodiments, member 160 may substantially fill recess 116. In certain embodiments, member 160 may include a securing device such as, for example, a screw.

FIGS. 7A and 7B depict a cross-sectional view of another embodiment of an expandable, articulating implant. Implant 162 may include upper body 102, lower body 104, insert 164, expansion member 152, and set screw 166 or similar device. Insert 164 may include one or more stops 168. In some embodiments, stop 168 may be a lip or ledge around a circumference of insert 164. In certain embodiments, insert 164 may include angled portion 130. In certain embodiments, expansion member 152 may include angled portion 170. Before insertion of expansion member 152 into recess 116, inferior surface 112 of upper body 102 may rest on superior surface 114 of lower body 104.

With insert 164 positioned in recess 116 of lower body 104, expansion member 152 may be inserted into recess 116. Angled portion 170 of expansion member 152 may engage angled portion 130 of insert 164 and expand implant 162. In some embodiments, set screw 166 may be used to inhibit backout of expansion member 152 after insertion of the expansion member. In certain embodiments, set screw 166 may be used to advance expansion member 152 as well as to inhibit backout of the expansion member.

After expansion of implant 162, a separation distance between inferior surface 112 of upper body 102 and superior surface 114 of lower body 104 may allow articulation of the upper body with convex superior surface 122 of insert 164. FIG. 7A depicts implant 162 after expansion. As depicted in FIG. 7A, upper body 102 is substantially parallel to lower body 104. FIG. 7B depicts implant 162 following articulation of upper body 102 with respect to lower body 104. As depicted in FIG. 7B, stops 168 may limit an angular range of motion of upper body 102 with respect to lower body 104. In some embodiments, a shape and/or thickness of stops 168 may limit a range of rotation of upper body 102 with respect to lower body 104 to less than about 20°. For example, a range of rotation of upper body 102 may be limited to less than about 5°, less than about 10°, or less than about 15°. A range of rotation may depend upon, for example, a shape (e.g., round, ellipsoidal, etc.) of the convex portion of superior surface 122 of insert 164.

FIGS. 8A and 8B depict different cross-sectional views of an embodiment of an expandable, articulating c-shaped implant. As shown in FIG. 8A, implant 172 depicts recess 116 designed to accept arcuate expansion member 152. Implant 172 may have opening 126 on an end (e.g., a short side) of the implant. Expansion member 152 may be impacted into place through opening 126 to elevate insert 118 from lower body 104 after implant 172 has been positioned in an intervertebral space. Recess 116, as well as expansion member 152, may have substantially the same shape (e.g., substantially the

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same curvature) as a portion of the upper body and/or the lower body of implant 172. In some embodiments, a portion of insert 118 may be oval or round (e.g., ellipsoidal, spherical) to allow improved biomechanical motion of the implant. In some embodiments, a bottom of recess 116 may include a feature (e.g., an integral part of the lower body or an element coupled to a portion of the lower body) designed to retain expansion member 152 in position after expansion. For example, as depicted in FIG. 8B, surface 174 of recess 116 may include lip 176 or other feature designed to retain expansion member 152 in the recess. During insertion of implant 172, a surgeon may force expansion member 152 over lip 176 into place. Passage of expansion member 152 over lip 176 and into place may allow the surgeon to feel when expansion member 152 has been properly inserted. In some embodiments, lip 176 may inhibit dislocation of the implant (e.g., backout of expansion member 152).

FIGS. 8C and 8D depict cross-sectional views of an embodiment of an expandable, articulating implant. Implant 178 may include stabilizers 180. Stabilizers 180 may be coupled to lower body 104 and may extend from the lower body into openings 182 in upper body 102. Stabilizers 180 and/or openings 182 may be of various sizes and/or shapes. For example, Stabilizers 180 may be substantially round and openings 182 may be substantially oval, allowing torsional mobility of upper body 102. In some embodiments, stabilizers 180 may be captive. Stabilizers 180 may inhibit dislocation of upper body 102 from lower body 104 during flexion, extension, and/or torsional motion of implant 178. As shown in FIG. 8D, when implant 178 is flexed or extended, stabilizers 180 may inhibit dislocation of upper body 102 from lower body 104.

The disclosed techniques of expanding an implant by insertion of an expansion member may also be employed to expand a PLIF or TLIF cage. FIGS. 9A-9C depict views of an embodiment of an expandable cage. FIG. 9A depicts a top view of cage 184. FIG. 9B depicts a cross-sectional view of cage 184 before expansion. In some embodiments, cage 184 may include cage element 186 and insert 188. Insert 188 may be positioned in cage element 186. In certain embodiments, cage element 186 may include osteoconductive scaffolding 110. For example, cage element 186 may include osteoconductive scaffolding 110 on inferior surface 190. An osteoconductive substance may be placed in osteoconductive scaffolding 110 to promote bone growth into cage 184. In some embodiments, cage element 186 may include opening 192 through superior surface 194.

In some embodiments, insert 188 may include member 196 having inferior surface 198 and superior surface 200. In some embodiments, member 196 may be substantially planar (e.g., a plate). In certain embodiments, osteoconductive scaffolding 202 may be coupled to superior surface 200 of member 196. Member 196 may include angled portion 130. Angled portion 130 may facilitate expansion of cage 184 (e.g., elevation of insert 188) upon insertion of expansion member 204. Expansion member 204 may be inserted into opening 206 of cage element 186 and advanced (e.g., impacted, driven) to engage angled portion 130 of member 196. FIG. 9C depicts a cross-sectional view of expanded cage 184. In some embodiments, lip 176 may inhibit dislocation of expansion member 204 after expansion of cage 184. In certain embodiments, lip 176 and/or one or more other features may secure expansion member 204 in cage element 186 in such a way that a surgeon may sense tactilely when the expansion member is fully inserted in cage 184.

FIGS. 9D and 9E depict cross-sectional views of an embodiment of an expandable cage. FIG. 9D depicts cage 208

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before expansion. Insert 210 of cage 208 may include osteoconductive scaffolding 212 coupled to superior surface 214 of member 216. In some embodiments, osteoconductive scaffolding 212 may have a T-shaped cross-section, such that the osteoconductive scaffolding rests upon superior surface 218 of cage element 220, providing an increased surface area between the osteoconductive scaffolding and the bony endplates within the intervertebral space.

In some embodiments, expandable cages may be expanded in two or more dimensions. FIG. 9F depicts an embodiment of a cage that may be expanded in two dimensions. Cage 222 may include cage element 186 and inserts 188. Cage element 186 may include opening 224 through inferior surface 190 as well as opening 192 through superior surface 194. Two inserts 188 may be positioned in cage element 186. As expansion member 204 is inserted into cage element 186 between inserts 188, the inserts may be forced through openings 192, 224 to engage the bony endplates within the intervertebral space.

FIGS. 10A, 10B, 11A, and 11B depict an embodiment of a lordotic, c-shaped expandable, articulating implant. The lumbar spine is lordotic, thus the anterior disc height is naturally larger than the posterior disc height. Therefore, an expandable implant for the lumbar spine may advantageously expand into a lordotic position. FIG. 10A depicts a posterior view of implant 226. FIG. 10B depicts a top view of implant 226. FIGS. 11A and 11B depict cross-sectional views of implant 226 before and after expansion of the implant, respectively.

Implant 226 may include upper body 228 and lower body 230. Lower body 230 may include two or more members. In some embodiments, members of lower body 230 may be coupled (e.g., hinged). Portions of upper body 228 and lower body 230 may be substantially parallel before expansion of implant 226. In some embodiments, superior surface 106 of upper body 228 and inferior surface 108 of lower body 230 may include osteoconductive scaffolding 110. In certain embodiments, at least a portion of inferior surface 112 of upper body 228 may be substantially concave.

Lower body 230 may include lower portion 232 and upper portion 234. In some embodiments, lower portion 232 and upper portion 234 of lower body 230 may be coupled with hinge 236. Hinge 236 may effectively fix posterior disc height 238 (shown in FIG. 11B). In certain embodiments, inferior surface 240 of upper portion 234 may be substantially flat. In certain embodiments, at least a portion of superior surface 242 of upper portion 234 may be convex. Lower portion 232 and inferior surface 240 of upper portion 234 may be substantially parallel prior to expansion. In some embodiments, lifting mechanism 244 may be located proximate anterior end 246 of lower portion 232. Following insertion of implant 226 in an intervertebral space, lifting mechanism 244 may be engaged to increase a height of anterior end 246 of implant 226. Increasing a height of anterior end 246 of implant 226 may provide a desired anterior disc height 248 and proper lordosis. As depicted in FIGS. 11A and 11B, anterior end 246 of upper portion 234 may include notch 250. Notch 250 may engage lifting mechanism 244 to secure a height of anterior end 246 of implant 226 following expansion.

In some embodiments, at least a portion of inferior surface 112 of upper body 228 may be concave. A concave portion of inferior surface 112 of upper body 228 may articulate with a convex portion of superior surface 242 of upper portion 234. When viewed in the medial or lateral direction, as shown in FIGS. 11A and 11B, upper body 228 may include extension 252 for coupling to elongated member 254. In some embodiments, elongated member 254 may couple upper body 228 to upper portion 234 of lower body 230, thus reducing a possi-

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bility of dislocation. FIG. 11B depicts the posterior placement of hinge 236 and anterior placement of lifting mechanism 244, with elongated member 254 positioned through upper body 228 and upper portion 234 of lower body 230.

A lifting mechanism may also be used to achieve desired lordosis with expandable PLIF and TLIF cages, as shown in FIGS. 12A and 12B. FIGS. 12A and 12B depict side cross-sectional views of cage 256 before and after expansion, respectively. Cage 256 may include upper body 258 and lower body 260. In some embodiments, hinge 262 may posteriorly couple upper body 258 to lower body 260. In certain embodiments, hinge 262 may fix posterior disc height 238 after expansion of cage 256. Superior surface 264 of upper body 258 and inferior surface 266 of lower body 260 may include osteoconductive scaffolding 110. Lifting mechanism 244 may be engaged to expand cage 256. In some embodiments, lifting mechanism 244 may engage notch 250 after expansion, reducing the possibility for dislocation after insertion and expansion of cage 256. A height of lifting mechanism 244 may be chosen to achieve a desired anterior disc height 248 (e.g., to achieve proper lordosis).

FIG. 13A depicts a cross-sectional view of an expandable, articulating lordotic implant. FIG. 13B depicts a cross-sectional view of an embodiment of an expandable lordotic cage. Implant 268 in FIG. 13A and cage 270 in FIG. 13B both include expansion member 272 to achieve proper lordosis. In some embodiments, expansion member 272 is generally wedge-shaped. In certain embodiments, posterior end 274 of expansion member 272 may include angled portion 276. Angled portion 276 may facilitate expansion of implant 268 and cage 270. Protrusion 280 may be located on superior surface 278 of the anterior end of expansion member 272. As shown in FIG. 13A, expansion member 272 may be inserted between upper portion 234 and lower portion 232 of lower body 230. Protrusion 280 may engage notch 250 to secure a height of implant 268 and cage 270 following expansion. Lip 176 or other feature may be located on an anterior end of superior surface 282 of lower portion 232 to reduce the potential of dislocation of expansion member 272.

FIG. 14A depicts a perspective view of an embodiment of an expandable, articulating implant. Implant 284 may be of any size and/or shape known in the art. FIGS. 14B and 14C depict cross-sectional views of implant 284 before and after expansion, respectively. Implant 284 may include upper body 286, lower body 288, and elongated member 290. In some embodiments, lower body 288 may include channel 294. Lower body 288 may include openings 296 on opposing walls for receiving elongated member 290. In certain embodiments, elongated member 290 may traverse a portion (e.g., a length) of implant 284.

In some embodiments, elongated member 290 may include cam portion 298. In certain embodiments, cam portion 298 may include a spiral cam portion. Cam portion 298 may include an arcuate surface that resides within channel 294 of lower body 288. In some embodiments, cam portion 298 may be coupled to elongated member 290. In certain embodiments, cam portion 298 may form an integral part of elongated member 290. In some embodiments, cam portion 298 may wrap partially around elongated member 290 with increasing thickness. In some embodiments, as depicted in FIG. 14B, implant 284 may be in an unexpanded position when cam portion 298 rests at the bottom of channel 294. When elongated member 290 is rotated, cam portion 298 may spin upward to expand implant 284. FIG. 14C depicts a cross-sectional view of expanded implant 284.

Superior surface 300 of upper body 286 may contact the bony surface of a human vertebra after insertion of implant

284 in a human spine. In some embodiments, an inferior surface of upper body **286** may articulate with the arcuate surface of cam portion **298**. In certain embodiments, upper body **286** may move back and forth against the arcuate surface of cam portion **298**. This movement may allow biomechanical motion in a human spine in which implant **284** has been inserted and expanded. In some embodiments, elongated member **290** may be held in place in openings **296** to fix a height of implant **284** after expansion. For example, a ratcheting device or fastener (e.g., a set screw) may be used to fix a position of elongated member **290**. In certain embodiments, superior surface **300** of upper body **286** and/or inferior surface **302** of lower body **288** may be coupled to osteoconductive scaffolding.

FIGS. **15A-15C** depict an embodiment of a c-shaped expandable, articulating implant. FIG. **15A** depicts a top view of implant **304** with insert **306**. In some embodiments, a portion of insert **306** may be substantially round, providing a close approximation to natural biomechanical motion. FIGS. **15B** and **15C** illustrate side cross-sectional views of implant **304** before and after expansion, respectively. Expansion member **308** may be inserted through opening **310**. In some embodiments, opening **310** may be threaded. Advancing element **312** may be inserted in opening **310** following insertion of expansion member **308**. Advancing element **312** may be used to advance expansion member **308** into position below insert **306**. In some embodiments, advancing element **312** may remain in recess **314** to inhibit dislocation of expansion member **308** after expansion of implant **304**. Use of advancing element **312** (e.g., a set screw) to advance expansion member **308** into place may reduce impaction during positioning of the expansion member. Reducing impaction during positioning of expansion member **308** may reduce stress on portions of a patient's body during the insertion procedure. It should be noted that the expansion member/advancing element combination may be employed with any of the disclosed implants, including cages.

FIGS. **16A** and **16B** depict perspective views of an embodiment of a c-shaped expandable, articulating implant before and after expansion, respectively. As shown in FIG. **16A**, implant **316** may include insert **306** and expansion member **308**. Insertion of expansion member **308** is achieved by movement of advancing element **312** through opening **310** in an end of implant **316**. Advancing expansion member **308** with advancing element **312** or other device (e.g., a threaded driver) rather than impacting the expansion member may allow a smaller expansion member to be used. Using a smaller expansion member may require a shorter access to the implant, allowing an implant to be positioned in a final TLIF position and then expanded. For example, a smaller expansion member may require a shorter access to the implant. Raising insert **306** with expansion member **308** may increase a height of implant **316**. Increasing a height of implant **316** may increase a range of articulation of the implant after insertion of the implant in a human spine.

FIG. **17** depicts a perspective view of an embodiment of a portion of an expandable implant. Implant **318** may include expansion member **320**. Expansion member **320** may be advanced with advancing element **322**. As depicted in FIG. **17**, advancing element **322** may be a screw. In some embodiments, advancing element **322** may engage expansion member **320** from a side (e.g., anterior side, posterior side) of implant **318**. In some embodiments, expansion member **320** may include two angled portions. Angled portion **324** may engage a portion of implant **318** (e.g., an insert or a portion of an upper body or a lower body). Advancing element **322** may engage angled portion **326**, thus allowing a component of the

force from the advancing element to increase a height of implant **318**. Accessing expansion member **320** from a longer side (e.g., posterior side) of implant **318** (PLIF approach) may advantageously require a smaller incision and/or cause less tissue damage during insertion of the implant than accessing the expansion member from shorter end of the implant (TLIF approach).

FIG. **18A** depicts an embodiment of a c-shaped expandable, articulating implant designed to accept a spacer between an upper body and a lower body of the implant after expansion. Upper body **328** of implant **330** may include upper portion **332** and lower portion **334**. Upper portion **332** and lower portion **334** may both have substantially the same c-shape. In some embodiments, superior surface **336** of upper portion **332** may contact a bony surface of a vertebral body after insertion of implant **330** in a human spine. At least a portion of inferior surface **338** of upper portion **332** may be concave. At least a portion of superior surface **340** of lower portion **334** may be convex. In some embodiments, inferior surface **338** of upper portion **332** may articulate with superior surface **340** of lower portion **334**.

In some embodiments, inferior surface **342** of lower portion **334** may include angled portion **344**. As depicted in FIG. **18A**, angled portion **344** may be a downward projecting ramp. In certain embodiments, angled portion **346** of expansion member **348** may engage angled portion **344** of lower portion **334** during insertion of the expansion member. After expansion of implant **330**, spacer **350** may be inserted in gap **352** between lower portion **334** of upper body **328** and lower body **354**. In some embodiments, spacer **350** may be a shim. In certain embodiments, a superior surface of lower body **354** may include one or more guides **356**. Guides **356** may include, but are not limited to, protrusions, keyways, rails, grooves, ridges, notches, and/or combinations thereof. Guides **356** may align spacer **350** during insertion of the spacer. In some embodiments, guides **356** may inhibit dislocation of spacer **350** after insertion of the spacer.

FIG. **18B** depicts a top view of an embodiment of spacer **350**. In some embodiments, spacer **350** may have substantially the same shape and/or profile as upper body **328** and/or lower body **354** of implant **330**. In certain embodiments, spacer **350** may be sized such that the spacer is substantially flush with an outside edge of implant **330**. In other embodiments, spacer **350** may protrude from implant **330** (e.g., from a side surface of implant **330**) to facilitate alignment and placement of the spacer in the implant. In some embodiments, spacer **350** may include one or more guides **358**. Guides **358** may include, but are not limited to, grooves, keyways, rails, ridges, protrusions, notches, and/or combinations thereof. Guides **358** on spacer **350** may be complementary to guides on a portion (e.g., upper body, lower body) of an implant.

A height of a spacer may be chosen to provide a desired expanded height of an implant. A height of a spacer may be, for example, 2 mm, 3 mm, 4 mm, or greater. Spacer height may be chosen to achieve a desired height of an implant in a patient's spine. In some embodiments, a spacer with a variable thickness may be used to provide lordosis to an implant. In some embodiments, a spacer may be constructed of biocompatible metal (e.g., titanium). In certain embodiments, a spacer may be constructed of the same material as an implant into which the spacer is to be inserted. In other embodiments, a spacer may include elastomeric material (e.g., silicone) to absorb shock and/or allow additional bending.

FIG. **19A** depicts a perspective view of an embodiment of an expandable implant with an elongated, rotating insert following expansion. Implant **360** may include upper body **362**, lower body **364**, insert **366**, and advancing element **368**.

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Intended placement of implant **360** in the spine may determine a shape of upper body **362** and lower body **364** (e.g., c-shaped, round). Superior surface **370** of lower body **364** may include recess **372**. In some embodiments, recess **372** may be a channel. Insert **366** may be positioned in recess **372**. Insert **366** may remain in recess **372** during insertion and expansion of implant **360**. In some embodiments, inferior surface **374** of insert **366** may be substantially flat. Insert **366** may have an elongated shape with one or more angled portions **376** on superior surface **378** of the insert.

As advancing element **368** is advanced, angled portions **376** may engage extensions **450** of upper body **460**. Advancement of advancing element **394** and rotation of insert **366** may increase a separation distance between upper body **460** and lower body **462**.

FIG. **19B** depicts a cross-sectional view of implant **360** before expansion. During expansion, angled portions **376** on superior surface **378** of insert **366** may engage angled portions **380** extending downward from inferior surface **382** of upper body **362**. As advancing element **368** is advanced into recess **372** in lower body **364**, insert **366** rotates in recess **372** on superior surface **370** of lower body **364**. In some embodiments, insert **366** remains in recess **372** and is not elevated during insertion and expansion of implant **360** in a human spine. As insert **366** is rotated, angled portions **380** of upper body **362** slide up the angled portions **376** of insert **366**, and the upper body is elevated above lower body **364** to increase a height of implant **360** and/or to increase a separation distance between the upper body and the lower body. The elongated nature of insert **366** may result in a more stable expanded implant than an insert of a shorter length. As shown in FIG. **19B**, angled portions **376** and/or angled portions **380** do not include a platform portion. Thus, implant **360** may have a variable expansion height. An expansion height of implant **360** may be secured with advancing element **368** or with a spacer of a desired height.

FIG. **19C** depicts a view of an inferior side of upper body **362** with insert **366** positioned on retaining post **384**. Insert **366** may rotate around retaining post **384**. In certain embodiments, retaining post **384** may limit a height of implant **360** and/or limit a separation distance between upper body **362** and lower body **364**.

FIG. **20A** depicts a perspective view of an embodiment of a c-shaped expandable implant with a cam device. Implant **386** may include upper body **388**, lower body **390**, insert **392**, and advancing element **394**. In some embodiments, advancing element **394** may be an expansion member. In some embodiments, insert **392** may be a cam. As with all of the disclosed embodiments, the placement of implant **386** in the spine will determine a shape of upper body **388** and lower body **390**. In some embodiments, lower body **390** may include recess **398** in superior surface **396**. In certain embodiments, insert **392** may be positioned in recess **398**.

In some embodiments, as shown in FIG. **20B**, insert **392** may have a generally cylindrical central portion **400** with opening **402** defined therethrough. In certain embodiments, insert **392** may include one or more projections **404** extending radially from central portion **400**. In some embodiments, projections **404** may be arms. Insert **392** may be positioned in recess **398** in lower body **390** on a projection (not shown) extending upward from a superior surface of the lower body such that the projection fits in opening **402** of central portion **400** of the insert. The projection may align and/or retain insert **392** in a desired position.

In some embodiments, upper body **388** may include one or more angled portions or cam ramps **406** that extend downward from inferior surface **408** of the upper body. In certain

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embodiments, cam ramps **406** may be positioned such that projections **404** of insert **392** engage the cam ramps as central portion **400** of the insert is rotated around the projection of lower body **390**, increasing a separation distance between upper body **388** and lower body **390**.

In certain embodiments, insert **392** may be rotated via the insertion of advancing element **394** (e.g., a screw), as shown in FIG. **20C**. In some embodiments, stabilizers **412** may extend downward from inferior surface **408** of upper body **388** or upward from a superior surface of lower body **390**. In some embodiments, stabilizers **412** may be, for example, retaining pegs. Stabilizers **412** may be of various shapes or sizes as required to limit separation of upper body **388** and lower body **390** as desired. When upper body **388** is placed over lower body **390**, a large diameter portion (e.g., T-shaped, circular, ellipsoidal, rectangular) of stabilizers **412** may be held in openings **414** in lower body **390**. In certain embodiments, stabilizers **412** may be inserted through inferior surface **416** of lower body **390** and then coupled (e.g., spot welded) to inferior surface **408** (e.g., openings in the inferior surface) of upper body **388**.

As depicted in FIG. **20A**, expansion of implant **386** may increase a separation distance between upper body **388** and lower body **390** to form gap **418** between the upper body and the lower body. The force of advancing element **394** on projections **404** of insert **392** may inhibit the insert from rotating after expansion, thus inhibiting implant **386** from undesirably returning to an unexpanded position. In some embodiments, a spacer may be placed in gap **418** between upper body **388** and lower body **390** to remove the force on advancing element **394** and to ensure that implant **386** remains in an expanded position.

The cam device employed in the embodiment illustrated in FIGS. **20A-C**, as with all the disclosed embodiments of expandable implants, may also be employed in an articulating, or functional, implant. FIG. **20D** depicts a cross-sectional view of an embodiment of an expandable, articulating implant with a cam insert. Insert **392** of implant **422** may be positioned in recess **398** of lower body **390**. Projection **424** (e.g., a post) may extend upward from the superior surface of lower body **390**. Insert **392** may rotate about projection **424**.

Superior surface **426** of upper portion **432** of upper body **388** may contact the bony surface of an adjacent vertebral body after insertion. At least a portion of inferior surface **428** of upper portion **432** may be concave. At least a portion of superior surface **430** of lower portion **434** may be convex. A convex portion of lower portion **434** may be, for example, circular or ellipsoidal in shape. In some embodiments, a circular convex portion may allow biomechanical motion that mimics motion of the human spine. In certain embodiments, an ellipsoidal convex portion may allow translation as well as rotation between, for example, an upper portion and a lower portion of an upper body of an implant. In some embodiments, upper portion **432** and lower portion **434** of upper body **388** may articulate with respect to each other (e.g., may form a functional joint). In certain embodiments, cam ramps **406** may extend downward from inferior surface **436** of lower portion **434** into lower body **390**. Advancing element **394** may push against projections **404** of insert **392**, thereby rotating the insert and causing the projections to engage cam ramps **406**. As projections **404** of insert **392** engage cam ramps **406** and the projections travel up the cam ramps, lower portion **434** and upper portion **432** of upper body **388** may be elevated with respect to lower body **390**. As with the other disclosed embodiments, stabilizers (e.g., captive pegs) may also be employed to inhibit separation of upper body **388** from lower body **390**.

After expansion of implant 422, gap 418 may exist between lower portion 434 of upper body 388 and lower body 390. A spacer (e.g., a shim) may be placed in gap 418 to inhibit implant 422 from returning to an unexpanded position. A spacer may be of various desirable shapes and/or sizes. For example, one side of a spacer may be thicker than another side of the spacer to achieve a desired lordotic angle of the implant. In some embodiments, implant 422 may be inserted in a spine upside down (e.g., upper body 388 oriented inferior to lower body 390) such that an axis of rotation of the implant is located closer to the inferior body after insertion.

FIGS. 21A and 21B depict a perspective view of embodiments of c-shaped expandable, articulating implant 422 depicted in FIG. 20D. FIGS. 21A and 21B depict retention of stabilizers 412 in lower body 390. As shown in FIG. 21A, superior surface 426 of upper portion 432 of upper body 388 and inferior surface 416 of lower body 390 may include teeth 438. Teeth 438 may be of any regular or irregular desired size, shape, and/or spacing to promote retention of implant 422 between vertebrae after insertion. In some embodiments, teeth 438 may be randomly spaced protrusions or barbs. In certain embodiments, upper body 388 and/or lower body 390 may include openings to allow for bone ingrowth into an interior portion of implant 422.

FIG. 21A depicts implant 422 before expansion. In some embodiments, no visible gap may exist between upper body 388 (or upper portion 432) and lower body 390 of implant 422. Thus, a height of implant 422 before expansion may be a minimal height of the implant (e.g., the implant may not be able to articulate before expansion). In some embodiments, a visible gap may exist between upper body 388 (or upper portion 432) and lower body 390 of implant 422. Thus, a separation distance between upper body 388 (or upper portion 432) and lower body 390 of implant 422 may increase during expansion. FIG. 21B depicts fully expanded implant 422 (teeth are not shown for clarity) after advancement of advancing element 394. In some embodiments, advancing element 394 may be a screw (e.g., a set screw). In certain embodiments, advancing element 394 may be positioned on a side (e.g., posterior side) of implant 422 (e.g., for a TLIF application). In certain embodiments, advancing element 394 may be positioned on an end of implant 422 (e.g., for a PLIF application).

Implant 422 may be fully expanded when platform 440 of cam ramps 406 rests on a superior surface of insert 392 (e.g., on a superior surface of projections 404 of the insert). In some embodiments, articulation of upper portion 432 with lower portion 434 may be determined by a degree of convex curvature of inferior surface 428 of upper portion 432 and superior surface 430 of lower portion 434 and/or a relative height (and depth) of complementary convex/concave contacting surfaces of the upper portion and the lower portion. In certain embodiments, stabilizers 442 may be used to align upper portion 432 with lower portion 434 of upper body 388 and/or to retain the upper portion on the lower portion and/or to limit articulation between the upper portion and the lower portion. As depicted in FIG. 21B, stabilizers 442 may be coupled to lower portion 434 of upper body 388 and reside in openings 444 of upper portion 432. In some embodiments, stabilizers 442 may be coupled to upper portion 432.

FIG. 22 depicts an embodiment of a portion of an expandable implant. In the embodiment depicted in FIG. 22, insert 446 includes four cam ramps 448. In other embodiments, an insert may include fewer (e.g., 2 or 3) or more (e.g., 5 to 12 or more) cam ramps. In contrast to the embodiment depicted in FIG. 21, in which the cam ramps are a part of the upper body of the implant and are stationary during expansion of the

implant, cam ramps 448 may rotate as advancing element 394 rotates insert 446. In some embodiments, advancing element 394 may rotate insert 446 until an inferior surface of extensions 450 of upper body 452 rest on a superior surface (e.g., a platform) of cam ramps 448, as depicted in FIG. 22. Thus, the portion of the insert depicted in FIG. 22 may be used without a spacer to achieve a fixed separation distance between an upper body and a lower body of an implant. In some embodiments, a spacer may be used to provide extra stability and/or to reduce force exerted on cam ramps 448 of insert 446. In certain embodiments, a spacer may be used to achieve a separation distance less than the fixed separation distance determined by a cumulative height of cam ramps 448 and extensions 450 of upper body 452.

In some embodiments, one or more cam ramps may be positioned on an inferior surface of an upper body or a superior surface of a lower body of an implant. FIG. 23 depicts an embodiment of an upper body of an implant. Upper body 464 may include cam ramps 406. Advancement of an insert up a curved and/or inclined surface of cam ramps 406 may determine an expansion height of an implant (e.g., a separation distance between an upper body and a lower body of the implant). Stabilizers 466 may allow upper body 464 and a lower body of the implant to remain coupled during and after expansion of the implant. In some embodiments, stabilizers 466 may limit a height of an implant and/or a separation distance between an upper body and a lower body of the implant. Opening 468 of upper body 464 may allow bone graft material to be packed inside the implant.

In some embodiments, a spacer and an insert may include complementary portions that allow a spacer to be coupled to an implant (e.g., reversibly or irreversibly locked into place between an upper body and a lower body of the implant). FIG. 24A depicts a perspective view of an embodiment of spacer 470 coupled to insert 472. FIG. 24B depicts a perspective view of spacer 470. FIG. 24C depicts a perspective view of another spacer 474. Spacers 470, 474 may include protrusion 476. In some embodiments, protrusion 476 of spacers 470, 474 may be press fit or loose fit into a recess of a member of an implant (e.g., an insert). Fitting (e.g., snapping) protrusion 476 into a recess may advantageously provide a tactile indication to a surgeon that spacer 470, 474 is properly placed and secured in an implant.

Spacers may have various features designed to facilitate insertion in an implant, retention in an implant, and/or removal from an implant. For example, spacer 470 shown in FIG. 24B may include recess 478. Recess 478 may allow spacer 470 to be grasped for insertion in an implant and/or for removal from an implant. Spacer 474 shown in FIG. 24C may include lip 480. Lip 480 may facilitate (e.g., guide) insertion of spacer 474 into a gap in an implant. In some embodiments, lip 480 may promote retention of spacer 474 in a gap between an upper body and a lower body of an implant. In some embodiments, a spacer may include a lip around a superior and/or inferior surface of the entire spacer. In certain embodiments, a spacer may include a lip around a superior and/or inferior surface of a portion (e.g., one side) of a spacer. In some embodiments, a lip may be an external lip or an internal lip. In certain embodiments, a lip on an inferior surface of an upper body or a superior surface of a lower body of an implant may be used together with or instead of a lip on a spacer.

FIG. 24D depicts a perspective view of an embodiment of an insert. Insert 472 may include recess 482. Recess 482 may be complementary to a protrusion of a spacer (e.g., protrusion 476 of spacers 470, 474). As depicted in FIG. 24A, protrusion 476 of spacer 470 may fit securely in recess 482 of insert 472, inhibiting backout of the spacer after the spacer has been fully

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inserted. FIG. 24E depicts a perspective cross-sectional view of spacer 474 with lip 480 used to maintain a separation distance between insert 472 and an upper body of an implant.

FIG. 25 depicts a perspective view of an embodiment of an expanded c-shaped implant during insertion of a spacer. Implant 484 may include upper body 486 and lower body 488. Spacer 490 may be inserted in gap 492 between upper body 486 and lower body 488. Opening 494 in upper body 486 may allow bone graft material to be packed inside implant 484.

FIG. 26A depicts a perspective view of an embodiment of an expanded c-shaped articulating implant during insertion of a spacer. Implant 496 may include upper body 498 and lower body 500. Upper body 498 may include upper portion 502 and lower portion 504. Spacer 506 may be inserted in gap 508 between lower body 500 and lower portion 504 of upper body 498. In some embodiments, stabilizers 510 may extend from lower portion 504 through openings 512 in upper portion 502 of upper body 498. A size and/or shape of stabilizers 510 and/or openings 512 may allow a desired amount of articulation between upper portion 502 and lower portion 504 of upper body 498 (e.g., about a convex portion of the superior surface of lower portion).

FIGS. 26B and 26C depict perspective views of implant 496 after spacer 506 has been fully inserted. FIG. 26B depicts implant 496 with upper portion 502 angled relative to lower portion 504 of upper body 498. Superior surface of lower portion 504 may include a convex portion (e.g., substantially ellipsoidal or round) that articulates with a concave portion of inferior surface of upper portion 502 to allow translation, rotation, anterior/posterior bending, and/or lateral bending of upper portion 502 relative to lower portion 504 of upper body 498, subject to size, shape, and orientation of stabilizers 510 and openings 512. FIG. 26C depicts implant 496, with details of stabilizers 510 and openings 512 visible. Stabilizers 510 may be shaped and oriented such that upper portion 502 is angled onto lower portion 504 during assembly of implant 496. Angled portions of stabilizers 510 and openings 512 may allow desired ranges of translational and/or rotational motion of upper portion 502 relative to lower portion 504 while inhibiting separation of the upper portion from the lower portion.

FIG. 27 depicts a perspective view of an embodiment of a c-shaped expandable implant with a spacer. Implant 514 may include spacer 516 between upper body 518 and lower body 520. Spacer 516 may have a larger profile than upper body 518 and lower body 520 of implant 514. Thus, a portion of spacer 516 may protrude from a circumference of implant 514. A spacer with a larger profile than an upper body and/or lower body of an implant may provide torsional support and/or facilitate insertion of the spacer during a surgical procedure.

FIG. 28A depicts a side view of an embodiment of a facet replacement device. Facet replacement device 522 may include upper pedicle screw 524 and lower pedicle screw 526. Rod 528 may be retained in head 530 of upper pedicle screw 524 and head 532 of lower pedicle screw 526. Rod 528 may have washer-type ends 534 that allow for posterior compression, but not extension.

FIG. 28B depicts a side view of an embodiment of a facet replacement device. Facet replacement device 536 may include rod 538. Rod 538 may include a single washer-type end 540 on lower end 542. Head 544 of upper pedicle screw 546 may have threaded locking screw 548, as shown in the cross section in FIG. 28C. Threaded locking screw 548 may hold rod 538 in place and inhibit head 544 of pedicle screw 546 from swiveling while allowing rod 538 to rotate and translate through the head of the pedicle screw.

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FIG. 28D depicts a cross-sectional view of an embodiment of a head-locking insert that may be used in conjunction with a pedicle screw having a locking-type head. In some embodiments, insert 550 may have a similar shape to head 544 of pedicle screw 546. Insert 550 may be of solid construction, with opening 554 defined therethrough. In some embodiments, opening 554 may substantially align with the opening defined through head 544 of pedicle screw 546. As set screw 556 is engaged into head 544 of pedicle screw 546, force is applied to the top of insert 550 and is transferred to the bottom of the head. The force locks head 544 of pedicle screw 546, as with conventional locking pedicle screws; however, the force is not transferred to rod 538. With no force transferred to rod 538, the rod may rotate in and translate through head 544 of the pedicle screw. Alternatively, a shorter insert 550 (e.g., threaded only part way into head 544) may be used to inhibit a transfer of force to the bottom of the head such that the pedicle screw head undergoes multi-axial motion while retaining the rod in the head.

FIG. 29A depicts a side view of an embodiment of a facet replacement device. Facet replacement device 558 may include upper pedicle screw 560 and lower pedicle screw 562. Rod 564 may be retained within heads of pedicle screws 560, 562. Both pedicle screws 560, 562 may be secured with locking screws 566 that inhibit heads 568, 570 of the pedicle screws from swiveling while allowing rotation and/or translation of rod 564. Rod 564 may include rod members 572, 574 coupled via ball joint 576. Ball joint 576 may allow for a generally upward rotation, away from the bony surfaces of the vertebrae to which pedicle screws 560, 562 are secured, but inhibit a generally downward rotation, which would bring the ball joint in contact with the vertebrae to which the pedicle screws are secured.

FIGS. 29B and 29C depict side and top views, respectively, of an embodiment of a facet replacement device. Facet replacement device 578 may include upper pedicle screw 580 and lower pedicle screw 582 having post-type heads 584, 586. Rather than the previously described rod, retaining plate 588 may be included. Elongated openings 590 may be defined through retaining plate 588 positioned on the post-type heads 584, 586 of pedicle screws 580, 582. Post-type heads 584, 586 may be allowed to move in elongated openings 590, providing a limited range of motion. Employing cushioning pads 592 made of rubber or other elastomeric biocompatible material may dampen movement of retaining plate 588. Post-type heads 584, 586 may also include threaded or lockable caps 594 to inhibit dislocation of retaining plate 588 from the post-type heads.

FIG. 29D illustrates a pedicle screw having post-type head 584 used in conjunction with a pedicle screw having a locking or non-locking type head 598. Retaining plate 588 may be formed with rod 600 on one end, which may be slidably positioned through pedicle screw head 598.

As shown in FIGS. 29E and 29F, post-type heads 604 of pedicle screws 606 used in conjunction with retaining plate 588 may also exhibit multi-axial motion. Post-type head 604 may be coupled to pedicle screw 606 with ball joint 608. FIG. 29F shows spacer 610 disposed below retaining plate 588. Spacer 610 may allow for rotation of ball joint 608.

FIG. 30 depicts facet replacement device 558 of FIG. 29A in place on the spinal column. Note that implant 612 has been posteriorly placed within the intervertebral space through the void created by the surgical removal of the natural facet joint. In addition, ball joint 576 may rotate in the posterior (upward) direction during posterior compression to inhibit impact upon the bony surfaces of the spine.

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FIG. 31A depicts a perspective view of a portion of an embodiment of a facet replacement device. Facet replacement device 614 may include pedicle screw head 616, pedicle screw 618, lower saddle 620, upper saddle 622, and set screw 624. Rod 626 may be positioned between lower saddle 620 and upper saddle 622. Set screw 624 may secure lower saddle 620, upper saddle 622, and rod 626 in pedicle screw head 616 of facet replacement device 614. In some embodiments, a diameter of a portion of rod 626 held between lower saddle 620 and upper saddle 622 may substantially the same diameter as other portions of the rod. For example, rod 626 may be of substantially constant diameter. In certain embodiments, a portion of rod 626 held between lower saddle 620 and upper saddle 622 may be reduced in diameter relative to other portions of the rod. FIG. 31B depicts a cross-sectional view of reduced diameter portion 628 of rod 626 positioned in pedicle screw head 616 of facet replacement device 614.

FIGS. 31B and 31C depict perspective cross-sectional views of facet replacement device 614. As shown in FIGS. 31B and 31C, rod 626 may have reduced diameter portion 628 positioned between lower saddle 620 and upper saddle 622. Reduced diameter portion 628 of rod 626 may be secured in opening 630 formed by lower saddle 620 and upper saddle 622. Rod 626 may be retained in a desired position between lower saddle 620 and upper saddle 622 by O-rings 632. As depicted in FIG. 31B, O-rings 632 may reside in grooves 634 in rod 626. A position of grooves 634 in rod 626 may be chosen to allow translation of the rod through opening 630 with O-rings 632 positioned in grooves 634. O-rings 632 may be made of any biocompatible elastomeric material including, but not limited to, silicone. Grooves 634 may have any desirable cross-sectional shape including, but not limited to, rectangular, square, arcuate, or v-shaped.

As depicted in FIGS. 31B and 31C, opening 630 formed by lower saddle 620 and upper saddle 622 may have a diameter that exceeds a diameter of the portion of rod 626 (e.g., reduced diameter portion 628) held between the upper saddle and the lower saddle. With a diameter of opening 630 that exceeds a diameter of rod 626 held in the opening, the rod may be able to move relative to pedicle screw head 616 of facet replacement device 614. In some embodiments, rod 626 may be able to translate and/or rotate with respect to pedicle screw head 616. In certain embodiments, rod 626 may be able to rotate about axes parallel and/or perpendicular to a longitudinal axis of the rod. As depicted in FIG. 31B, rotation of rod 626 about an axis perpendicular to a longitudinal axis of the rod may result in tilting or angulation of the rod relative to pedicle screw head 616. In some embodiments, movement of rod 626 in opening 630 may be cushioned by O-rings 632.

FIG. 32 depicts a perspective view of a portion of an embodiment of a facet replacement device that may be used in a 2-level spinal stabilization procedure. Facet replacement device 636 may include pedicle screw head 616, pedicle screw 618, lower saddle (not shown), upper saddle 622, and set screw 624. Retainer 638 may hold rod 626 in opening 630 formed by the lower saddle and upper saddle 622. Opening 630 may be sized as noted with respect to facet replacement device 614 (FIG. 31) to allow rotational and/or translational motion of rod 626 in the opening. O-ring 632 may cushion movement of rod 626 in opening 630. Rod 626 used with facet replacement device 636 may have a substantially uniform diameter. That is, facet replacement device 636 does not require a portion of rod 626 to have a reduced diameter. Therefore, pedicle screw head 616 may be placed at any desired position along a length of rod 626. Adjustable positioning of pedicle screw head 616 along a length of a rod of

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uniform diameter may allow the use of the facet replacement device 636 in a two-level or multi-level spinal stabilization procedure.

Retainer 638 may be a c-shaped element with opening 640. A diameter of rod 626 may exceed a length of opening 640. Thus, after retainer 638 has been snapped onto rod 626, the retainer may remain securely on the rod. Rotational motion of rod 626 in opening 630 may be limited by relative diameters of rod 626 and opening 630. Translational motion of rod 626 through opening 630 may be limited by placement of retainers 638 on either side of pedicle screw head 616.

FIG. 33A depicts a perspective view of an embodiment of a portion of a facet replacement device including a plate rather than a rod. Facet replacement device 642 may include pedicle screw 618, pedicle screw head 644, and fastener 646. In some embodiments, fastener 646 may be, for example, a screw. Plate 648 may be coupled between pedicle screw head 644 and fastener 646. In some embodiments, plate 648 may have a T-shaped cross section. In certain embodiments, a T-shaped cross section may provide a lower profile than a rod, advantageously requiring less space at a surgical site. Size, thickness, and dimensions of a T-shaped cross section may vary as needed for strength, stability, and surgical access. For example, stem portion 650 of plate 648 may be of various heights.

FIG. 33B depicts a cross-sectional view of facet replacement device 642 including plate 648. Plate 648 may be coupled to pedicle screw head 644 between lip 652 of the pedicle screw head and lip 654 of fastener 646. In some embodiments, fastener 646 may have a threaded portion that engages a threaded portion inside pedicle screw head 644 (threaded portions not shown). In some embodiments, spacer 656 may be positioned between pedicle screw head 644 and fastener 646. In certain embodiments, spacer 656 may fit inside opening 658 in plate 648 (e.g., between the plate and fastener 646). A diameter of opening 658 may be sized such that plate 648 can rotate and/or translate relative to pedicle screw head 644. In some embodiments, spacer 656 may be a bushing or an O-ring. Spacer 656 may be made of elastomeric materials such as, but not limited to, silicone. Spacer 656 may cushion and/or dampen movement of plate 648 relative to pedicle screw head 644 and/or fastener 646 to allow smoother biomechanical motion after insertion in a human spine.

FIG. 34A depicts a perspective view of an embodiment of a portion of a facet replacement device with a pedicle screw that retains mobility after a rod is secured. Facet replacement device 660 may include pedicle screw head 662, pedicle screw 664, upper saddle 666, and set screw 624. Ball joint 668 of pedicle screw 664 may rest in base 670 of pedicle screw head 662. A portion of rod 626 may contact ball joint 668 of pedicle screw 664. In some embodiments, rod 626 may have a reduced diameter portion that resides in pedicle screw head 662 and contacts ball joint 668 of pedicle screw 664. In other embodiments, rod 626 may have a substantially constant diameter.

In some embodiments, an outside portion of upper saddle 666 and an inside portion of pedicle screw head 662 may be complementarily threaded (not shown), such that the upper saddle may be threaded into the head. In certain embodiments, pedicle screw head 662 may be threaded such that upper saddle 666 may be threaded a limited distance into the head (e.g., upper saddle 666 does not contact base 670). Set screw 624 may inhibit backout of upper saddle 666 from pedicle screw head 662. A length of threading in pedicle screw head 662 may be chosen such that upper saddle 666 may be fully secured in the head without tightening rod 626 onto ball joint 668. Thus, with rod 626 fully secured in head

662, the rod and pedicle screw 664 both retain rotational mobility. In some embodiments, O-rings 632 may be positioned on rod 626 on both sides of upper saddle 666. Translation of rod 626 in pedicle screw head 662 may be limited by the placement of O-rings 632 on the rod and/or by a retainer.

FIGS. 34B and 34C depict cross-sectional views of facet replacement device 660. As shown in FIGS. 34B and 34C, reduced diameter portion 628 of rod 626 may be held loosely between upper saddle 666 and ball joint 668 of pedicle screw 664. With threading (not shown) inside pedicle screw head 662 extending only partially down toward the base of the pedicle screw head, upper saddle 666 may secure rod 626 in the pedicle screw head without causing the rod to bear down on ball joint 668 of pedicle screw 664. With rod 626 and ball joint 668 able to move freely, the rod may retain rotational (and/or translational) mobility after insertion of facet replacement device 660 in a human spine.

In some embodiments, instruments may be used to install elements of an implant in a spine. Instruments may also be used to position (e.g., rotate, translate, expand) elements of an implant in vivo. In certain embodiments, a single instrument may be used to perform multiple steps of a spinal procedure. For example, an instrument may be used to position an implant in an intervertebral space and to actuate an expansion member to expand the implant in the intervertebral space.

FIG. 35 depicts instrument 700 for use in installing and expanding an implant. Instrument 700 may have proximal end 702 and distal end 704. Instrument 700 may include outer shaft 706, driver 708, holding device 710, and handle 712. As used herein, "shaft" includes elongated members having various regular and irregular cross-sections, including, but not limited to, round, square, rectangular, hexagonal, or irregular. A shaft may be solid or hollow.

Instrument 700 may include thumbwheel 714. Thumbwheel 714 may be coupled to driver 708. Thumbwheel 714 may act as a control member for driver 708. As used herein, "control member" includes any element that is operable by a user to control position, orientation, or motion of another element. Other examples of control members include, but are not limited to, a knob, a lever, or a button. In some embodiments, a control member may be operated using a tool.

In one embodiment, thumbwheel 714 may be fixedly coupled to driver 708 such that driver 708 rotates as thumbwheel 714 is rotated. In another embodiment, thumbwheel 714 may be threadably coupled to driver 708 such that driver 708 translates along its axis when thumbwheel 714 is rotated.

FIG. 36 depicts a detail view of distal end 704 of instrument 700. Holding device 710 may hold an implant during insertion of the implant between two vertebrae. As used herein, "holding device" includes any element or combination of elements that may be used to hold, support, or grip another element, such as an implant, spacer, or insert. Examples of holding devices include, but are not limited to, a clamp, a clip, or a threaded rod. In some embodiments, a holding device may include one or more opposing holding elements. For example, as shown in FIG. 36, holding device 710 may include holding arms 716. Holding arms 716 may be hinged to base 718. Base 718 may be coupled to outer shaft 706. Holding arms 716 may be coupled to spring clip 720. Spring clip 720 may maintain holding arms 716 in a closed position (as shown in FIG. 36) unless at least a predetermined amount of separation force is applied to instrument 700 and an implant.

Lobes 722 on holding arms 716 may engage complementary surfaces (e.g., notches, grooves) on an implant or spacer. Engagement between lobes and complementary surfaces on an implant or spacer may promote engagement between an

instrument and an implant or a spacer. Holding arms may include other engaging elements, such as tabs, grooves, or pins. In certain embodiments, the inner surfaces of holding arms on a holding device may be flat. The inner surfaces of holding arms may be textured or smooth.

In some embodiments, spring clip 720 may be at least partially made of a shape memory alloy. Spring clip 720 may be actuated by allowing the spring clip to reach a predetermined temperature. When spring clip 720 is actuated, the spring clip may urge holding arms 716 outwardly from a closed position. In one embodiment, spring clip 720 may be actuated by body heat. In another embodiment, spring clip 720 may be actuated by electrical current carried by insulated conductors in or on the instrument.

Base 718 of holding device 710 may allow for passage of driver 708. Driver 708 may include inner shaft 724 and driver head 726. Inner shaft 724 may be coupled with thumbwheel 714 (shown in FIG. 35). Driver head 726 may have any of various forms suitable for actuating (e.g., rotating, advancing) a portion of an expansion member or insert. In one embodiment, a driver head may include external threads that can engage internal threads on a portion of an implant. Other examples of driver head types include, but are not limited to, slotted, Phillips, square, hexagonal, or hexalobular. In some embodiments, the driver head may engage a set screw in the implant.

FIG. 37 depicts a detail view of proximal end 702 of instrument 700. Handle 712 may include grip portion 728 and end portion 730. End portion 730 may include a surface suitable for receiving impact by another instrument. Slot 732 may be provided between grip portion 728 and end portion 730. Thumbwheel 714 may partially reside in slot 732. In certain embodiments, surfaces of thumbwheel 714 may have knurls, ribs, or similar characteristics to facilitate rotation of the thumbwheel.

Handle 712 may protect portions of the instrument from damage during use. For example, handle 712 may protect against damage to threads on inner shaft 724 when another instrument is used to strike instrument 700. In one embodiment, a transverse cross section of handle 712 at slot 732 may be generally rectangular, as shown in FIG. 37. A rectangular cross section at slot 732 may allow a user to access a sufficient portion of thumbwheel 714 to turn the thumbwheel, but still protect thumbwheel 714 and inner shaft 724 (shown in FIG. 35) from damage. A transverse cross section of handle at slot 732 may be shapes other than rectangular, such as square, oval, hexagonal, or irregular.

Although the protecting portions of instrument 700 shown in FIG. 37 are an integral part of handle 712, a protector in other embodiments may be a separate component from the handle. In certain embodiments, a protector may be removable from an instrument so that a user may access a driver and/or control member.

FIG. 38 depicts implant 484 held by instrument 700 after driver 708 has been operated to expand the implant. When implant 484 is initially coupled to holding device 710, lobes 722 of holding arms 716 may engage in holding recesses 733 on either side of lower body 488. Engagement of lobes 722 in holding recesses 733 may help maintain a position of the implant during insertion and/or expansion of the implant. Engagement of lobes 722 within holding recesses 733 may place implant 484 in a desired alignment for insertion between the vertebrae and engagement with an expansion tool. The location of holding recesses 733 may be selected according to the approach to be used (e.g., TLIF, PLIF) and the location of an expansion member of the implant. For

example, for a TLIF implant, holding recesses may, in some embodiments, be located near both longitudinal ends of the implant.

In some embodiments, driver head **726** may engage an insert (e.g., insert **472** depicted in FIG. **24D**) of an implant. In other embodiments, driver head **726** may engage a set screw (e.g., advancing element **394** depicted in FIG. **21B**) of an implant, which may in turn actuate (e.g., translate or rotate) an insert. Actuation of driver **708** may expand implant **484** to the expanded position shown in FIG. **38**. After implant **484** has been expanded, instrument **700** may be pulled away from the surgical site with enough force to overcome the closing force of holding device **710**, thereby spreading holding arms **716** apart to allow separation of instrument **700** from implant **484** and removal of the instrument from the site. In another embodiment, a release mechanism can be used to spread holding arms **716** apart.

In some embodiments, an inserter for a spacer may be used in combination with an implant holder and/or a driver for an expansion member. In some embodiments, an inserter may include a guide that engages a portion of an implant holder. The guide may be used to position the spacer near a desired location near the implant and/or to insert the spacer in the implant. Examples of guides include, but are not limited to, a fork, a hook, a ring, a spring clip, a tab, a rail, or a groove. In some embodiments, an inserter may be used to guide a spacer to a location near an implant, such as at a gap between an upper body and a lower body of the implant. In certain embodiments, an inserter may be advanced on a shaft to fully insert a spacer between upper and lower bodies of an implant.

FIG. **39** depicts instrument **736** including inserter **738** for holding spacer **470**. Inserter **738** may include inserter shaft **740**, inserter handle portion **742**, spacer holding device **744**, and guide fork **746**. Guide fork **746** may engage outer shaft **706**. Inserter handle portion **742** may include bend **748**. Bend **748** may allow a proximal portion of inserter handle portion **742** to be positioned close to handle **712** so inserter handle portion **742** may be manipulated in a relatively small incision.

In the embodiment shown in FIG. **39**, inserter **738** may be easily separated from outer shaft **706**. Thus, the surgeon could first insert and expand the implant, then introduce inserter **738** into the incision. In other embodiments, an inserter may be permanently coupled to the rest of an instrument.

FIG. **40** depicts a detail view of implant **484** held by instrument **736**, as seen from the upper side of the implant. FIG. **41** depicts a detail view of implant **484** held by instrument **736**, as seen from the lower side of the implant. In FIGS. **40** and **41**, spacer **470** is partially inserted between upper body **486** and lower body **488** of implant **484**.

In the embodiment shown in FIG. **40**, spacer holding device **744** includes holding arms **716** that are fixed with respect to base **718**. Each of holding arms **716** may include ball detent mechanism **750**. FIG. **42** depicts a detail view of ball detent mechanisms **750**. Detent springs **752** may provide a desired amount of clamping force on spacer **470**. In other embodiments, a spacer holding device may include hinged arms that are similar to those of holding device **710** shown in FIG. **36**.

Referring again to FIG. **36**, it is noted that spring clip **720** may serve as a biasing element to maintain a holding force on the implant. As used herein, a "biasing element" includes any element that biases a device toward one position. A biasing element may be a separate element of a holding device or integral to another element of the device (e.g., a holding arm). Biasing elements include, but are not limited,

resilient members such as metal springs or elastomeric bands. Additional embodiments of holding devices with biasing elements are described below.

FIG. **43** depicts holding device **710** including holding arms **716** hinged to base **718** and connected by coil spring **754**. In one embodiment, coil spring **754** is spot welded to the holding arms. FIG. **44** depicts an alternate embodiment of holding device **710** that includes spring arms **755**. In certain embodiments, spring arms **755** may be made of 302, 314, or 316 stainless steel.

FIG. **45** depicts a holding device **710** having holding arms **716** made of a shape memory alloy. Holding arms **716** may be actuated by allowing the holding arms to reach a predetermined temperature. When holding arms **716** are actuated, the holding arms **716** may move outwardly from a closed position. Holding arms **716** may be actuated using body heat, insulated electrical current, or another heat source.

FIG. **46** depicts an alternate embodiment of a holding device. Holding device **710** may engage a top surface of implant **484**. Notches **756** in implant **484** may allow the outer surfaces of holding arms **716** to be flush with the outer surfaces of upper body **486** and lower body **488**, facilitating insertion of implant **484** between the vertebrae. In another embodiment, a holding device may engage top and bottom surfaces of a spacer for an expandable implant.

FIGS. **47A-47D** depict a top view of an expandable implant during expansion of the implant and insertion of a spacer between upper and lower bodies of the implant. FIG. **47A** depicts implant **484** on instrument **700** before expansion of implant **484**. Driver head **726** of driver **708** may be advanced into a tapped through hole in lower body **488** of implant **484** until the tip of driver head **726** engages insert **472**. Advancement of driver head **726** may rotate insert **472** to expand implant **484** between the vertebrae (see FIG. **47B**). Holding device **710** may exert sufficient force on implant **484** to maintain the implant in a fixed position during actuation of driver **708**.

Guide fork **746** of inserter **738** (shown in FIG. **39**) may be placed on outer shaft **706**. Inserter **738** may be advanced on outer shaft **706** to move spacer **470** into position between the upper body and the lower body of implant **484** (FIG. **47C**). Inserter **738** may be advanced until spacer **470** is fully installed between the upper and lower bodies of implant **484** (FIG. **47D**). Once spacer **470** is fully installed, instrument **700** and inserter **738** may be withdrawn from the surgical site, either together or one at a time.

In certain embodiments, an instrument may include a movable element for maintaining a holding device in a closed position. FIG. **48** depicts a distal end of instrument **758** including slide **760**. Slide **760** may include projections **762**. Projections **762** may define notches **764** at a distal end of slide **760**. Bottom surfaces **766** of notches **764** may act as stops against axial motion of holding device **710**. Spring clip **720** may bias holding arms outwardly from the closed position shown in FIG. **48**. When projections **762** are adjacent to holding arms **716** of holding device **710** (as shown in FIG. **48**, for example), the projections may inhibit outward rotation of the holding arms, thereby keeping the holding device in a closed position. When slide **760** is retracted from holding arms **716** (e.g., by moving the slide proximally with respect to the holding device), the holding arms may move apart under the force of spring clip **720** to allow release of an implant from the instrument.

Other arrangements may be used to maintain a holding device in a closed position. For example, a slide may include a cylindrical sleeve that passes over the outer sides of a

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holding device. The inner wall of the sleeve may inhibit the holding arms from moving out of a closed position.

In some embodiments, a holding device for an implant or spacer may be coupled to a control member, such as a thumbwheel or lever. The control member may be operated to selectively hold and release the implant or spacer. FIG. 49 depicts a perspective view of inserter 768 including holding device 710. Holding arms 716 of holding device 710 may be coupled to coil spring 754 in a similar manner as described above relative to FIG. 43. Coil spring 754 may bias holding arms 716 into a closed position on a spacer. Cable 770 may extend between thumbwheel 714 and holding arms 716 through hollow shaft 772. Thumbwheel 714 may be operated to draw cable 770 away from distal end 704 of instrument 768. Cable 770 may act against the force of coil spring 754 to open holding arms 716, thereby allowing the spacer to be released from the holding device. Inserter 768 may include guide fork 746. Guide fork 746 may slidably engage a portion of an implant holder (e.g., the outer shaft shown in FIG. 35) to facilitate positioning of the spacer prior to release of the spacer. In another embodiment, a control member may be connected to a locking slide to selectively lock and release a holding device.

FIGS. 50A and 50B depict instrument 774 including a pair of rods for inserting implant 776 having spacer 778. Bottom rod 780 and top rod 782 of instrument 774 may be commonly supported on base member 784. Bottom rod 780 may include threaded portion 781. Threaded portion 781 may engage in a tapped hole in lower body 786 of implant 776. In one embodiment, tab 787 on spacer 778 may engage a channel or groove in top rod 782 to help guide and/or align spacer 778. Top rod 782 may be used to guide spacer 778 to a gap between upper body 788 and lower body 786, as shown in FIG. 50A. Once spacer 778 is in position for insertion between upper body 788 and lower body 786 of implant 776, top rod 782 may be repositioned in base member 784 such that a distal end of top rod 782 is behind spacer 778, as shown in FIG. 50B. Top rod 782 can be used to advance spacer 778 between upper body 788 and lower body 786. In certain embodiments, top rod 782 may be used to impact spacer 778 between upper body 788 and lower body 786.

FIG. 51 depicts alternative embodiment of an instrument 790 including driver 708 with driver head 726. Driver head 726 may include threaded portion 792. In one embodiment, threaded portion 792 may be threaded into a tapped through opening in an upper or lower body of an implant. As threaded portion 792 of driver head 726 is advanced through the opening, a distal tip of driver head 726 may actuate (e.g., translate, rotate) an insert. Instrument 790 may include outer shaft 706 and holding device 710. In certain embodiments, holding device 710 of instrument 790 may be shaped to match a contour of an implant or a spacer. In one embodiment, holding device 710 may have an arcuate shape. Driver head 726 may be actuated by thumbwheel 714. Instrument 790 may include removable cover 794. Removable cover 794 may protect thumbwheel 714 from damage during use.

FIGS. 52A and 52B depict an alternate embodiment of an instrument for placing and expanding an implant and inserting a spacer. Instrument 796 may include base member 798. Base member 798 may carry holder rod 800, driver rod 802, and inserter rod 804. Holder rod 800 may threadably engage a tapped hole in lower body 786 to support implant 806. Driver rod 802 may threadably engage through hole 808 in lower body 786. Driver rod 802 may be advanced to actuate insert 810 to increase a separation distance between lower body 786 and upper body 788, thereby expanding implant 806. Spacer 812 may be threadably coupled to inserter rod

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804. Inserter rod 804 may be guided on base member 798 to advance spacer 812 between lower body 786 and upper body 788. Holder rod 800, driver rod 802, and inserter rod 804 may be rotated to disengage the rods from implant 806. The rods may be removable from base member 798. In some embodiments, inserter rod 804 may be loaded into an open channel in base member 798.

It will be understood that any or all of the threaded tips on rods 800, 802, and 804 may be replaced by other holding devices including, but not limited to, the holding devices shown in FIGS. 36-44. It will be further understood that in other embodiments, an instrument may omit one or more of the implant holder, the expansion driver, or the spacer inserter. For example, an instrument may include only an implant holder and an expansion driver, or only an implant holder and a spacer inserter.

In an embodiment, a driver for components of a spinal system may include a feature for locking with an element of a spinal system. FIG. 53 depicts a schematic view of a proximal end of head 816 on fastener 818 for a spinal system. Head 816 may include side hole 820. A fastener for a spinal system may include, but is not limited to, a set screw, a pedicle screw, or a threaded top for a polyaxial screw. FIG. 54 depicts a schematic view of a distal end of driver 822. Driver 822 may include sleeve 824 having socket 826. Driver 822 may include lock element 828. Lock element 828 may retractably extend into socket 826. Button 830 on sleeve may be manually operated to retract lock element 828 from socket 826. When sleeve 824 of driver 822 is placed on head 816 of fastener 818, lock element 828 of driver 822 may engage in side hole 820.

Engagement of lock element 828 in side hole 820 may inhibit axial separation of driver 822 from head 816 of fastener 818. A locking element may reduce a risk of a fastener disengaging from a tool during use. In certain embodiments, lock element 828 may be used to capture a break-off head of a top for a polyaxial screw. In certain embodiments, driver 822 may be coupled with a detachable handle. In some embodiments, driver 822 may be used with a power tool (e.g., a drill).

In an embodiment, an implant (e.g., for an expanse cage, dynamic cage) may be placed in a human spine using a posterior approach to a diseased lumbar disc. In some embodiments, the surgeon may use the same approach as is typically used in a microdiscectomy, TLIF, or minimally invasive posterior exposure. Such procedures involve removing some of the lamina and the medial facet joint. More bone, including the spinous process and the entire facet may be removed if indicated.

The vital structures involved with the posterior approach are the nerve roots. The exiting root is the root that leaves the spinal canal just cephalad (above) the disc, and the traversing root leaves the spinal canal just caudad (below) the disc. The thecal sac houses the other nerve roots that exit lower. The triangle between the exiting nerve root and the traversing nerve root (Pambin's or Cambin's triangle) is the extent of the access to the disc. The triangle may be enlarged by retracting the traversing nerve root medially. If retraction is done too vigorously, however, retraction injuries may occur and serious complications such as nerve root sleeve tear may result, causing spinal fluid leakage, nerve root injury, avulsion and even spinal cord injury.

After the lamina has been removed and the traversing root retracted medially, the posterior annulus may be exposed. While the root is retracted gently, the surgeon may create an annulotomy. Pituitary forceps may be used to remove disc material. Successively larger forceps may be used until an adequate amount of disc is removed. Care should be taken not

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to penetrate the anterior annulus and enter the retroperitoneal space. After adequate disc material has been removed, the end plates may be prepared using osteotomes to remove posterior osteophytes and cutting curettes to decorticate the end plates. The object of end plate preparation is to remove the cartilaginous tissue and score the cortical bone without completely removing the cortical strength.

Once the end plates have been prepared, a trial may be placed in the disc space. The trial should be snug without significantly distracting the end plates. An unexpanded implant of approximately the same size as the trial may then be inserted into the disc space. Once positioned anterior to the nerve roots, the implant may be expanded. In some embodiments, a spacer may be introduced following expansion of the implant. The spacer may include a protrusion, groove, or similar element that snaps or locks into place to provide a tactile sensation as the spacer reaches a fully inserted position. A tactile sensation may provide the surgeon with positive feedback that the spacer is in place. In certain embodiments, the implant may be further rotated within the space after the spacer is introduced, according to the preference of the surgeon.

An expandable implant (e.g., an expanse cage or dynamic device) may allow a larger device to be placed into the disc from a posterior approach without over distracting the nerve roots or the ligaments. In some embodiments, the implant may be expanded without any over distraction. This advantage may allow the surgeon to tension the annulus, avoid resection of the anterior longitudinal ligament, and decompress the nerve roots without requiring over distraction and the attendant possibility of injury to the nerves and ligaments. For reasons outlined above, many patients are not suitable candidates for an anterior approach. In one embodiment, an implant of less than about 12 mm in width is placed posteriorly without over distraction. In another embodiment, an implant of less than about 10 mm in width is placed posteriorly without overdistracting.

In an embodiment, an expandable implant may expand throughout its entire width. In some embodiments, an expandable implant may be used for posterior disc height restoration without increasing lordosis. In other embodiments, an expandable implant may be used for posterior disc height restoration with increasing lordosis. In certain embodiments, an implant may be placed using a TLIF approach. Although some of the description herein relates to a PLIF or TLIF approach, it will be understood that implants as described herein may be placed using an anterior approach.

In this patent, certain U.S. patents, U.S. patent applications, and other materials (e.g., articles) have been incorporated by reference. The text of such U.S. patents, U.S. patent applications, and other materials is, however, only incorporated by reference to the extent that no conflict exists between such text and the other statements and drawings set forth herein. In the event of such conflict, then any such conflicting text in such incorporated by reference U.S. patents, U.S. patent applications, and other materials is specifically not incorporated by reference in this patent.

Further modifications and alternative embodiments of various aspects of the invention will be apparent to those skilled in the art in view of this description. Accordingly, this description is to be construed as illustrative only and is for the purpose of teaching those skilled in the art the general manner of carrying out the invention. It is to be understood that the forms of the invention shown and described herein are to be taken as examples of embodiments. Elements and materials may be substituted for those illustrated and described herein, parts and processes may be reversed, and certain features of

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the invention may be utilized independently, all as would be apparent to one skilled in the art after having the benefit of this description of the invention. Changes may be made in the elements described herein without departing from the spirit and scope of the invention as described in the following claims.

What is claimed is:

1. An intervertebral implant system for a human spine, comprising:

a first body comprising:

a first external surface configured to be disposed adjacent a first vertebra during use, and

a first internal surface opposite the first external surface;

a second body comprising:

a second external surface configured to be disposed adjacent a second vertebra during use, and

a second internal surface opposite the second external surface;

an elongated insertion instrument releasably couplable to the first or second body during use; and

a spacer linearly advanced between the first internal surface of the first body and the second internal surface of the second body during use, wherein the elongated insertion instrument guides at least a portion of the linear advancement of the spacer after the first and second bodies have been disposed substantially between the first and second vertebrae from a position remote to the first and second bodies during use, and wherein the linear advancement of the spacer results in expansion of the intervertebral implant such that the first external surface and the second external surface move away from one another to expand a height of the implant.

2. The system of claim 1, wherein the spacer is disposed in a gap between the first and second internal surfaces of the first and second bodies during use.

3. The system of claim 1, wherein a leading end of the spacer comprises a wedge shaped nose.

4. The system of claim 3, wherein at least one of the first or second bodies comprise a ramped surface engaged by the wedge shaped nose as the spacer is linearly advanced during use.

5. The system of claim 1, further comprising an other elongated insertion instrument, wherein the elongated insertion instruments are located on opposite sides of the spacer during use.

6. The system of claim 5, wherein the elongated insertion instruments each comprise longitudinal axis running along their length, and wherein the longitudinal axes of the elongated insertion instruments are arranged substantially parallel to one another during use.

7. The system of claim 6, wherein the spacer is advanced linearly between the elongated insertion instruments in a direction substantially parallel to longitudinal axes of the elongated insertion instruments.

8. The system of claim 1, wherein an interface between the elongated insertion instrument and the spacer comprises a channel and complementary protrusion that guides linear advancement of the spacer.

9. The system of claim 8, wherein the spacer comprises a protrusion that engages a complementary channel of the elongated insertion instrument, and wherein the complementary channel is formed in the surface of the elongated instrument and extends along at least a majority of a longitudinal length of the elongated insertion instrument.

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10. The system of claim 1, further comprising an other elongated insertion instrument, wherein the other elongated insertion instrument is moved linearly to advance the spacer linearly during use.

11. The system of claim 10, wherein the other elongated insertion instrument engages a trailing end of the spacer and is moved linearly to push the spacer linearly during use.

12. The system of claim 1, wherein at least one of the first or second body comprises an instrument engagement feature engaged by a complementary body engagement feature of the elongated insertion instrument to rigidly couple the elongated insertion instrument to the first or second body during use.

13. The system of claim 1, wherein the elongated insertion instrument is releasably coupleable to the first body and the second body during use.

14. A method of implanting an intervertebral implant into a human spine, comprising:

disposing an upper body into an intervertebral space between an upper vertebra and a lower vertebra, wherein the upper body comprises:

a superior surface disposed adjacent the upper vertebra, and

an inferior surface opposite the superior surface;

disposing a lower body into the intervertebral space between the upper vertebra and the lower vertebra, wherein the lower body comprises:

an inferior surface disposed adjacent the lower vertebra, and

a superior surface opposite the inferior surface;

releasably coupling a distal end of an elongated insertion instrument to at least one of the upper body and the lower body;

positioning a spacer substantially adjacent to the upper and lower bodies after the upper and lower bodies have been disposed into the intervertebral space between the upper vertebra and the lower vertebra; and

linearly advancing a spacer between the inferior surface of the upper body and the superior surface of the lower body, wherein the elongated insertion instrument guides at least a portion of linear advancement of the spacer from a substantially proximal end of the elongated insertion instrument to a substantially distal end of the elongated insertion instrument, and wherein linear advancement of the spacer results in expansion of the intervertebral implant such that the superior surface of the upper body and the inferior surface of the lower body move away from one another to expand a height of the implant.

15. The method of claim 14, further comprising releasing the elongated insertion instrument after the spacer is disposed between the inferior surface of the upper body and the superior surface of the lower body.

16. The method of claim 14, wherein linearly advancing the spacer creates a gap between the inferior and superior surfaces of the upper and lower bodies.

17. The method of claim 14, wherein a leading end of the spacer comprises a wedge shaped nose.

18. The method of claim 17, wherein at least one of the upper and lower bodies comprise a ramped surface that is engaged by the wedge shaped nose as the spacer is linearly advanced.

19. The method of claim 14, further comprising providing an other elongated insertion instrument, wherein the elongated insertion instruments are located on opposite sides of the spacer during use.

20. The method of claim 19, wherein the elongated insertion instruments each comprise longitudinal axis running

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along their length, and wherein the longitudinal axes of the elongated insertion instruments are arranged substantially parallel to one another during use.

21. The method of claim 20, further comprising linearly advancing the spacer between the elongated insertion instruments in a direction substantially parallel to longitudinal axes of the elongated insertion instruments.

22. The method of claim 14, wherein an interface between the elongated insertion instrument and the spacer comprises a channel and complementary protrusion that guides linear advancement of the spacer.

23. The method of claim 22, wherein the spacer comprises a protrusion that engages a complementary channel of the elongated insertion instrument, and wherein the complementary channel is formed in the surface of the elongated instrument and extends along at least a majority of a longitudinal length of the elongated insertion instrument.

24. The method of claim 14, further comprising moving an other elongated insertion instrument linearly to advance the spacer linearly during use.

25. The method of claim 24, wherein the other elongated insertion instrument engages a trailing end of the spacer and is moved linearly to push the spacer linearly.

26. The method of claim 14, wherein at least one of the upper or lower body comprises an instrument engagement feature engaged by a complementary body engagement feature of the elongated insertion instrument to rigidly couple the elongated insertion instrument to the upper or lower body during use.

27. The method of claim 14, wherein releasably coupling the elongated insertion instrument to at least one of the upper body and the lower body comprises releasably coupling the elongated insertion instrument to the upper body and the lower body.

28. An intervertebral implant system for a human spine, comprising:

an upper body configured to be disposed in an intervertebral space between an upper vertebra and a lower vertebra during use, wherein the upper body comprises:

a superior surface configured to be disposed adjacent the upper vertebra, and

an inferior surface opposite the superior surface;

a lower body configured to be disposed into the intervertebral space between the upper vertebra and the lower vertebra during use, wherein the lower body comprises:

an inferior surface configured to be disposed adjacent the lower vertebra, and

a superior surface opposite the inferior surface;

an elongated insertion instrument configured to be releasably coupled to at least one of the upper body and the lower body during use; and

a spacer configured to be linearly advanced between the inferior surface of the upper body and the superior surface of the lower body during use;

an other elongated insertion instrument, wherein the elongated insertion instruments are located on opposite sides of the spacer during use, wherein the elongated insertion instruments each comprise longitudinal axis running along their length, and wherein the longitudinal axes of the elongated insertion instruments are arranged substantially parallel to one another during use, wherein the spacer is advanced linearly between the elongated insertion instruments in a direction substantially parallel to longitudinal axes of the elongated insertion instruments from a substantially proximal end of the elongated insertion instruments to a substantially distal end of the elongated insertion instruments, wherein the elongated

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insertion instrument guides at least a portion of linear advancement of the spacer, and wherein linear advancement of the spacer results in expansion of the intervertebral implant such that the superior surface of the upper body and the inferior surface of the lower body move away from one another to expand a height of the implant.

29. The system of claim 28, wherein the spacer is disposed in a gap between the inferior and superior surfaces of the upper and lower bodies, respectively, during use.

30. The system of claim 28, wherein a leading end of the spacer comprises a wedge shaped nose.

31. The system of claim 30, wherein at least one of the upper or lower bodies comprise a ramped surface engaged by the wedge shaped nose as the spacer is linearly advanced during use.

32. The system of claim 28, wherein an interface between the elongated insertion instrument and the spacer comprises a channel and complementary protrusion that guides linear advancement of the spacer.

33. The system of claim 32, wherein the spacer comprises a protrusion that engages a complementary channel of the

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elongated insertion instrument, and wherein the complementary channel is formed in the surface of the elongated instrument and extends along at least a majority of a longitudinal length of the elongated insertion instrument.

34. The system of claim 28, further comprising an other elongated insertion instrument, wherein the other elongated insertion instrument is moved linearly to advance the spacer linearly during use.

35. The system of claim 34, wherein the other elongated insertion instrument engages a trailing end of the spacer and is moved linearly to push the spacer linearly during use.

36. The system of claim 28, wherein at least one of the upper or lower body comprises an instrument engagement feature engaged by a complementary body engagement feature of the elongated insertion instrument to rigidly couple the elongated insertion instrument to the upper or lower body during use.

37. The system of claim 28, wherein the elongated insertion instrument is configured to be releasably coupled to the upper body and the lower body during use.

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